C13 ENS M33 C13 ENT M50

TECHNICAL AND REPAIR MANUAL

JUNE 2007 EDITION







FOREWORD

We strongly recommend that you carefully read the indications contained in this document: compliance with these indications protects the engine from irregular operation, assures reliability, safeguards sea-going and protects maintenance personnel from accident hazards.

The indications contained in this document pertain to the C13 ENS M33 and C13 ENT M50 marine engines and complement the IVECO MOTORS-FPT "Marine Diesel Engines Installation Handbook". You should refer to this for anything that is not explained herein.

Technical engineers and fitters must comply with work safety regulations. They must implement and adopt the methods foreseen for personal safety while carrying out maintenance or checks.

There is a reminder of the safety rules in Section 11 of the present publication.

There is a reminder of the regulations for engine handling at the end of Section 6 of the present publication.

To start the engine, you must adhere to the procedure stated at the end of Section 5 of the present publication.

To get best engine performance you must conform with its intended mission profile. The engine must not be used for purposes other than those stated by the manufacturer. IVECO MOTORS-FPT is available for a prior examination of any requirements regarding special installations, should this be necessary.

In particular

- □ Use of unsuitable fuels and oils may compromise the engine's regular operation, reducing its performance, reliability and working life.
- Exclusive use of IVECO Original Parts is a necessary condition to maintain the engine in its original integrity.
- Any tampering, modifications, or use of non-original parts may jeopardize the safety of service personnel and boat users.

To obtain spare parts, you must indicate:

- Commercial code, serial number and the indications shown on the engine tag;
- The number of the spare part. This can be found in the spare part catalog.

The information provided below refers to engine characteristics current at the date of publication.

IVECO MOTORS-FPT reserves the right to make modifications at any time and without advance notice, to meet technical or commercial requirements or to comply with local legal and regulatory requirements.

We refuse all liability for any errors and omissions.

The reader is reminded that the IVECO MOTORS-FPT Technical Assistance Network is always at the Customer's side with its competence and professionalism. IVECO MOTORS-FPT Publication edited by: IVECO PowerTrain Advertising & Promotion Pregnana Milanese (MI) www.ivecomotors.com

Printed P3D32C002 E - June 2007 Edition

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Indications for consultation

The several engine versions are usually explained with common images and descriptions. In cases of considerable differences, they are explained separately.

The specific characteristics of the C13 ENS M33 engine electric system are described in Section 9.

Sections 1-2-3 are intended for sales personnel, to provide them with an exact knowledge of the product's characteristics and enable them to accurately meet the Customer's requirements.

The remaining sections are intended for the personnel that has the task of performing both ordinary and extraordinary maintenance; by referring carefully to the chapter devoted to diagnosis, they too will be able to provide an effective service of technical assistance.

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OVERVIEW

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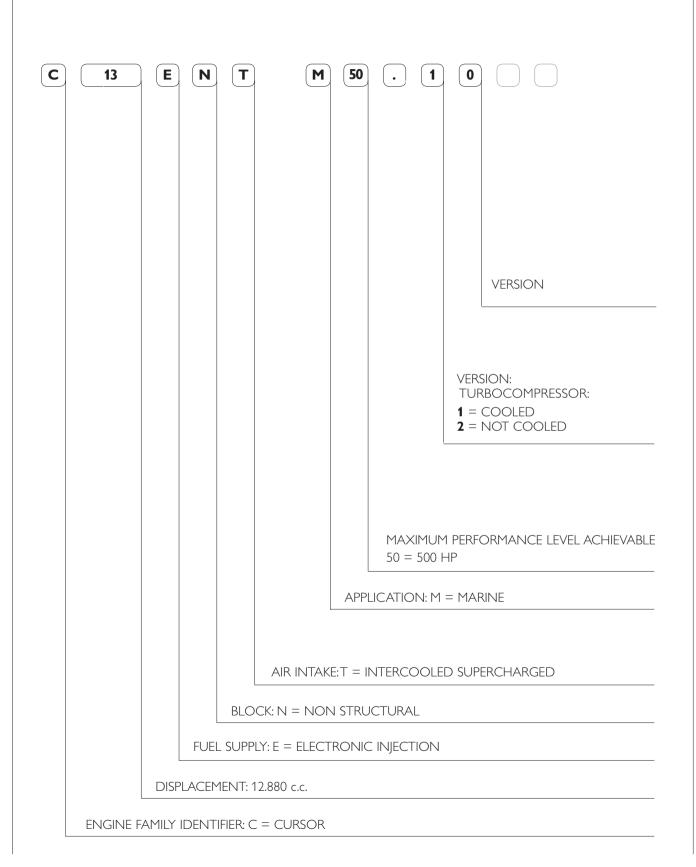
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IDENTIFICATION DATA

	I			
Figure 1				
dentification Tag				
Viale dell'Industria, 15/17 - 20010 Pregnana Mil.se MI - ITALY				
ENGINE TYPE				
ENGINE FAMILY ENGINE DWG				
POWER (KW) AND SPEED (RPM) POWER SET CODE				
ENGINE S/N YEAR OF BUILD				
COMMERC. TYPE / VERSION				
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Figure 2				
A A A SCO				
CAR DE C				
	<u>_</u>			
The engine identification data are stenciled on a tag positioned over the engine coolant tank.				

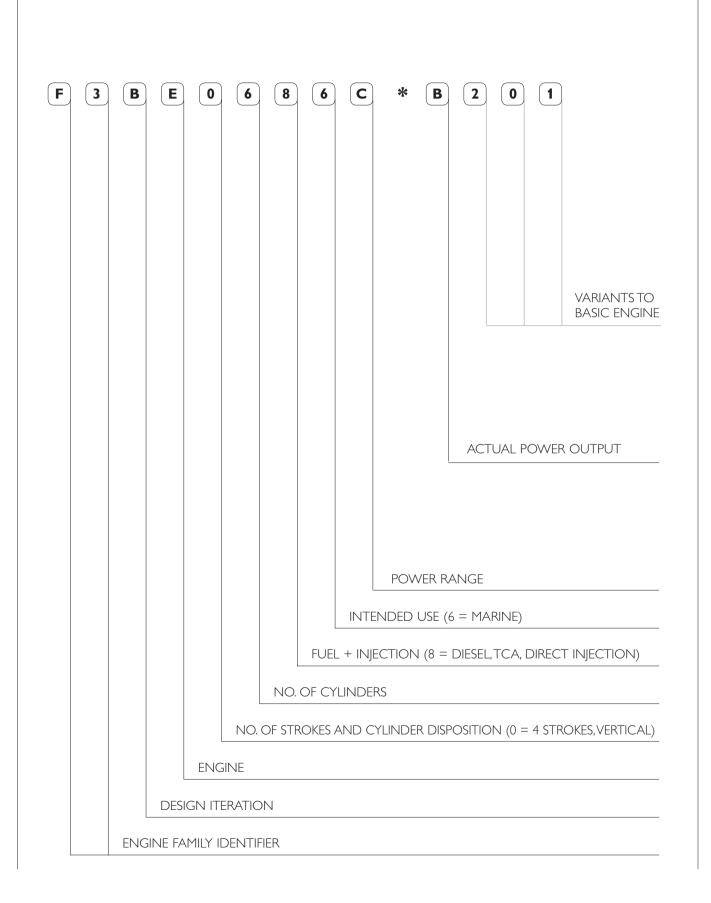
COMMERCIAL CODE

The purpose of the commercial code is to make it easier to understand the characteristics of the product, categorizing the engines according to their family, origins and intended application. The commercial code, therefore, cannot be used for technical purposes and to identify the engine's components, this is the purpose of the "ENGINE S/N".

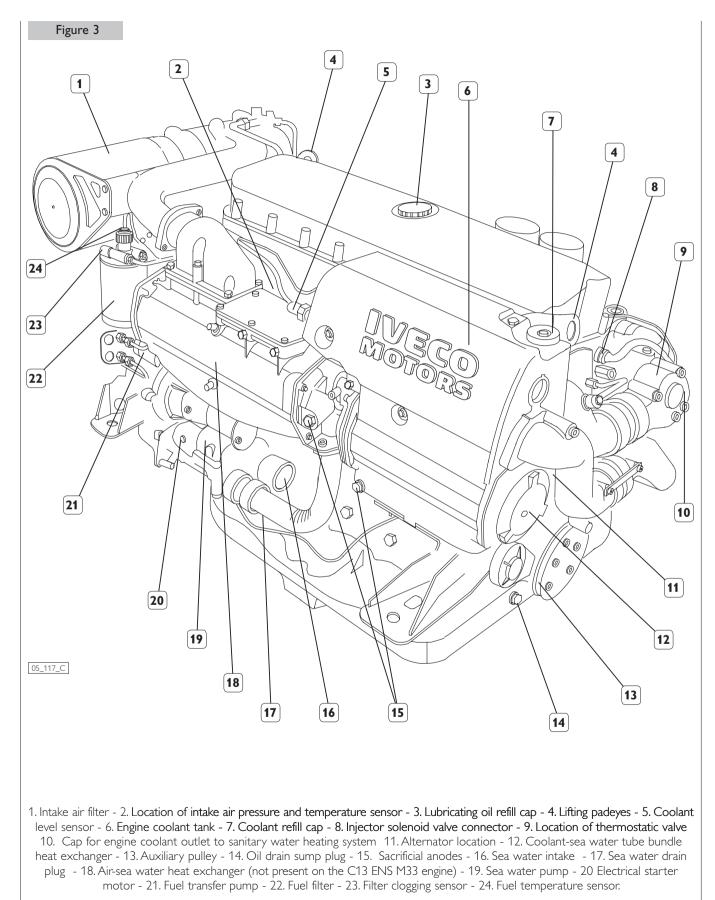


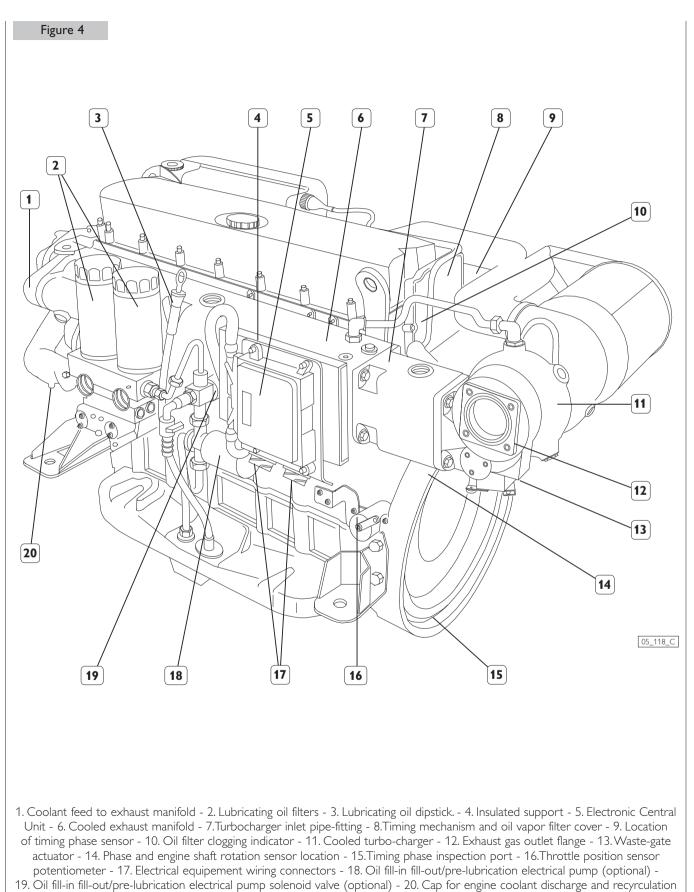
PRODUCT MODEL NUMBER

The model number is assigned by the manufacturer; it is used to identify the main characteristics of the engine, and to characterize its application and power output level. It is stamped on the side of the crank-case.



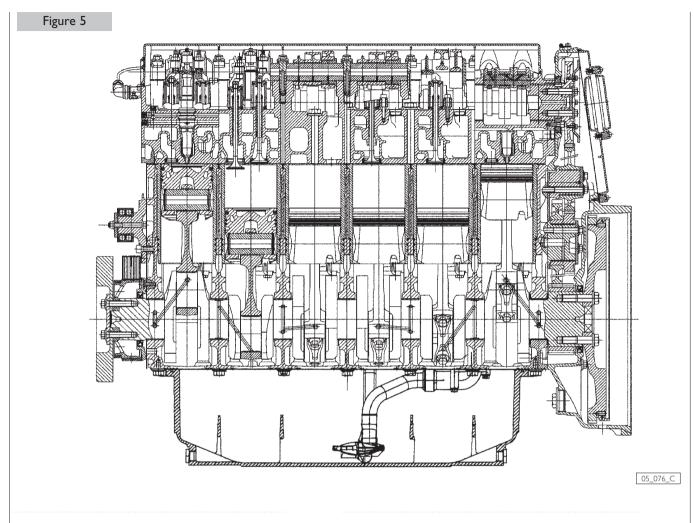
ENGINE PARTS AND COMPONENTS





from sanitary water heating system.

ENGINE ARCHITECTURE



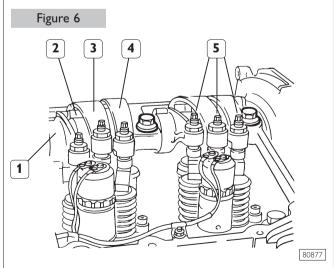
With the CURSOR series engines, IVECO MOTORS-FPT has reached unequalled standards in power delivery for industrial, marine, and automotive uses; CURSOR engines are the result of a continuous research process aimed at product improvement, and they inherit no elements of previous propulsion units. They adopt the most rational and effective solutions to achieve, with smaller displacement engines, power outputs that are typical of larger, heavier engines.

The architecture of these engines is characterized by six cylinders in line, four valves per cylinder and roller rocker arms with overhead cam shaft and "bonded" block.

Electronic control extended to all functions ensures reliable and durable operation, offering important benefits in terms of performance and usage.

IVECO MOTORS-FPT's contribution to environmental protection is amply demonstrated by the CURSOR engines' environmental performance: fumes and noise are well below current regulatory requirements and compliance with future limits was the target of the whole design effort.

The 24 valve cylinder head with its camshaft with seven supports, incorporates the intake manifold and the conduits for the cooling and lubrication fluids, as well as for fuel supply. The overhead camshaft with roller rocker arms directly activates both the valves and the EUI (Electrical Unit Injector).



Rocker arm shaft - 2. Intake valve rocker arm Pump injector rocker arm - 4. Exhaust valve rocker arm Calibration screw.

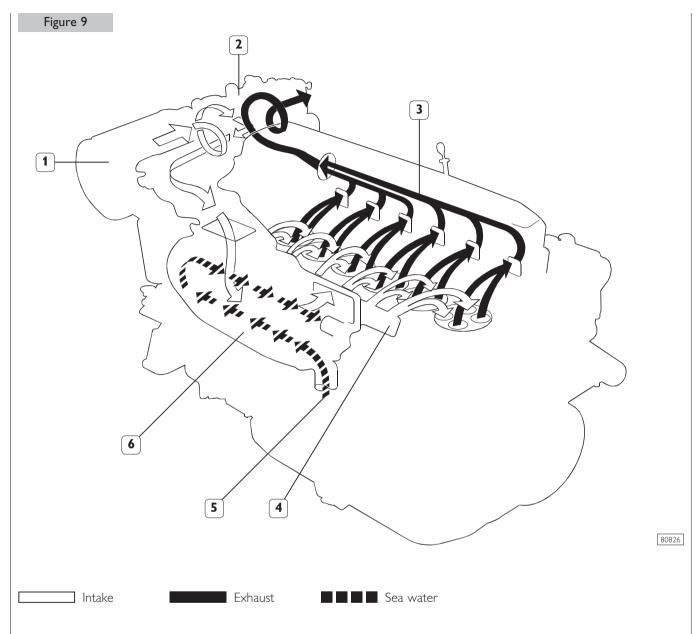
Figure 7 80824 Timing control is to the rear to reduce torsional effects and it is built with helical tooth gears to contain noise. Figure 8 80825 Block and sub-block constitute a rigid assembly to reduce vibration and noise and secure the drive shaft with seven shaft supports. Aluminum pistons provide effective heat dissipation.

Pump injectors are mounted at the center of the combustion chamber and provide the highest possible thermodynamic efficiency thanks to an injection that is able to reach pressures that exceed 1600 bar. Electrically driven by the electronic control, they deliver fuel at a time that minimizes fuel consumption and contains gas emissions, while maximizing torque and power output.

The EDC, Electronic-Diesel-Control system, constantly monitors environmental and engine operating conditions, providing an optimized injection control to maximize performance at all times. Even when operating in critical conditions, control is optimized. This permits navigation and operation to continue in complete safety.

The electronic unit's control over the entire engine's efficiency provides information about the engine's global performance and other, specific, information for each cylinder, thereby making servicing operations easy; associated with the testing of the working condition of the injection system's electrical and electronic components, it stores information about the most significant events that occur during the engine's operation and allows maintenance personnel to anticipate the onset of faults and resolve them.

COMBUSTION AIR INTAKE AND EXHAUST SYSTEM



1. Air filter - 2. Turbocompressor - 3. Exhaust gas manifold - 4. Intake manifold incorporated in cylinder head - 5. Sea water inlet from pump - 6. Air/sea water heat exchanger (not present on the C13 ENS M33 engine).

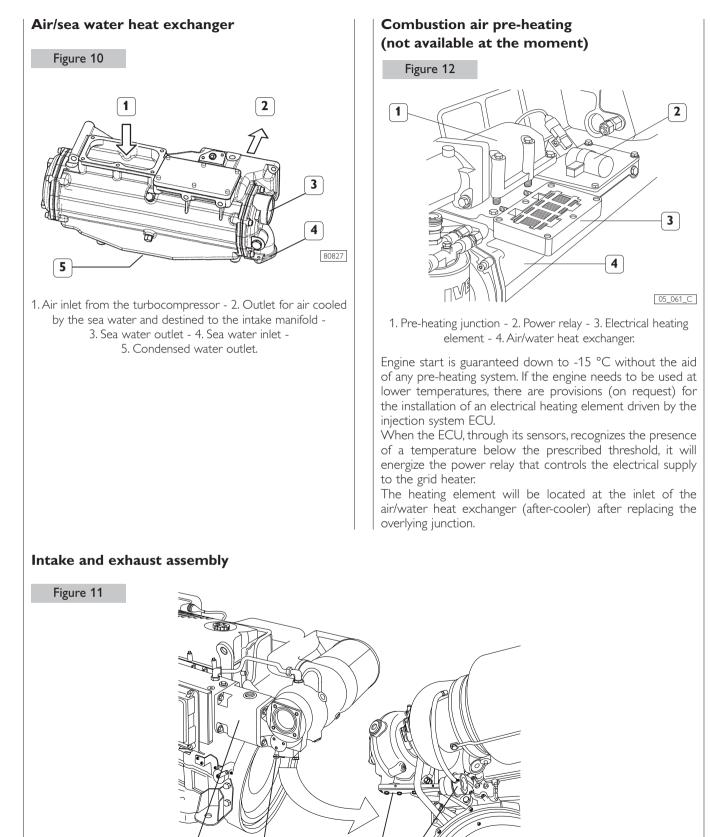
Description and Operation

Air, drawn in and compressed by the turbocompressor, flows through the heat exchanger together with sea water. The latter, by reducing temperature, allows an increase in the engine's volumetric efficiency.

The air density at the inlet of the intake manifold is measured by two sensors, for pressure and temperature, allowing the ECU of the EDC system to calculate fuel dosage relative to the actual quantity of air available for combustion.

Lubricating oil vapors (blow-by) not condensed in the separator, are sent to the engine intake by a gauged hole downstream of the air filter. Exhaust gas expelled by the engine flows through the cooled exhaust manifold to reach the turbocompressor rotor wherein, depending on the supercharging pressure reached, it may be switched by waste gate to exhaust to limit the thrust exerted on the turbocompressor rotor and contain the pressure generated by the compressor within the maximum rated value.

Exhaust manifold and turbocompressor body are cooled by the fresh water loop. Exhaust gases flow into the exhaust terminal and, when provided, they are mixed with the sea water it carries for overboard discharge.



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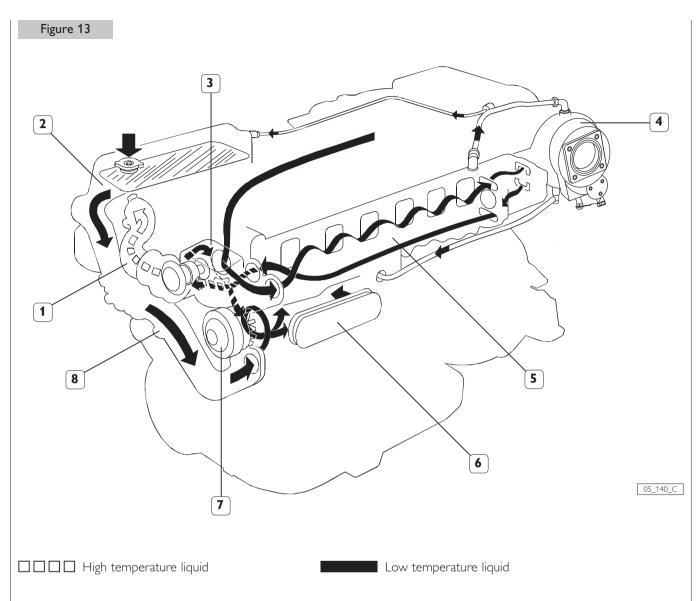
1. Turbocompressor supply feeder-line - 2. Waste gate valve command rod. - 3. Command rod guard - 4. Waste gate valve pneumatic actuator.

3

4

2

COOLING FRESH WATER CLOSED LOOP



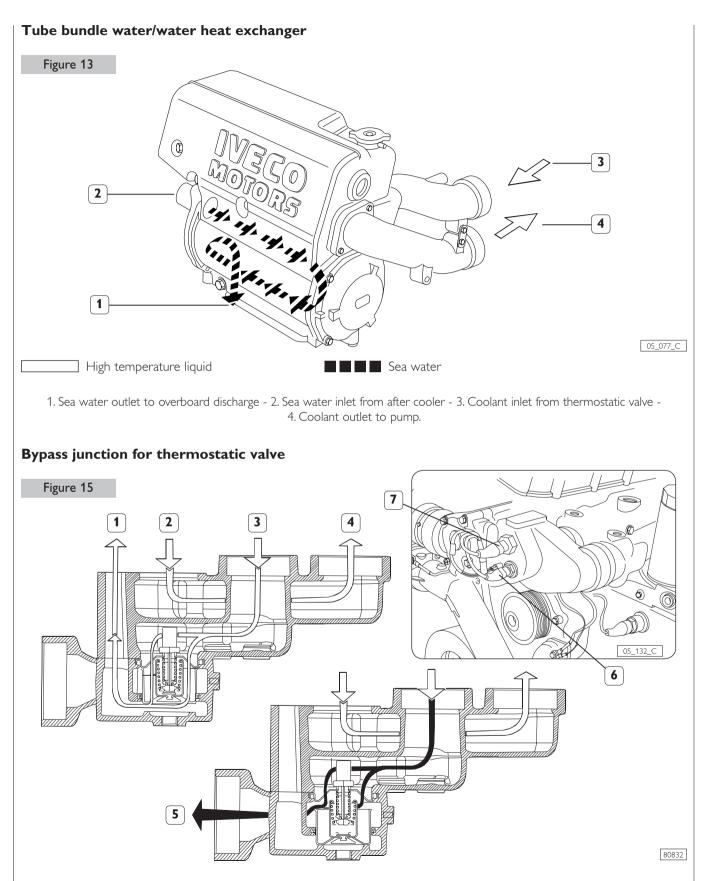
1. Thermostatic valve/coolant tank junction pipe - 2. Coolant tank incorporated in sea water heat exchanger - 3. Bypass junction for thermostatic valve - 4. Turbocompressor - 5. Cooled exhaust manifold - 6. Engine oil/coolant heat exchanger - 7. Coolant pump - 8. Heat exchanger junction pipe.

Description and operation

The centrifuge pump, rotated by the drive shaft with a poly-V belt, draws in the coolant coming from the fresh water/sea water heat exchanger or from the exhaust manifold cooling loop and sends it into the block, where it comes in contact with the lubricating oil heat exchanger. It then touches the heat exchange areas of the cylinders and subsequently those of the engine head, from which it exits flowing through the junction fitting that contains the temperature sensors for the instrument panel and the injection system. This junction has the purpose of bypassing the coolant from the engine head to the exhaust manifold and from the exhaust manifold to the thermostat - which routes it according to the temperature either to the water/water heat exchanger or to the recirculation pump.

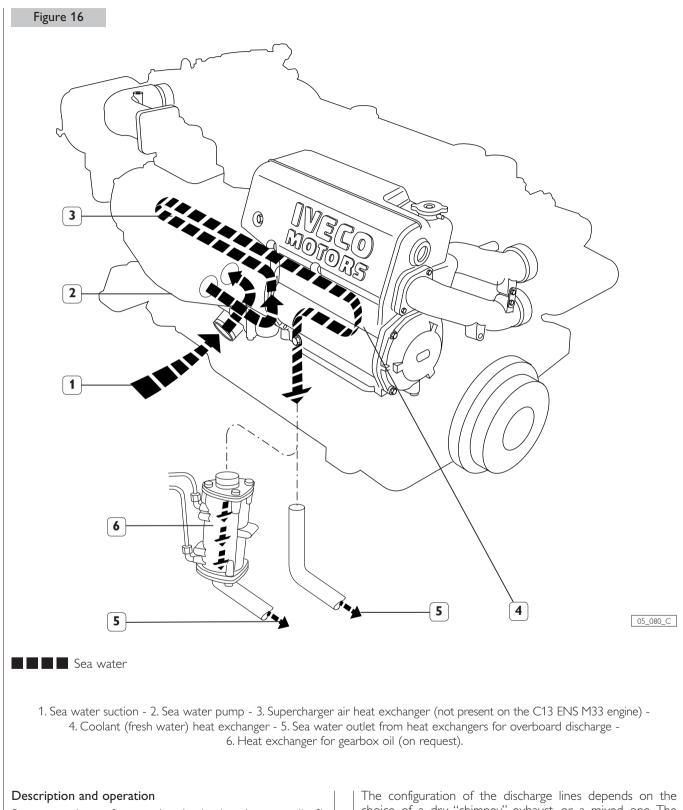
From the bypass fitting the liquid is then injected into the heat exchange chamber of the exhaust manifold - through which it flows going to touch the body of the waste gate, of a portion the exhaust and of the turbo compressor. When it returns into the bypass junction it comes in contact with the wax actuator of the thermostatic valve. This will throttle flows according to temperature.

Part of the liquid will enter the tank and flow through the tube bundle heat exchanger, releasing heat to sea water, while the rest will go directly to the pump, to be recirculated.



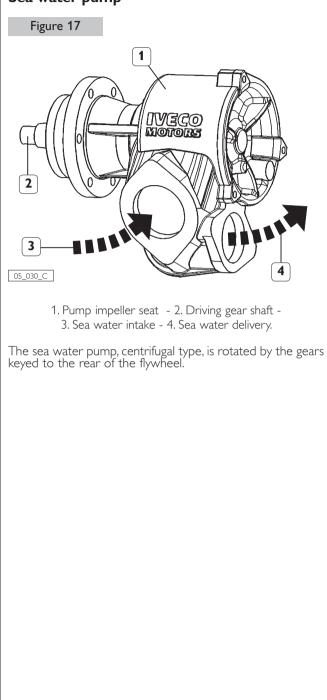
1. Bypass flow to engine - 2. Outflow from engine - 3. Outflow from exhaust manifold - 4. Inflow to exhaust manifold - 5. Flow to sea water heat exchanger - 6. EDC temperature sensor - 7. Temperature sensor for the control panel and indicators.

SEA WATER OPEN COOLING LOOP

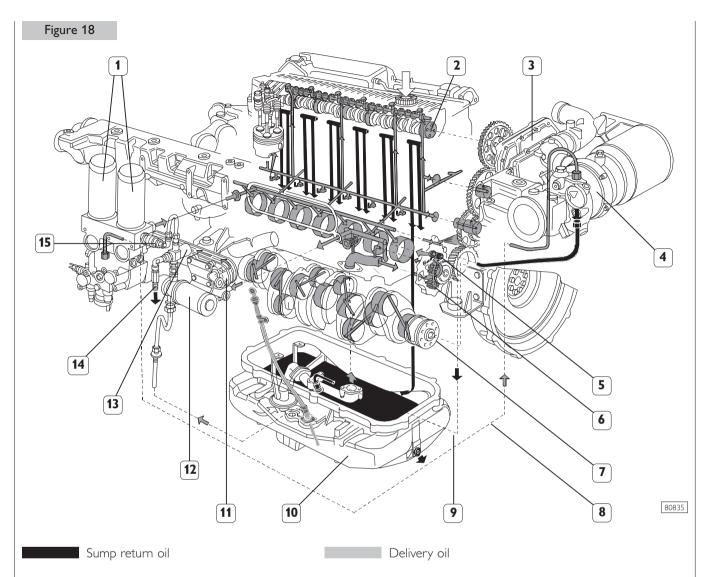


Sea water, drawn from under the keel and necessarily filtered, is drawn by the pump and sent to the supercharger air heat exchanger and from there to the water/water heat exchanger of the closed cooling loop; only after this will it flow through the heat exchanger for the gearbox oil, if one is provided. The configuration of the discharge lines depends on the choice of a dry "chimney" exhaust, or a mixed one. The outlet pipe will carry the water directly to the overboard discharge or, if the water/exhaust gas mixer solution is adopted, a conduit will connect the outlet of the last heat exchanger with the mixer inflow junction pipe.

Sea water pump



ENGINE OIL - LUBRICATION LOOP



 Oil filters - 2. Camshaft on cylinder head - 3. Oil vapor condenser and filter (blow by) - 4. Turbocompressor - 5. Oil pump safety valve - 6. Lubrication oil pump - 7. Drive shaft - 8. Turbocompressor lubricating oil flow line - 9. Oil return flow from turbocompressor - 10. Oil sump - 11. Heat exchanger with coolant - 12. Electrical pump for pre-lubrication and oil filling/emptying (on request) - 13. Solenoid valve for switching between the pre-lubrication or oil filling/emptying functions (on request) -14. Oil emptying junction - 15. One-way pre-lubrication valve.

Description and operation

The gear pump, rotated by the gears at the rear of the flywheel sends the lubricating oil directly to the heat exchanger which, incorporated in the block and lapped by the coolant, reduces temperature to maintain optimal lubricating capability. The thermostatic valve that regulates oil flow is located at the inlet of the heat exchanger, opening the bypass pipe if temperature falls below calibration temperature.

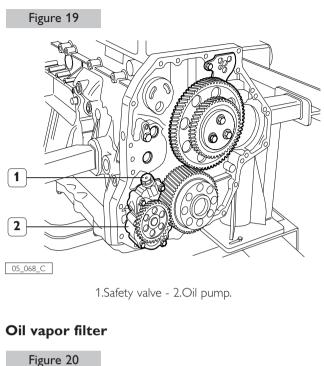
From the output of the heat exchanger, the oil is sent to the filter assembly and from this back to the engine block to lubricate all anti-friction elements. The blow-by vapor condenser, provided with filter and safety valve, is located on the upper part of the timing mechanism lid. The vapors, after returning to the liquid state, will flow from the vapor condensor into the sump. The engine is provided with the pre-lubrication system on request. This can inject enough oil into the engine's ducts to guarantee a totally safe start.

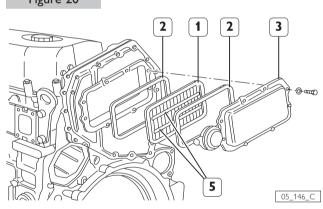
The operation of the electrical pre-lubrication pump (on request), is automatically controlled by the ECU electronic unit.

This system, with the aid of the flow-switching solenoid valve, also permits the oil sump to be emptied and filled.

Detailed descriptions of this operation are provided in Section 3.

Gear pump



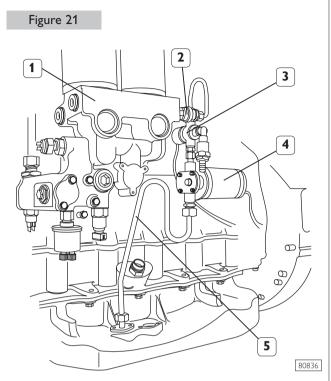


1.Oil vapour filter - 2. Gaskets- 3. Cover- 4. Exit of vapour from the motor extraction system - 5. Reinforcing bars

The oil vapours go through the filter (1) where their liquid parts condense and flow back in the sump whilst the remaining gas exits from the connection (4) and are sucked by the motor positioned after the air filter.

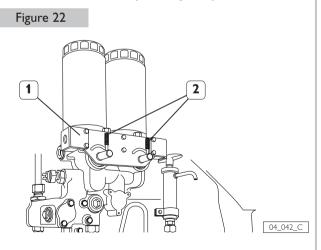
The filter (1) only works in one direction. Consequently it must be assembled with the two reinforcing bars (4) on the visible side, as shown in the picture.





1. Oil filter support - 2. One-way valve to prevent emptying - 3. Switching solenoid valve - 4. Electrical pump -5. Oil sump inflow and suction pipe.

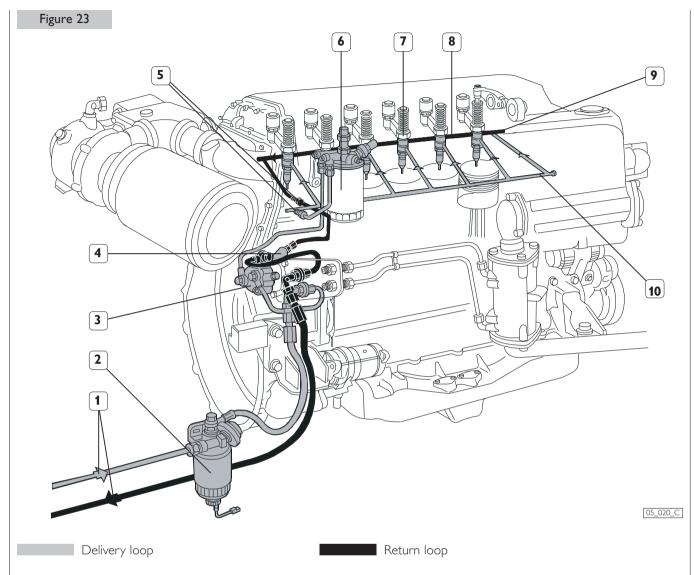
Commutable filters (on request)



1. Commutable oil filters support- 2. Filters activation/ deactivation levers.

The supports are equipped with levers and, if necessary, they enable the replacement of a filter even if the motor is rotating. If necessary, operate very carefully to avoid risks of burning. Do not exclude both the filters together for any reason.

FUEL LINES



 Recirculation and suction flows from the tank - 2. Pre-filter - 3. Supply pump - 4. Pressure regulating valves - 5. Inlet outlet fittings from cylinder head - 6. Filter - 7. Pumping injector - 8. Recirculation collecting channel - 9. Cylinder head venting point -10. Collecting channel for intake to injectors.

Description and operation

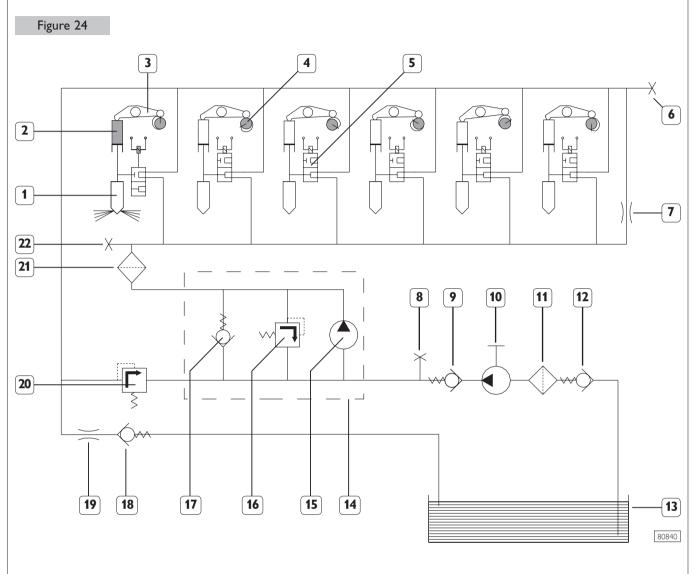
Fuel is supplied at low pressure by means of a gear pump secured to the flywheel bell. When the engine runs, the pump (3) draws fuel from the tank through the pre-filter (2) and sends it through the main filter (6) to the inlet junction on the cylinder head; there, a first longitudinal conduit (10) takes the fuel, through a series of transverse conduits, to the "EUI" pumping injectors. A second longitudinal conduit, machined at the center of the head, conveys through the housings of the injectors the flow of the fuel that was not injected, to permit it to exit.

Along this section of circuit, the fuel undergoes washing to eliminate any traces of vapors formed as a result of fuel overheating during the pumping phases in the injectors.

To limit the quantity of fuel to be recirculated to the tank, the fuel flowing out of the head is sent back to the pump and partially reused. The output fitting to the pump is fitted with a valve calibrated to a pressure of 3.5 bar, which allows to maintain, within the injector supply loop, the minimum pressure required to fill the injectors. The fuel not reused by the pump returns to the tank via a calibrated hole and a one-way valve to prevent emptying, calibrated to the pressure of 0.2 bar.

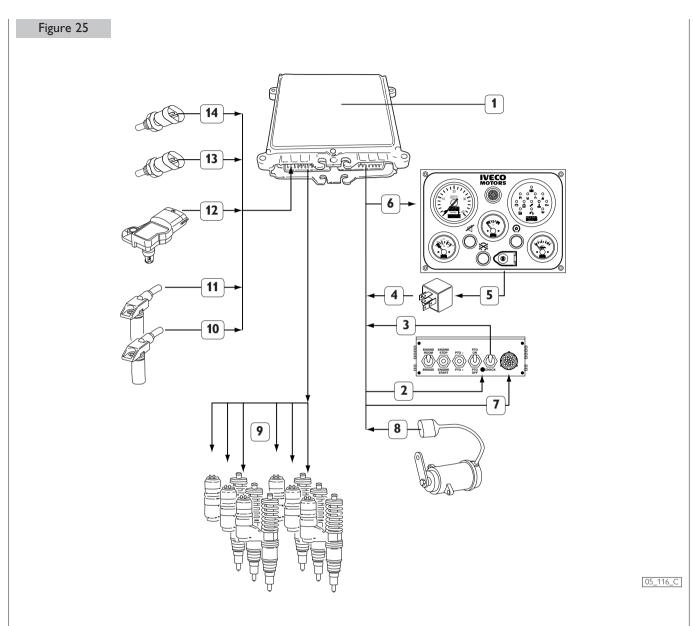
The pressure in the injector supply loop grows as engine RPM increases; it is therefore necessary to limit its maximum value to 5 bar, by means of a valve positioned in the body of the gear pump.

The fittings for venting the loop are located on the prefilter support, on the filter support and in the front of the cylinder head near the electrical connector of the EUI injector circuit. Hydraulic schematic diagram



1. EUI injector - 2. EUI pumper - 3. Rocker arm - 4. Actuating cam - 5. EUI solenoid valve - 6. Vent fitting on cylinder head - 7. Calibrated hole - 8. Vent fitting on pre-filter - 9. One-way valve - 10. Hand pump - 11. Fuel pre-filter - 12. One-way valve - 13. Fuel filter - 14. Gear pump assembly - 15. Fuel supply gear pump - 16. Pressure limiter valve (initial opening pressure 5 bar) - 17. One-way valve - 18. One-way valve - 19. Calibrated hole - 20. Pressure regulating valve (initial opening pressure 3.5 bar) - 21. Fuel filter - 22. Vent fitting on fuel filter support.

INJECTION SYSTEM - EDC (Electronic Diesel Control)



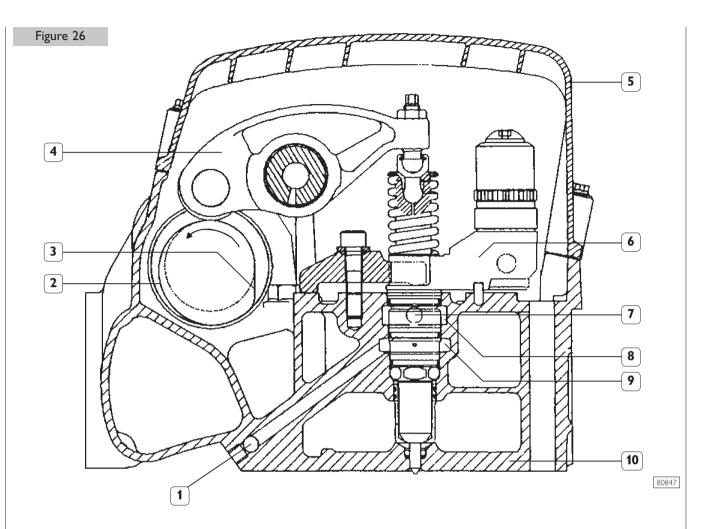
Central electronic unit ECU with atmospheric pressure sensor - 2. Fault indicator light - 3. Blink code request push-button Main relay - 5. Key control - 6. RPM Gauge - 7. Diagnostics connector - 8. Throttle position sensor - 9. Pumper injectors with electrical control, EUI - 10. Timing sensor - 11. Flywheel sensor - 12. Combustion air pressure/temperature sensor Fuel temperature sensor - 14. Engine coolant temperature sensor.

CURSOR engines are equipped with the modern MS 6.2 injection system which drives electrically controlled single pumper injectors, or EUI, Electric Unit Injector. This component gives a prompt fuel supply, extremely small pressure losses and quiet operation, even though injection pressures exceed 1600 bar.

Adoption of the overhead camshaft and roller rocker arms for the actuation of engine valves and injectors provides the whole engine with innovative features, making it compact and giving it a high performance to weight ratio.

An overall improvement in performance was achieved by the availability of considerably higher injection pressures than those achievable with traditional injection pumps, together with a completely electronic management of all injection functions and the extreme precision of the injectors. The presence of individual pumping elements allows to con-

trol independently, "cylinder by cylinder", injection duration and advance - computed and optimized in each instant by the central unit according to the engine parameters measured by the sensors.



Fuel inflow channel (with view of the section of the longitudinal manifold) - 2. Actuation cam: injector filling profile Actuation cam: injection pumping profile - 4. Rocker arm - 5. Timing cover - 6. EUI, Electric Unit Injector - 7. Section of the recirculating fuel collector channel - 8. Exhaust chamber - 9. Supply chamber - 10. Cylinder head.

EUI electrically controlled pumping injector

The pumper injector element comprises an injector with its own pumping element actuated, like the engine valves, by the timing camshaft. Fuel metering is achieved by means of a solenoid valve which, by controlling the supply flow of the nozzle during the pumping phase, sets the timing for the beginning and end of the injection.

The technological solution of integrating pump and injector is not new in the engine field; as early as the Fifties, pump injectors were used, with mechanical metering control, on engines for marine, industrial and heavy vehicle applications.

Today, the compactness of this injection system and the benefits deriving from the absence of high pressure pipes - with a consequent elimination of flow resistance and actuation delays -, are enhanced by the presence of an electronic control capable of controlling with extreme precision duration and starting time, matching with unparalleled accuracy the injection to even the most critical operating conditions, as measured by the sensors fitted on the engine. The pump injector elements are inserted in appropriate seats machined in the cylinder head and are supplied with low pressure fuel flowing through conduits in the casting. The underlying injector inflow channel is supplied with the fuel from the transfer pump, while the channel above, the recirculating fuel manifold, carries the injector washing and cooling fuel and the fuel not used for injection.

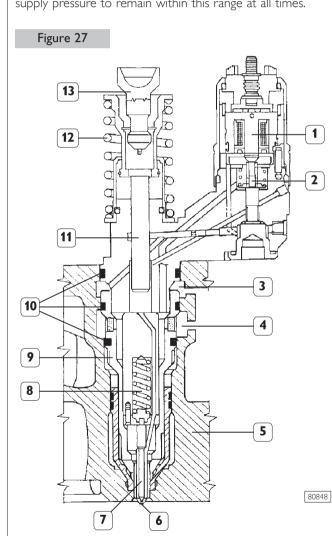
To translate the operation of the injector pumper, a roller rocker arm is used. This is driven by a third cam positioned between those for the intake and exhaust valves. The particular profile of the cam meets the requirement of producing a rapid pumping stroke, in order to rapidly obtain the required injection pressures, and a slow, constant pumper return stroke to avoid causing sudden pressure drops in the supply conduits, with the accompanying risk of vapor formation.

Operation

When the pumper, pushed by the rocker arm, starts the downward stroke, no pumping effect is produced until the moment the solenoid valve is energized, because the fuel is made to circulate at low pressure through the injector to the two inflow and recirculation conduits; only after the solenoid valve is energized is pressure boosted inside the injector. This, once the value for nozzle opening is reached, starts the injection.

When the electrical signal to the solenoid valve ceases, the pressurized fluid, being able to flow out through the channels within the injector, causes injection pressure to drop and thus the nozzle to shut, ending the injection.

The 5 bar limiter valve positioned in the transfer pump and the one-way outflow valve calibrated at 3.5 bar allow injector supply pressure to remain within this range at all times.



Solenoid valve - 2. Shutter - 3. Exhaust chamber in the cylinder head. - 4. Supply chamber in the cylinder head. - 5. Cylinder head - 6. Spray nozzle - 7. Nozzle needle - 8. Calibration spring - 9. Nozzle housing - 10. Sealing rings - 11. Pumper - 12. Pumper return spring - 13. Control tappet.

CAUTION

Injectors do not require calibration and because of the components' high level of precision and the complexity of their assembly, none of their components can be replaced.

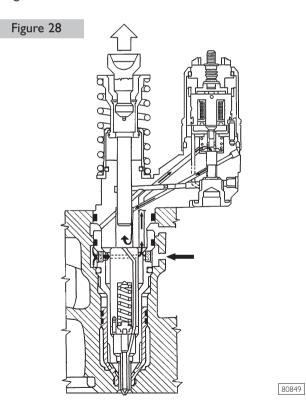
If replacement does become necessary, contact the IVECO MOTORS-FPT Technical Assistance Service to receive appropriate operating instructions. Prescriptions for removal and re-assembly are provided in Section 6.

Delivery characteristic

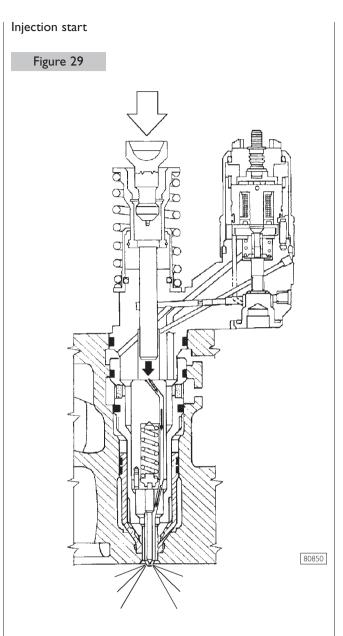
This term is used to indicate the ratio between driving times and fuel quantities delivered. The delivery characteristic is a non linear function with tight tolerances, typical of any injector family, and is the basis for the injection data stored in the ECU: the "dimensioned plans".

For better engine operation efficiency and for the precision required when controlling the fuel supply system, it is imperative to use certified injectors which comply with the prescribed delivery characteristics, i.e. similar to those used to determine the "dimensioned plans" of the injection times stored in the ECU.

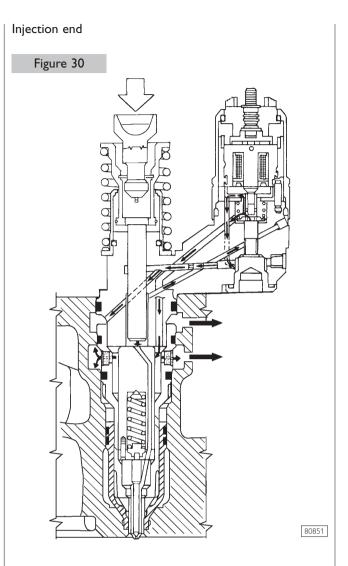
Filling



During the pumper return stroke, with the solenoid valve de-energized, the shutter is in a resting position and allows the low pressure fuel to flow through channels inside the injector to saturate the pumping chamber.



The pumper, thrust by the rocker arm, starts the downward stroke. Since the solenoid valve is de-energized, there is no injection effect because the fuel exits the pumping chamber through the shutter seat, returning to the supply and exhaust chambers. When the solenoid valve is energized, the shutter closes the pumping chamber output, allowing pressure to rise in the chamber. Once the pressure exceeds the value of the calibration spring, the nozzle needle lifts, starting injection.

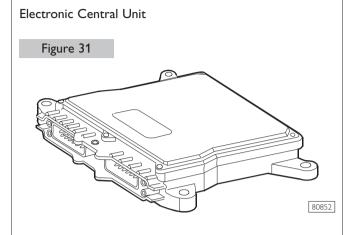


Once the solenoid valve ceases to be electrically driven, the shutter returns to the resting position, allowing the pressurized fuel to flow out towards the inflow and exhaust channels. The consequent pressure drop causes the calibrated spring to prevail and the nozzle needle returns to the position where it closes the injection holes; injection ends.

Washing and cooling

During the resting phases as well as during injection, the fuel that flows from the transfer pump to the supply conduits is made to circulate in the channels of the injector, to cool its inner parts and cause the fuel not injected and overheated during compression to flow out rapidly to the exhaust chamber. Raising the pressure beyond 1600 bar causes considerable heating in the fuel oil, generating conditions that favor its vaporization. Washing and cooling are therefore necessary to avoid forming vapor pockets in the fuel which could hamper delivery of the correct quantity of fuel oil, with a consequent irregular operation of the engine.

Electrical and electronic components



The ECU (Electronic Central Unit) is the component that controls the operation of the entire injection system. Processing starts when the main program is started along with the run-up procedure, which allows to send to RAM the data that had characterized the engine's operation until the previous shutdown and had been stored in the non volatile E²PROM memory at the time of the after-run procedures.

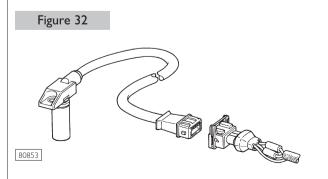
The run-up is followed by the indicator light test and the procedures that lead to engine start; during these procedures, the presence and consistency of the sensors' electrical signals is also tested. The start of the routine for calculating injection time and advance is preceded by the analog to digital conversion of the data from the sensors.

When processing is completed, the final injection data, still in digital format, is transferred to the several final and power stages that will drive appropriately the solenoid valves of the injectors and the other actuators.

Atmospheric pressure sensor

Positioned within the ECU, this produces the data required to match the injection modes to the volumetric efficiency of the engine, as caused by variations in environmental pressure conditions.

Sensor on flywheel



Inductive with variable reluctance, it faces the outer circumference of the flywheel to detect the passage of three sectors, each one with 18 holes drilled radially on it. It generates periodic alternating signals due to flux variations in the magnetic circuit produced within it by the presence of a permanent magnet.

The signal from this sensor is processed in the ECU to evaluate:

- Engine RPM;
- Angular position of the engine relative to the top dead center of the piston pairs;
- Angular acceleration of the drive shaft.

It generates the engine RPM information on the instrument panel.

An interruption of the signal from this sensor during engine operation is obviated by an ECU "recovery", by using the signal of the sensor on the timing pulley, which also prevents engine shutdown.

Sensor on the timing pulley

Inductive, like the previous sensor, this generates signals at the passage of 6 +1 projections of a phonic wheel, keyed onto the gearwheel driving the camshaft.

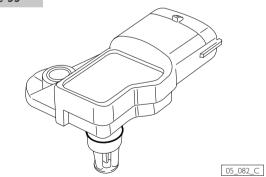
Six equidistant projections provide signals of the succession of the phases in the 6 cylinders; the seventh projection provides the synchronisation signals that allow detection of the typical injection sequence:

1 - 4 - 2 - 6 - 3 - 5.

An interruption of this signal during engine operation is obviated by having the injection sequence always stored in the ECU; if this should occur before the engine is started, a specific phase recognition strategy needs to be implemented.

Combustion air pressure and temperature sensor

Figure 33



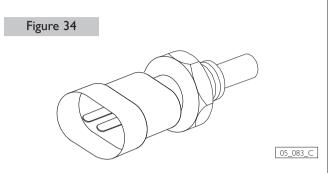
This is a part which integrates the temperature and pressure sensors for the air sent to the turbocharger sucking connection.

Positioned at the inlet of the intake manifold, it produces a signal proportional to the absolute pressure value of intake and supercharged air. This information, together with the temperature data, must allow the matching of injection time and advance to the combustion air density, to enable the best possible thermodynamic efficiency and avoid noxious emissions and smoke.

The pressure sensor is solid state with an amplifier electronic circuit compensated for thermal drift.

Temperature is detected through a resistor with a negative temperature index. Pneumatic sealing ring is green.

Fuel temperature sensor



A neative temperature coefficient resistor, it is located on the filter support. This provides data to determine the density of the fuel that feeds the injectors, so as to match injection time to the actual quantity to be injected.

The de-rating strategies, adopted when the fuel's critical temperature is exceeded (as determined experimentally) are due to a considerable reduction in its lubricating action that is caused by its increase in temperature. These strategies can at times be observed in a limitation of the engine's top performance.

Coolant temperature sensor

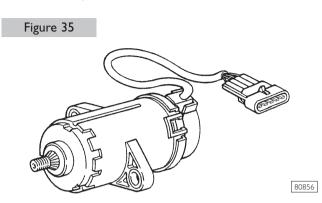
A negative temperature coefficient resistor like the previous sensor, located on the junction where the thermostatic valve is positioned.

It provides the information needed to control injection metering and advance in the different phases of the engine's operation:

- Cold start;
- Warm up;
- Warm;
- Over-temperature.

Recognition of an over-temperature condition leads to the adoption of de-rating strategies to reduce heat production and safeguard the efficiency of the engine as a whole.

Throttle lever position sensor



It provides one of the primary indications for computing the quantity of fuel to be injected.

Operated by the rods of the bridge controls or of the servo drive, it outputs a potentiometric change in the voltage that powers it, according to the throttle position.

A simultaneous safety indication is provided by the internal switch to confirm the position of the throttle: idle/outside idle.

This indication is used by the self-adapting strategies of the potentiometric signal and also in case of faults - to control "limp-home" strategies, which enable to return the vessel to harbor even with a failed potentiometer.

Actuators

These are electromechanical components which, powered with electrical signals, produce mechanical work. They can be categorized according to the modes in which they are electrically driven:

On/Off

Used to control components which react relatively slowly or that simply work at nominal voltage only. Components of this kind, driven directly by the ECU are:

- EDC fault indicator light;
- Pre-heating indicator light;
- Relays.

Through the relays the ECU controls,

- The pre/post heating electrical element;
- Power stages within the ECU.

PWM

These provide an answer to the requirement of an analog adjustment of mechanical actuators.

The actuators are driven with nominal voltage impulses, but of variable duration, to provide control over the average value of the driving electrical current.

In this system, PWM control is used to drive the injector solenoid valves to obtain fast operation and a limit to the absorbed electrical current.

Electrical heating element (on request)

See figure 12

This replaces the traditional fuel heat starter and is an optional component, given the engine's capability of starting at the minimum temperature of -15 °C; it is interposed between the intake conduit connected to the turbocompressor and the after cooler heat exchanger, replacing the final junction fitting.

It consists of an electrical resistor powered at the system's nominal voltage by a relay controlled directly by the ECU.

Its characteristic positive temperature coefficient causes its electrical resistance to increase as temperature rises, thereby limiting current absorption and, as a consequence, also the maximum temperature achievable.

System functions

Computerized electronic control allows to perform in rapid succession both primary functions, such as calculating injection metering and advance, and secondary functions that are required only in particular conditions.

Activated three times per rotation by the drive shaft, metering and advance control are computed selectively cylinder by cylinder at each injection, while secondary functions such as managing an acceleration or operating intake air pre-heating are controlled only as required.

The electronic unit is also programmed to perform continuous checks of the presence and consistency of the signals coming from the system's sensors, in order to provide timely indications of the occurrence of any failures or to exclude a data item if its content is in contrast with the logical sequence of the events that took place until then.

Run up

Immediately after powering up the system (key to ON), the central control unit **before driving the starter motor** transfers into the main memory the data that characterized optimum engine operation during the previous operating period; they represent the progressive ageing of the engine and change with its usage.

With this function, engine management is continuously optimized from the initial operating phases, regardless of the engine's condition of use.

The data transferred during run up is that stored after the last engine shutdown during the "after run" function.

Starting

This engine function management phase is characterized by the adoption of strategies to obtain a rapid recognition of the engine's endothermic operation.

The most evident of the inhibited signals is recognition of throttle position, which thus does not need to be operated until start-up is complete.

Fuel metering and injection

This takes place by varying the duration of the electrical driving of the injector solenoid valves during the pumping phase; the main data, i.e. quantity of fuel to inject, is calculated based on the following information:

- Throttle position;
- Engine RPM.

The data is further corrected based on the following data:

- Combustion air pressure and temperature;
- Fuel temperature;
- Engine coolant temperature.

The duration of the driving may also be changed to linearize an acceleration gradient, the idle RPM, avoid overspeed conditions or control the onset of extreme engine operating conditions.

To obtain an exact delivery of the quantity calculated, the duration of the driving period of the solenoid valve is related to the value of battery voltage.

Only in case of failures entailing a risk of severe damage to the engine will injection actually be zeroed.

Injection advance control

This is obtained by varying, within the time interval of a revolution of the drive shaft, the instant when the injector's electrical driving starts. Implemented values may differ from one injection to the next, as may the differentiated metering of the cylinders.

The parameters that influence injection advance are:

- Position;
- Engine RPM;
- Combustion air pressure and temperature;
- Fuel temperature;
- Engine coolant temperature.

Values are determined experimentally for best performance in compliance with exhaust gas and sound emissions reduction targets.

Additional dynamic matching is provided during acceleration to give a greater pickup torque to the engine.

Information to check the actual implemented value is given by the impedance change of the injector valve solenoid. This allows corrections to be made until the value is exact: "closed loop" control.

Idle RPM adjustment

This function allows to obtain a constant, reproducible RPM although environmental operating conditions may change. Adjustment is obtained by controlling metering and the instant when the injection is started, based on processed

information received from the sensors. if battery voltage dips below normal values, the ECU

increases engine RPM to improve the charge obtained from the alternator.

Self-diagnosis

This is a constant check of the presence of electrical signals sent by the sensors or delivered to actuators. If anomalies are detected it enables the electronic unit to process data according to a "recovery" programme, to avoid engine shutdown.

The central unit, not only checks the efficiency of sensors, actuators and the wiring connected to these but also checks the consitency of the signals and the information deduced.

It is thus possible to recognise an inconsistency and not use an invalid datum - replacing it with a predefined one - by means of comparison with pre-programmed limit parameters or by assessing their increasing or decreasing gradient. The "recovery" procedure is complemented by the storing of codes that identify the errors detected. These codes can be decoded by using computerized diagnostic appliances or the flashing of the "blink code" light.

The functions stated below are actuated only under special engine operation conditions:

Air pre-heat control

(with optional components)

In the case that even only one among the temperature, water, oil or fuel oil sensors indicates a value below +10 $^{\circ}$ C, the ECU activates intake air pre-heating, powering up via relay the heating element positioned in the air line.

This pre-heating phase, whose duration is a function of the measured temperature, is indicated by the light of the optical indicator on the panel and ends when the latter starts to blink.

Once start-up is complete, the subsequent post-heating phase, whose duration is a function of temperature, prevents exhaust smoke.

EDC and pre-heating optical indicators

Positioned on the instrument panel, they are driven directly by the central unit of the EDC system.

Normally off, they will light for an instant immediately after powering on the system, to test their operating condition. If the EDC indicator lights up, this signals a possible fault in the injection system or irregular operation of the engine or its components.

Linearization of the acceleration gradient

Noxious exhaust and sound emissions are contained via the implementation of strategies that operate above all on the control of the injection required for accelerations.

During transients, fuel metering and injection advance are controlled with progression modes obtained experimentally and stored in the central unit.

Balancing cylinder torque delivery

This function contributes to reduce engine vibrations and balance its operation.

It is achieved through "cylinder by cylinder" control of injection flow rate and advance; this allows alignment of the angular acceleration of the drive shaft produced by each combustion.

Cylinder balancing, because of its complex software structure, can be performed only during idling, but the data obtained are used, after an appropriate adaptation, at higher RPM values as well.

Rotation speed control

This is the electronic equivalent of speed regulators in traditional injection pumps. Like these, it regulates:

- Idling and maximum RPM;
- All RPM settings.

Maximum RPM limitation

This feature safeguards the operating condition of the engine, preventing even accidental over-speed conditions.

Limitation strategies are implemented in the following ways:

- Upon exceeding a first safety threshold, fuel flow rate is progressively reduced;
- When maximum RPM is reached, fuel flow is set to zero.

Cut off

This function consists in not injecting fuel during engine deceleration phases.

This is active until a minimum RPM value is reached - below this the thermal operation of the engine could not be restored.

De-rating

This can be considered as a recovery program. It does not store fault information and does not entail indications of faults on the panel; it is carried out when the maximum temperature thresholds for fuel, coolant and combustion air have been exceeded.

De-rating is implemented as a reduction in the torque delivered by the engine, to prevent the risk of damage.

It is implemented proportionally to risk severity, upon recognizing temperatures above 75 °C for fuel or 105 °C for the coolant.

Recovery

This is a particular control and management mode, characterized by the adoption of one of many strategies that allow the system to operate even if the self-diagnosis system has recognized the presence of faults.

In nearly all cases, the ability to continue navigation is assured, either with regular or reduced performance levels.

Adoption of a recovery strategy entails storing in memory the fault code and the corresponding limitation of maximum power delivered by the engine. Power limitation due to a recovery strategy is maintained active until the engine is shut down even if the detected anomaly is no longer present.

The indicator light on the instrument panel will light up in the more severe cases.

After run

This takes place after each engine shutdown, and is characterized by a delayed de-energizing of the main relay powering the ECU. During this phase the central unit remains powered for some seconds, during which the data that characterizes the current optimized management of the engine are moved from the main volatile memory to the non volatile EEPROM memory, so that they are available the next time the engine is started.

The data can be summarized as:

- Control modes (idling RPM, torque delivery balancing, smoke limit...);
- The settings of minimum/maximum signal recognition thresholds;
- Fault memory.

The importance of having available at each start the data that optimize engine management and behavior in terms of TORQUE AND POWER YIELD, is such as to prohibit the use of battery detaching devices or engine shut down procedures that differ from those prescribed by the manufacturer (key to OFF) or which may prevent the correct development of the after run function.

Reference signals

Recognition of the engine's operating phases by the ECU is achieved by analyzing the sequences of electrical pulses generated by the sensors located on the flywheel case and on the timing; the set of these two sequences is called "reference signal set".

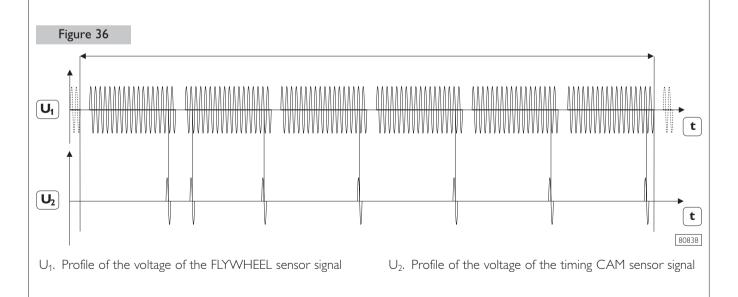
The frequency of the signal generated by the flywheel sensor provides engine RPM indication, while each pulse subsequent to recognition of the zeroing defines a precise angular position of the flywheel and consequently the precise position of each pair of pistons in the engine cycle. The sequence of the cam signal is asymmetrical because of the presence of a tooth that is not equidistant from the others. This allows recognition of the injection sequence: 1-4-2-6-3-5.

The compared analysis of the flywheel and timing signals allows the ECU's software to recognize the different phase of each piston in the pair and its exact position in the thermodynamic cycle, enabling selective management of injection functions in "cylinder by cylinder" mode.

A precise performance of engine management functions (based on the above), depends to a great extent on the precision with which the signals of the two sensors represent what is actually taking place in the engine and consequently on the correct mechanical positioning of these sensors in relation to their references on the engine.

CAUTION

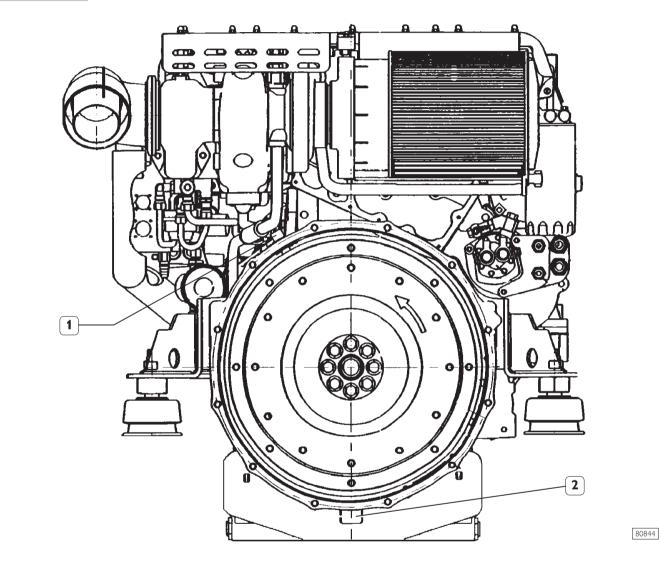
It is imperative to recall that the efficiency of an engine's operation does not depend merely on the factors set out above, but also on all those factors that have long been known to engine professionals who are fully capable of evaluating them correctly.



Flywheel signal

This is produced by a variable reluctance sensor (pick up) secured to the flywheel case in such a position as to detect the passage of the series of holes drilled radially on the circumference of the flywheel.

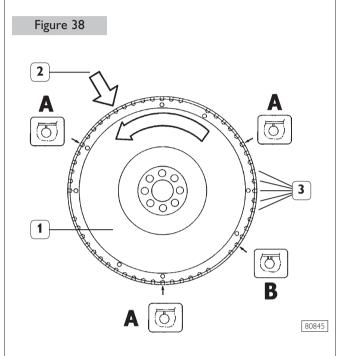




1. Flywheel sensor - 2. Location of the inspection hole

Three series of 18 holes, 6° apart from each other, alternate with an absence of 2 holes every 120° - to enable the sensor to generate pulses for zeroing the count.

Each 18 hole sector represents the engine revolution angle involved in the compression and combustion phases of the different pairs of cylinders and hence of interest for injection purposes. The signal will be correctly in phase when the sensor is exactly in front of a particular hole of the sector at the time in which the associated pair of pistons reaches the exact top dead center position, otherwise the actual instant when injection starts will be different from the one prescribed by the tune-up and programmed in the ECU, and without the possibility of recognition via the PT 01 diagnostics analysis. The tune-up and phasing operations are described in Section 6. To make it easier for service personnel to recognize the top dead center position of the three piston pairs, onenotch punches were provided next to the reference hole, whilst a two-notch punch allows to recognize the sector associated with the pair 1 - 6, so as to generate the correct relationship between the two sequences of the flywheel and cam signals.



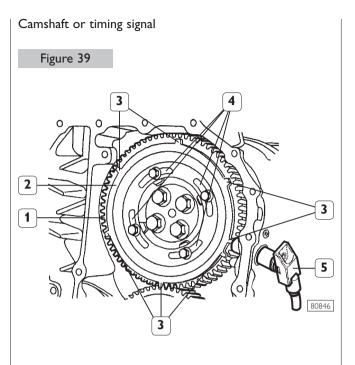
Engine flywheel - 2. Position of the flywheel sensor Radial holes
 A. One-notch punch for identifying TDC -

B.Two-notch punch to correlate the phase of the flywheel and cam signals.

This figure shows the position and characteristics of these references, visible through the inspection hole drilled in the lower part of the flywheel case. If for a particular installation this hole should not be accessible, a specific tune-up procedure will have to be followed, as described in the "diagnostics" section 6.

Absence of the flywheel signal due to failure is obviated with a recovery strategy that uses the sequence of the cam signal to recognize engine RPM and the thermodynamic phases of the cylinders.

A simultaneous absence of both sensors' signals will not permit the engine to operate.



1. Gear wheel to drive the camshaft. - 2. Phonic wheel -3.Teeth detected by the sensor - 4. Slotted tuning holes -5. Camshaft sensor.

This is obtained via a sensor similar to the one located on the flywheel case, but positioned so as to detect the passage of 6 + 1 teeth of a phonic wheel keyed onto the gearwheel driving the camshaft; the presence of a tooth that is not equidistant from the others gives rise to a sequence with a non-constant period that can be used to recognize the exact injector driving sequence.

The method of fastening to the gearwheel, achieved with slotted holes, allows to match the electrical information to the different cam arrangement solutions, and requires accurate phasing, otherwise this can give rise to irregular operation and even cause the engine to fail to start; remember that this signal is the reference for the entire engine control and if it is absent the "recovery" information will be the flywheel signal. In case of absence of the cam signal alone, if it occurs while the engine is running, the injection sequence validated until that time will be used; if it is due to a failure preceding start-up, it will be obviated by a software strategy which by means of successive attempts will enable to start the engine and then adopt the stored sequence: 1-4-2-6-3-5.

The simultaneous absence of both signals will prevent engine operation.

SECTION 2

TECHNICAL DATA

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SPECIFICATIONS

Engine		C13 ENT M50
Cycle Charge Injection		4-Stroke Diesel Supercharged and intercooled Direct
Number of cylinders		6 in line
Bore	mm	135
Stroke	mm	150
Total displacement	cm ³	12880
Compression ratio		16.5 ± 0.8 to 1
Direction of rotation, flywheel side		counterclockwise
Minimum idling rpm	rpm	600 ± 25
Maximum engine rpm, no load	rpm	2170 ± 25
Allowed engine inclination angles		
Maximum longitudinal in continuous operation (static + dynamic)	degrees/360	+ 20°
Maximum transverse in continuous operation(static + dynamic)	degrees/360	± 22° 30'
Longitudinal for oil level check with standard dipstick	degrees/360	0 to +10°
Supercharge		
Turbocompressor with water-cooled body	HOLSET	HE 55IM
Pressure regulation		with waste-gate
Waste-gate maximum opening pressure	bar	2.1 ± 0.1
Lubrication		
Oil	type	SAE 15 W 40/E 3
Oil compliant with specifications		ACEA E3 / API CF4 / MIL L2104E/F
Total oil capacity on first filling	liters (kg)	42 (38)
Total oil capacity with sump at minimum level	liters (kg)	29 (26.3)
Total oil capacity with sump at top level	liters (kg)	36 (32.7)
Oil pressure, warm engine, minimum idling rpm	bar	≥ 1.5
Oil pressure, warm engine, maximum rpm	bar	≥ 5
Maximum allowed temperature	°C	105
Oil dipstick valid for static inclination	degrees/360	0 to +10°
Fuel supply		
Fuel oil compliant with standard		EN 590
Low pressure transfer pump		gear pump
Flow rate at maximum rpm	kg/h	88
Fuel return flow rate to tank	kg/h	≤ 12
Filtering: pre filter	μm	36.5
Filtering: filter	μm	5

Engine		C13 ENT M50
Injection system		
Туре		pump - injectors (EUI)
System		Bosch EDC MS 6.2
Maximum injection pressure	bar	1600
Low temperature starting		
Allowed, without external aids, down to	°C	-15
With electrical heating of intake air (optional), down to	°C	-25
With additional external heater, down to	°C	-30
Cooling		
Closed coolant loop with sea water heat exchanger		50% mixture of water/Paraflu II or equiv. Compliant with SAE J 1034 specification
Total coolant quantity	liters	45
Engine-only capacity	liters	19.5
Expansion tank		standard
Forced circulation		centrifugal pump
Flow rate at maximum rpm	l/h	36800
Temperature regulation Initial opening Sea water line	°C °C	with thermostatic valve 68 ± 2 78 ± 2
Sea water line	-	forced circulation
Sea water pump		centrifugal self-priming
Max. pump capacity	l/h	2800
Exhaust gas expulsion		
Optional		stack
Optional		riser
Electrical system		
Nominal voltage	Vcc	24
Self-regulated alternator: Voltage Maximum current intensity	Vcc A	29 90
Electrical starter motor: Nominal voltage Absorbed electrical power	V W	24 5500
Recommended batteries capacity	Ah	≥ 180
Current discharge at - 18 °C (SAE J 537)	A	≥ 1200

Engine		C13 ENT M50)
Drive train coupling			
Flywheel diameter	mm (inches)	355 (14)	
Flywheel case	type	SAE 1	
Weights			
Without liquids and without gearbox	kg	1345	
Dimensions Figure 1	Sizes in mm (inches)	92 (439,05)	1040 (40,94)

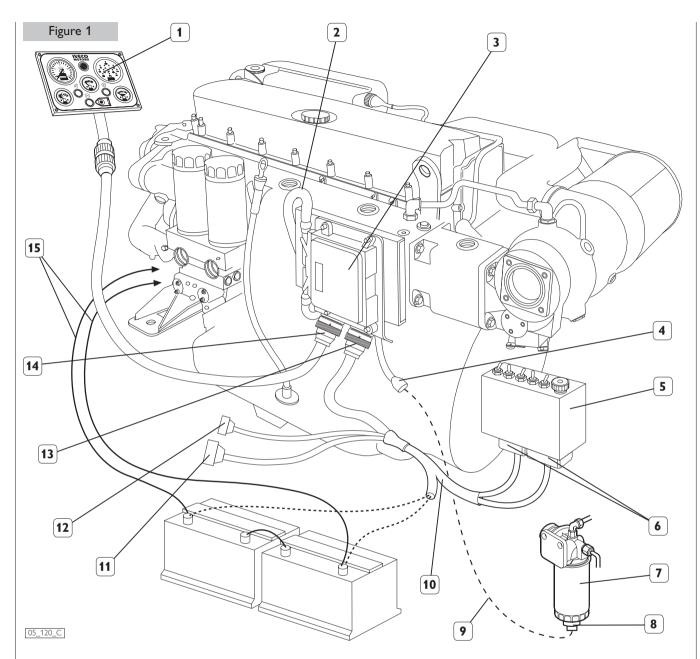
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OVERVIEW



 Instrument panel - 2. Engine wiring - 3. Electronic Central Unit - 4. M Connector - 5. Relay box - 6. JF and JF1 connectors -7. Sedimenting pre-filter - 8. Sensor for presence of water in the fuel - 9. Wiring harness to be manufactured by the yard Interface and power supply wire harness - 11. JG connector for prelubricating system - 12. JE Connector for certified installations by classification Bodies - 13. JA Connection - 14. JB Connection - 15. Power line for electric starter motor and alternator.

The electric equipment of the system carries out the main connections by means of the wiring provided with the engine, to which are connected the power supply, the electronic components assembled on the engine, the electronic central unit of the injection system, relay box and the instrument panel.

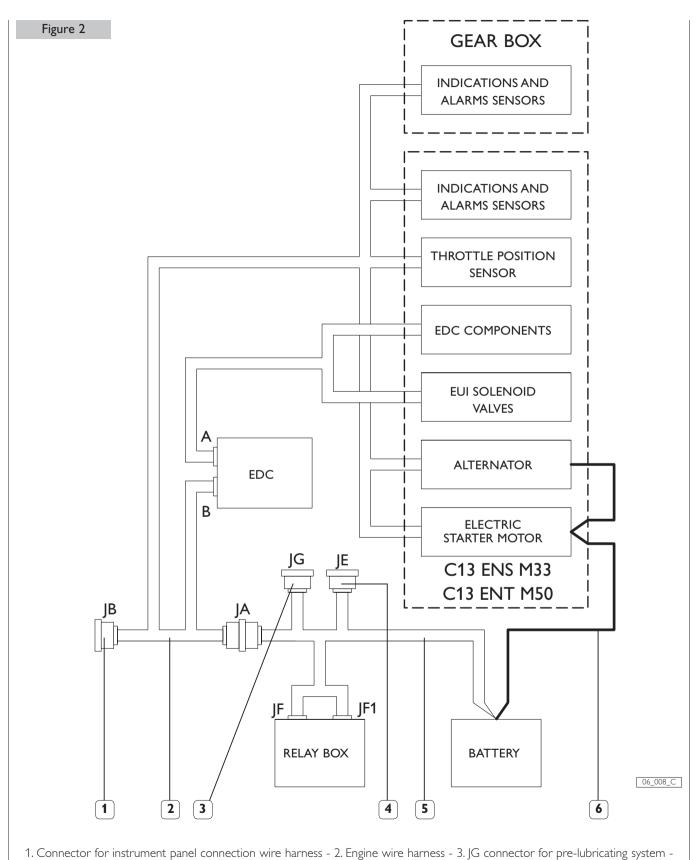
The overall implementation is suitable for the requirements of an adequate installation and complying with electromagnetic compatibility limits legislation on electric installations (EMC). The wiring cannot be modified in any way and any possibility of bypassing the wiring lines to use different components is completely excluded. The wiring harness for power supply has to be manufactured by the yard following the indications contained in the "C13 ENS M33 - C13 ENT M50 Installation Directive" document.

CAUTION

Never use the wiring of the engine equipment to power any other electrical appliance of the boat.

Information related to analogue and digital control panel and relative sensors is included in the "C13 ENS M33 - C13 ENT M50 Installation Directive" document.

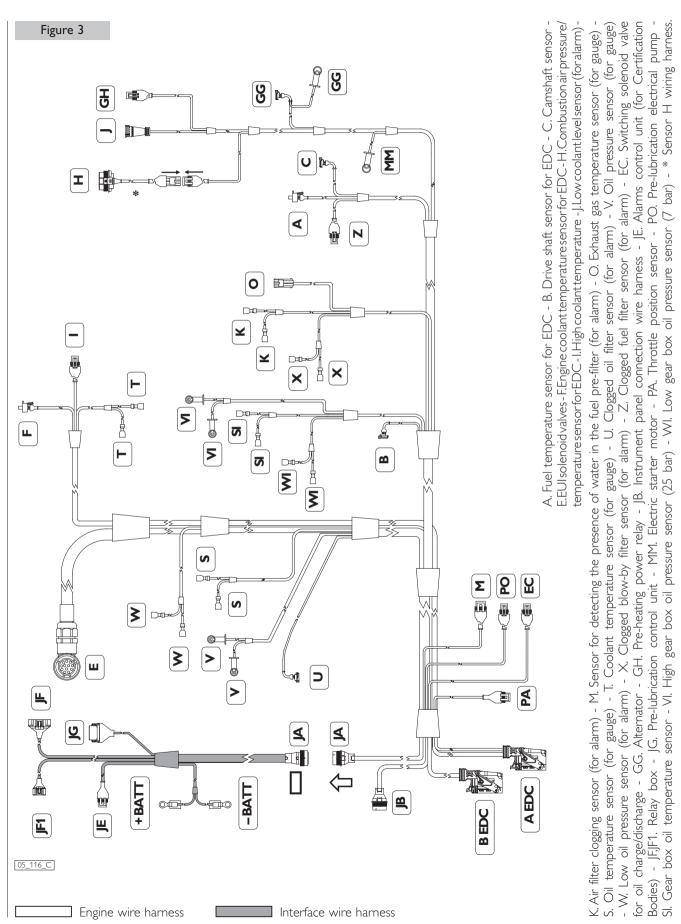
SYNOPSIS



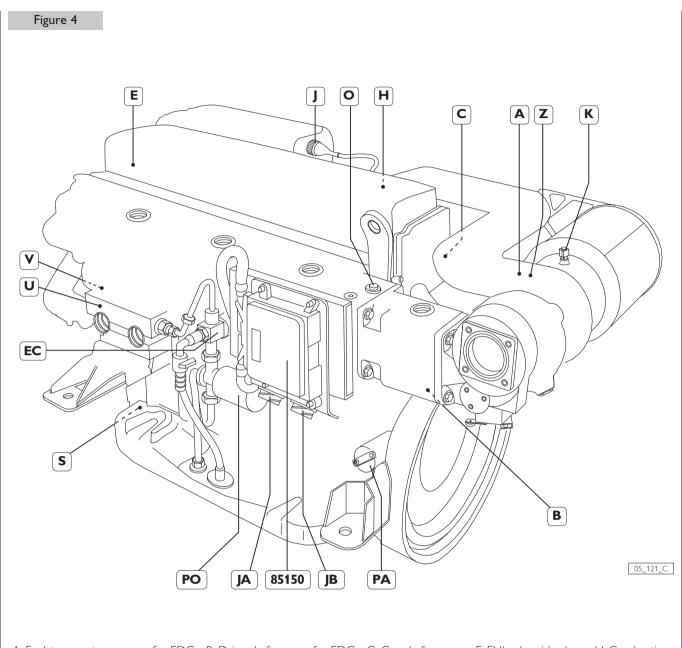
4. JE Connector for certified installations by classification Bodies - 5. Interface wire harness - 6. Power line.

The wire harnesses provided with the engine include connectors for all optional components that can be ordered and their connections to the JB connector for the instrument panel.

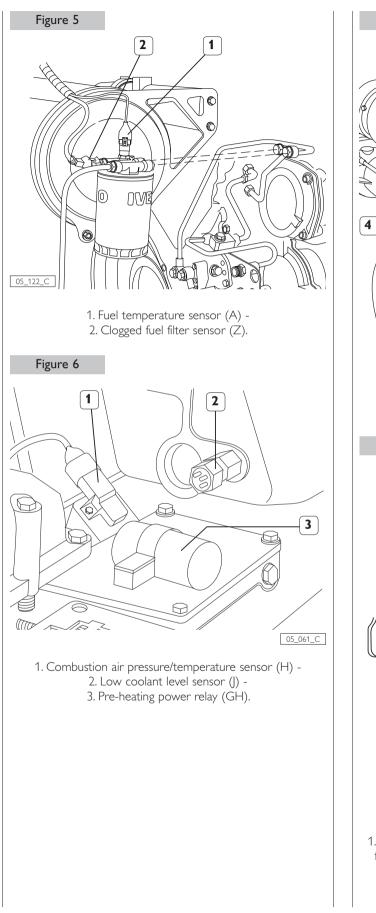
WIRE HARNESS

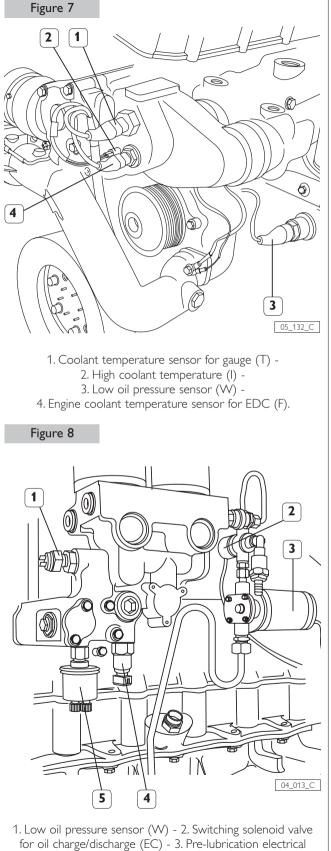


LOCATION OF ELECTRICAL COMPONENTS ON ENGINE



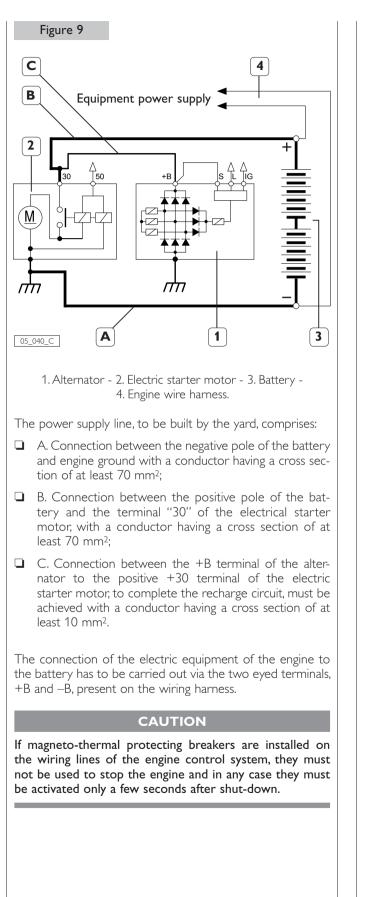
A. Fuel temperature sensor for EDC - B. Drive shaft sensor for EDC - C. Camshaft sensor - E. EUI solenoid valves - H. Combustion air pressure/temperature sensor for EDC - J. Low coolant level sensor (for alarm) - K. Air filter clogging sensor (for alarm) - O. Exhaust gas temperature sensor (for gauge) - S. Oil temperature sensor (for gauge) - U. Clogged oil filter sensor (for alarm) - V. Oil pressure sensor (for gauge) - Z. Clogged fuel filter sensor (for alarm) - EC. Switching solenoid valve for oil charge/discharge - JA. Connection between engine wiring and interface wire harness - JB. Instrument panel connection wire harness - PA. Throttle position sensor - PO. Pre-lubrication electrical pump - 85150. EDC ECU.





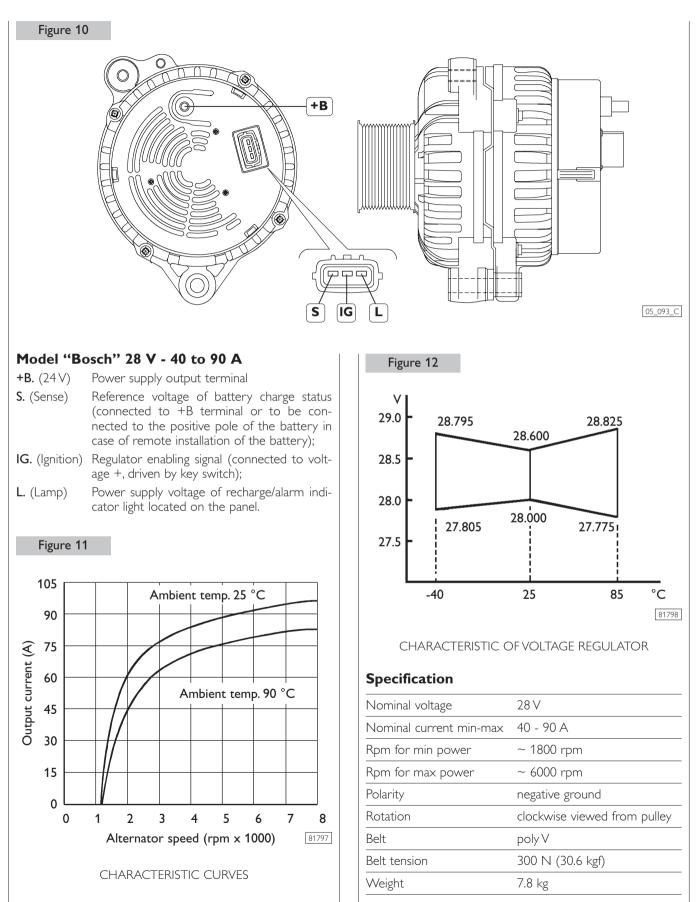
pump (PO) - 4. Clogged oil filter sensor (U) -5. Oil pressure sensor (V).

POWER SUPPLY LINE

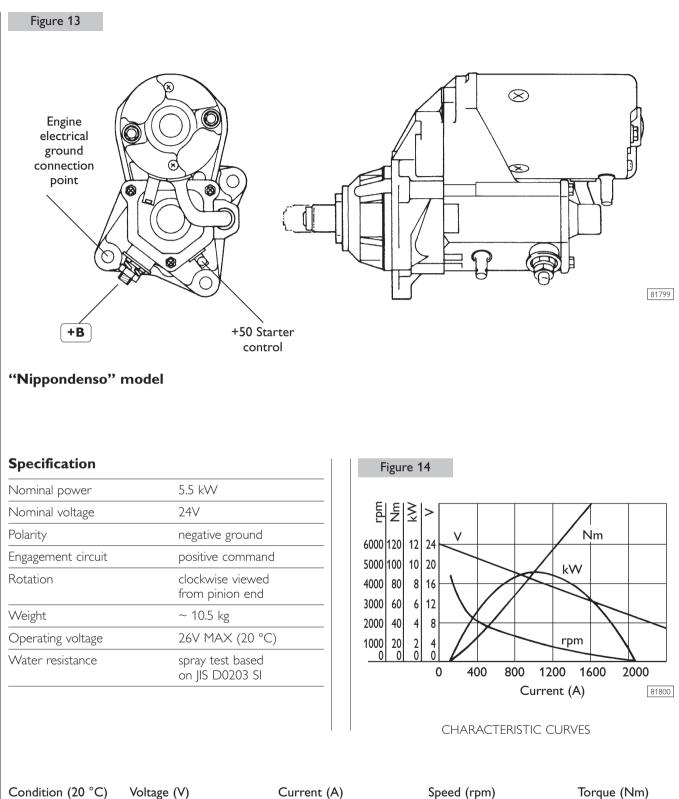


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ALTERNATOR

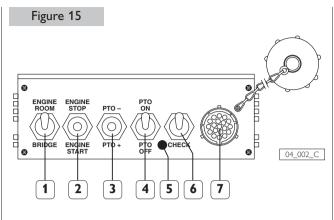


ELECTRICAL STARTER MOTOR



Condition (20 C	.) Voltage (V)	Current (A)	speed (rpm)	Iorque (INM)
No load	23	120	3800	-
Load	16	690	900	49
Stall	6	1260	0	73.5

RELAY BOX



- Engine control selector on bridge or engine room (SW1)
 Start and stop push button in engine room (SW2) Manual throttle in engine room (SW3) -
 - 4. PTO ON / PTO OFF selector (SVV3) -
 - 5. LED signaling anomalies EDC and blink code (DL1) 6. Pushbutton for blink code query (SW5) 7. Connector for external diagnosis instrument([1))

This is the main point of interconnection and carries out many interfacing functions with the various components of the system.

The electrical commands positioned on the panel allow to control engine start and stop (2) directly from the engine room, while excluding any possibility that anyone may involuntarily start the engine from the bridge (1), during servicing operations.

Engine rpm can be controlled directly from the engine room by the push-button (3) after positioning the switch (4) to ON. Among the controls present on the panel there are also the pushbutton (6) and the "blink code" light indicator (5), these can be used (also during navigation), for indications leading to the identification of failures or improper engine operating conditions (see Section 4).

Inside the box, anchored to a printed circuit board, are the power management relays of some components and the elements that protect the electrical lines against short circuits or excessive current absorption.

These components perform a similar function to that of fuses, almost completely avoiding the need to restore the electrical continuity of circuits that have been subjected to an anomaly condition. These components can limit and eliminate short circuit currents without melting - restoring their own and the circuit's electrical continuity, once the cause of the anomaly is removed.

On the relay box is located the multipolar connector, protected by a screw-on lid (7), for connection with the computerized diagnostic tools prescribed by IVECO MOTORS-FPT (see Section 4).

This is to be installed and anchored in such a way as to dampen vibrations and stresses when underway, and must be accessible during both servicing operations and when underway.

Relays contained in the relay box

- K1. EDC main (power supply);
- K2. Key switch electric discharge;
- K3. Emergency engine shut-down provision;
- K4. To enable engine start from engine room;
- K5. Power supply to terminal 50 of the electric starter motor;
- K6. Cranking exclusion when engine is running.

RPM control

To allow to easily control engine RPM from the "engine room", a simultaneous acceleration/deceleration function (PTO+ / PTO-) has been implemented, active only when the switch (1) is in the "ENGINE ROOM" position, and the switch (4) is in PTO ON position.

Acceleration (PTO +)

If the (3) push-button is held down in the "**PTO+**" position when the engine is running, then engine rpm is progressively increased. The increase ends when the push-button is released, allowing the engine to run at the desired rpm.

Deceleration (PTO -)

If the (3) push-button is held down in the "**PTO** –" position when the engine is running, then engine rpm is gradually decreased. The reduction ends when the push-button is released, allowing the engine to run at the desired rpm.

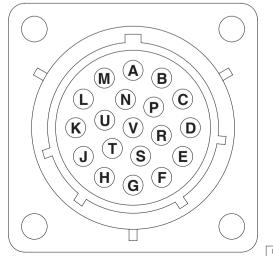
The rpm reached at that point is maintained until the engine is stopped (function takes priority and always stops the engine) or switching the (4) push-button in the PTO OFF position.

CAUTION

Never operate the "BRIDGE - ENGINE ROOM" switch when the engine is running.

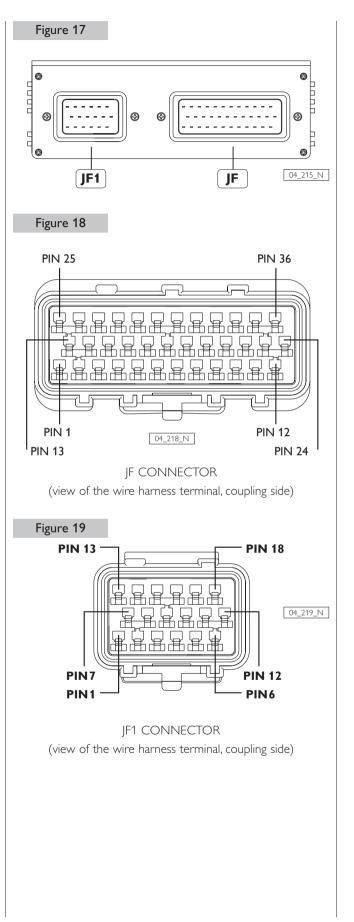
Diagnosis connector J1



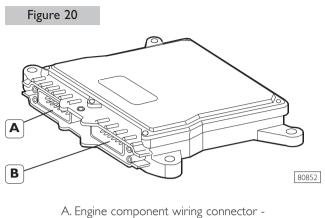


04_084_C

RELAY BOX CONNECTORS



CONNECTIONS OF THE CENTRAL ELECTRONIC UNIT (ECU)

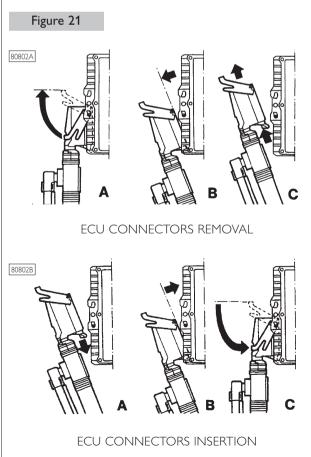


B.Vessel side wiring connector.

The connection of the central electronic unit, ECU, to the EDC system, takes place by means of two 35 way connectors mechanically polarized in the latching system to prevent inversion.

The presence of the two connectors provides for a subdivision of the wiring harnesses - to distribute the large quantity of conductors and at the same favor a quicker identification of lines during testing operations conducted by technical assistance personnel.

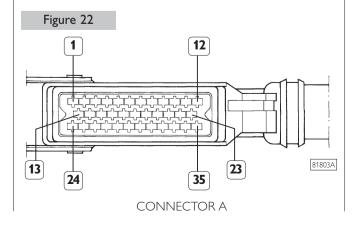
ECU connector removal and insertion



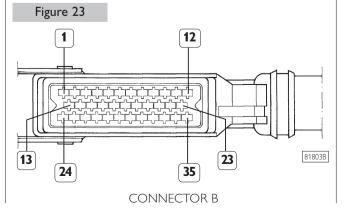
Identification of terminal functions

A Connector

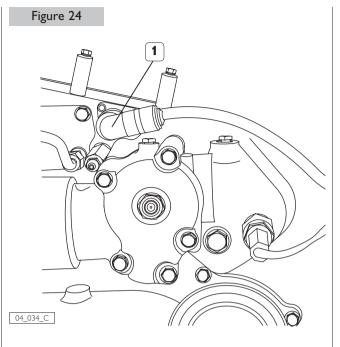
Pin	Function
1	Flywheel sensor
2	Camshaft sensor
3	By-pass intercooler control (not used)
3 4 5	Not used
5	Coolant temperature sensor ground
6	Fuel temperature sensor ground
7	Not used
8	Not used
9	Not used
10	Not used
11	Fuel temperature sensor signal
12	Intake air pressure sensor signal
13	Flywheel sensor
14	Camshaft sensor
15	Not used
16	Not used
17	Intake air pressure/temperature sensor ground
18	By-pass intercooler control (not used)
19	Not used
20	Not used
21	Intake air temperature sensor signal
22	Coolant temperature sensor signal
23	Intake air pressure sensor supply
24	Solenoid valves EUI supply cyl. 1, 2, 3
25	Solenoid valves EUI supply cyl. 4, 5, 6
26	Solenoid valve EUI control cylinder 4
27	Solenoid valve EUI control cylinder 6
28	Solenoid valve EUI control cylinder 5
29	Not used
30	Not used
31	Not used
32	Not used
33	Solenoid valve EUI control cylinder 3
34	Solenoid valve EUI control cylinder 2
35	Solenoid valve EUI control cylinder 1



Pin	Function
1	Negative supply
2	Negative supply
3	Positive supply (from relay K1)
4	Positive supply (from relay K1)
5	Engine speed output signal
6	EDC fault indicator control
7	Not used
8	Not used
9	Engine phase output signal
10	Pre-heating relay control
11	CAN line
12	CAN line
13	Diagnosis line
14	Not used
15	Positive connected to + 15
16	Throttle position sensor supply
17	Idling switch signal
18	Pre-heating indicator control
19	Not used
20	Not used
21	Not used
22	Not used
23	Throttle position sensor signal
24	Diagnosis line
25	Resistor 3.3 k Ω (balancing load)
26	Not used
27	Main relay control
28	Not used
29	Resistor 3.3 k Ω (balancing load)
30	Not used
31	Not used
32	Not used
33	Not used
34	Not used
35	Throttle position sensor ground



EUI SOLENOID VALVE CONNECTOR



1. E connector.

The wiring that connects the solenoid valves of the EUI injectors to the ECU is divided into two branches: the first is located in the compartment that houses the distribution elements, connects each solenoid valve to the 12 way through-bulkhead connector, fastened on the front part of the cylinder head; the second is integrated into the engine wire harness connected to the EDC ECU and terminates with the threaded ring nut connector.

Figure 25

VIEW FROM THE ENGINE OUTER SIDE

A	Injector 1 control	Pin ECU A 35
В	Injector 1 supply	Pin ECU A 24
С	Injector 2 control	Pin ECU A 34
D	Injector 2 supply	Pin ECU A 24
E	Injector 3 control	Pin ECU A 33
F	Injector 3 supply	Pin ECU A 24
G	Injector 4 control	Pin ECU A 26
Н	Injector 4 supply	Pin ECU A 25
	Injector 5 control	Pin ECU A 28
L	Injector 5 supply	Pin ECU A 25
Μ	Injector 6 control	Pin ECU A 27
Ν	Injector 6 supply	Pin ECU A 25

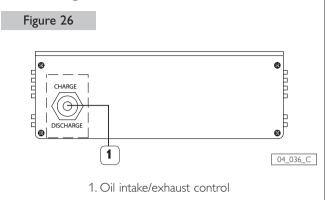
CAUTION

The wiring that connects the injector solenoid valves to the through-bulkhead connector is made with connectors whose insulation is capable of withstanding the challenging conditions of the environment where it is located. These are braided to avoid generation of electromagnetic interference.

For an improved operating efficiency, no junctions or repairs are allowed either along the conductors or on the terminals. If flaws are noted in this wiring portion, it must be replaced with an original spare part.

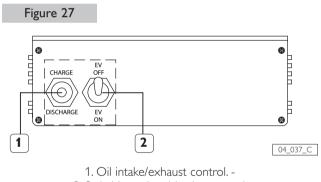
OPTIONAL EQUIPMENT

Lubricating oil transfer module



Lubricating oil transfer operations are simplified by the presence of an electrical control system connected to the JG connector of the interface wiring harness. Manual control for transfer operations is positioned on the front panel unit. For safety reasons, control is enabled only with the key switch in the "OFF" position.

Pre-lubrication and oil transfer module

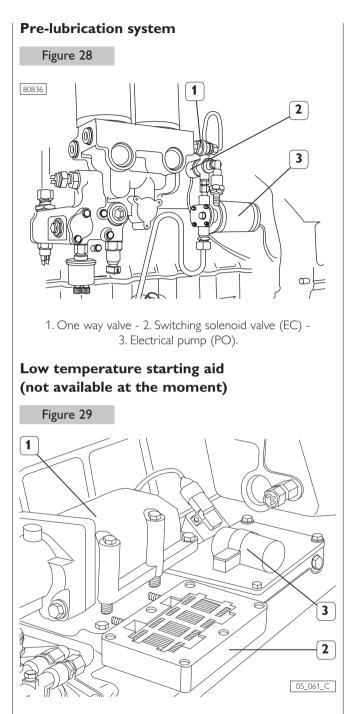


2. Switching solenoid valve control.

The module is connected to the JG connector of the interface wiring harness.

The task of pre-lubricating the engine's internal components is managed and controlled by the electronic circuit of the module when the key switch is placed in "ON" position. With the key switch in the "OFF" position, the operation can also be performed manually by using the oil intake/ exhaust push-button positioned on the front panel. If the push-button is placed for a few seconds in the "DISCHARGE" position, the filters and the internal engine ducts will be filled. Lubricating oil transfer sequence:

- 1. Place the "EV-OFF / EV-ON" (2) switch in the "EV-ON" position, thus energizing the switching solenoid valve to place the emptying/filling junction in communication with the electrical pump and with the oil sump;
- 2. Use the "CHARGE / DISCHARGE" (1) push-button to complete the desired operation;
- 3. Place the "EV-OFF / EV-ON" switch back to the "EV-OFF".



1. Specific junction pipe - 2. Electrical grid heater - 3. Power relay.

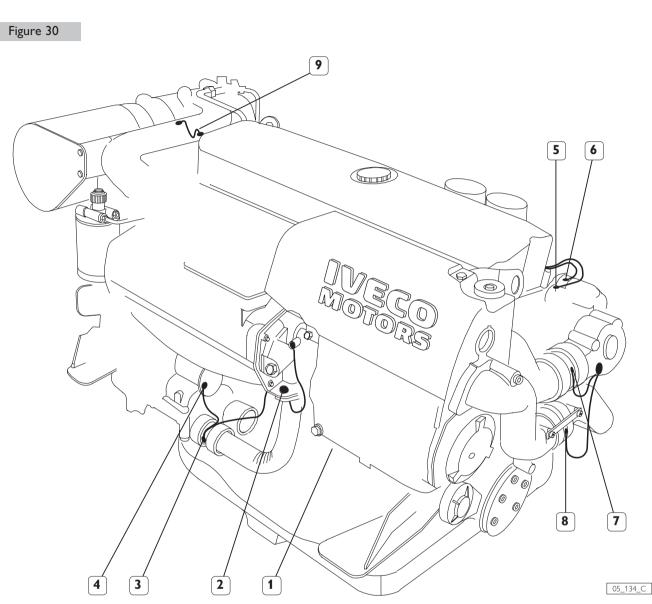
When the engine is to be used at temperatures lower than -15 °C, an electrical grid heater (PH) is installed. Its operation is controlled by the electronic unit of the injection system. The element will be placed between the turbocompressor and the air/water heater exchanger (after-cooler), replacing the terminal part of the intake duct.

Connection to the electrical wiring provided is achieved interposing a specific relay (GH) and connection to the power supply grid.

For use at temperatures lower than -25 °C, adoption of an auxiliary preheating system is recommended.

EQUIPOTENTIAL CONNECTIONS TO ENGINE GROUND

To prevent electrochemical corrosion phenomena, some elements included in the cooling circuits are electrically grounded with copper braids with eyelet terminations.



Elements connected to engine ground with metallic braid conductor:

Sea water outlet junction from water/water heat exchanger (not shown) - 2. Sea water supply pipe to air/sea water exchanger - 3. Sea water pump outlet junction - 4. Sea water pump closure lid - 5. and 6. Inlet-outlet junction for the fresh water cooling the exhaust manifold - 7. Junction of the pipes supplying fresh water to the water/water exchanger - 8. Junction of the fresh water outlet pipes from the water/water heat exchanger - 9. Air input connection for the air/sea water heat exchanger.

CAUTION

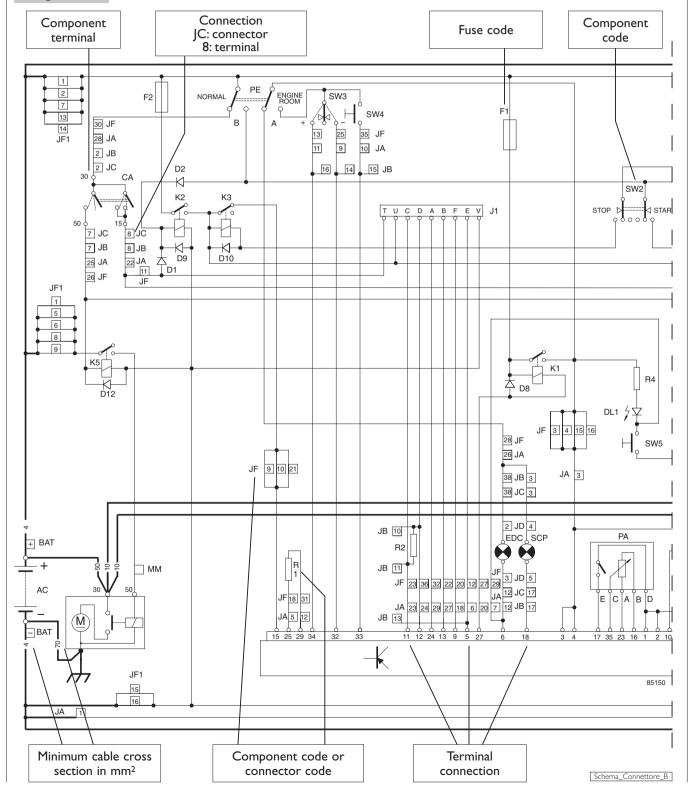
To enhance connection efficiency, the screw threads and the surfaces in contact with the electrical terminals must be clean and not oxidized. Thoroughly inspect and remove any impurities before each reinstallation procedure.

Wiring diagram key

General condition for the preparation and interpretation of wiring diagrams

- □ Key switch open;
- Engine not running;
- Liquids at efficient levels and pressures.

Figure 31



Electrical equipment component code

A	fuel temperature sensor for EDC
AC	battery
AQ	engine shut-off push-button on main panel
AS	engine shut-off push-button on secondary panel
В	drive shaft sensor for EDC
C CA CS	camshaft sensor
CA	key switch
CS	engine start push-button on secondary panel
DL1	EDC fault indicator and blink code LED (on relay box panel)
EC	switching solenoid valve for oil charge/discharge
F	engine coolant temperature sensor for EDC
GG	alternator
GH	power relay for starting aid
Н	combustion air pressure/temperature sensor for EDC
	high coolant temperature sensor (for alarm)
IN	injectors solenoid valve
J	low coolant level sensor (for alarm)
К	air filter clogging sensor (for alarm)
L	instrument panel light switch
Μ	sensor for detecting the presence of water in the fuel pre-filter (for alarm)
MC	CAN - BUS converter module for digital panel
MM	electric starter motor
MP	pre-lubrication and oil transfer module
MS	IVECO MOTORS-FPT indications and alarms module
0	exhaust gas temperature sensor (for gauge)
P1	sound alarm inhibition push-button
PA	throttle position sensor
PE	emergency shut-down push-button (optional, installer's responsibility)
PH	grid heater
PO	pre-lubrication electrical pump

QP	main analog instrument panel
QS	secondary analog instrument panel
R1	3.3 k ${f \Omega}$ resistor to inhibit speed input
R2	DL1 resistor
R3	alternator pre-excitation resistor
S	oil temperature sensor (for gauge)
SA	buzzer
SI	gearbox oil temperature sensor
SW1	bridge or engine room engine control selector (on relay box panel)
SW2	start and stop push button (on relay box panel)
SW3	manual accelerator throttle control in engine room (on relay box panel)
SW4	PTO ON / PTO OFF selector (on relay box panel)
SW5	blink code emission request push-button (on relay box panel)
Т	coolant temperature sensor (for gauge)
U	Clogged oil filter sensor (for alarm)
V	oil pressure sensor (for gauge)
VI	high gearbox oil pressure sensor (25 bar)
W	low oil pressure sensor (for alarm)
WI	low gearbox oil pressure sensor (7 bar)
X Z	clogged blow-by filter sensor (for alarm)
Z	clogged fuel filter sensor (for alarm)
85150	ECU of the EDC system

(continues on next page)

Electrical equipment component code (cont.)

Connectors

A	35 pole EDC boat components
 B	35 pole EDC engine components
 E	EUI injectors solenoid valve
]1	external diagnostic tool (on the relay box panel)
JA	connection between engine wiring and interface wire harness
JA on se	ECONDARY DIGITAL INSTRUMENT PANEL set for connection to the main digital instrument panel
JB on en	IGINE WIRE HARNESS set for connection to the main analog instrument panel or to the interface wire harness for converter module
JC on m	AIN ANALOG INSTRUMENT PANEL set for connection to the engine wire harness
JD	IVECO MOTORS-FPT indications and alarms module
JD on in	ITERFACE WIRE HARNESS FOR CONVERTER MODULE external throttle control
JE on m/	AIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog instrument panel
JE on in	TERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the main digital instrument panel
JE on m	AIN DIGITAL INSTRUMENT PANEL set for connection to the secondary digital instrument panel
JE on m	AIN INTERFACE WIRE HARNESS set for connection to the alarms control unit (for Certification Bodies)
JE1 on II	NTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the 2 nd main digital instrument panel
JF	relay box
JF1	relay box
JG	pre-lubrication control unit
JH on se	ECONDARY ANALOG INSTRUMENT PANEL set for connection to the main analog instrument panel
JH on m	AIN DIGITAL INSTRUMENT PANEL set for connection to the interface wire harness for converter module

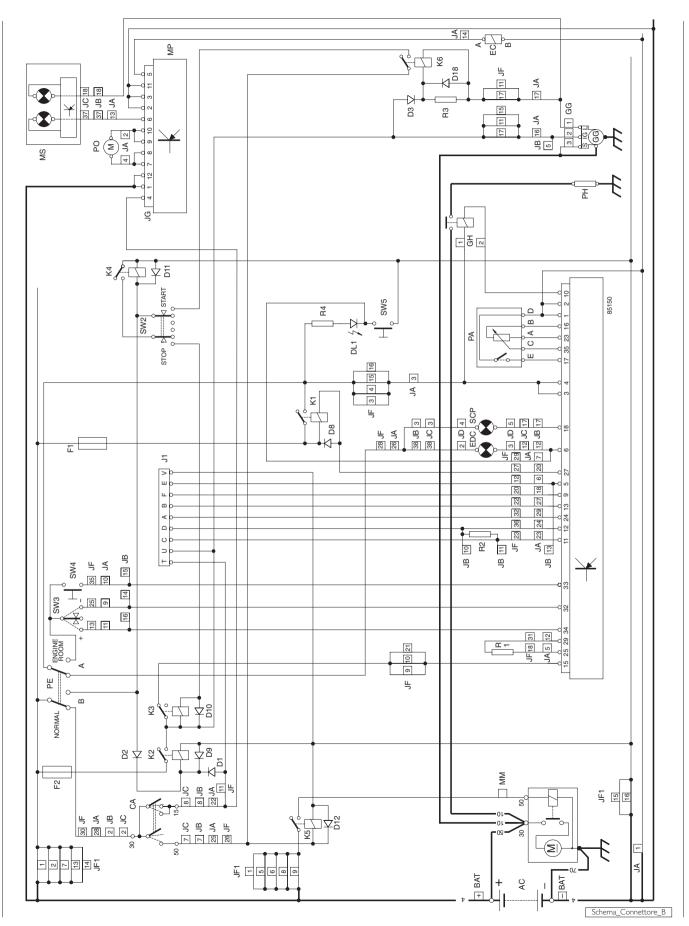
edc	EDC malfunction		
SAC	presence of water in fuel pre-filter		
SATA	coolant high temperature		
SBLA	low coolant level		
SBPO	low oil pressure		
SCP	pre-post heating		
SIFA	clogged air filter		
SIFB	clogged oil vapor filter		
SIFC	clogged fuel filter		
SIFO	clogged oil filter		
SIM	expired programmed maintenance interval		
SP	pre-lubrication		
SS	alternator fault		
SSV	overspeed engine		
Gauges			
Gauges CG	revolution-counter		
	revolution-counter gearbox oil pressure		
CG			
CG MI	gearbox oil pressure		
CG MI MO	gearbox oil pressure engine oil pressure		
CG MI MO TA	gearbox oil pressure engine oil pressure engine temperature		
CG MI MO TA TI	gearbox oil pressure engine oil pressure engine temperature gearbox oil temperature		
CG MI MO TA TI TS V Relays c	gearbox oil pressure engine oil pressure engine temperature gearbox oil temperature exhaust gas temperature voltmeter		
CG MI MO TA TI TS V	gearbox oil pressure engine oil pressure engine temperature gearbox oil temperature exhaust gas temperature voltmeter		

K3	emergency engine shut-down provision		
K4	enabling start engine from engine room		
K5	power supply to terminal 50 of the electric starter motor		
K6	cranking exclusion when engine is running		

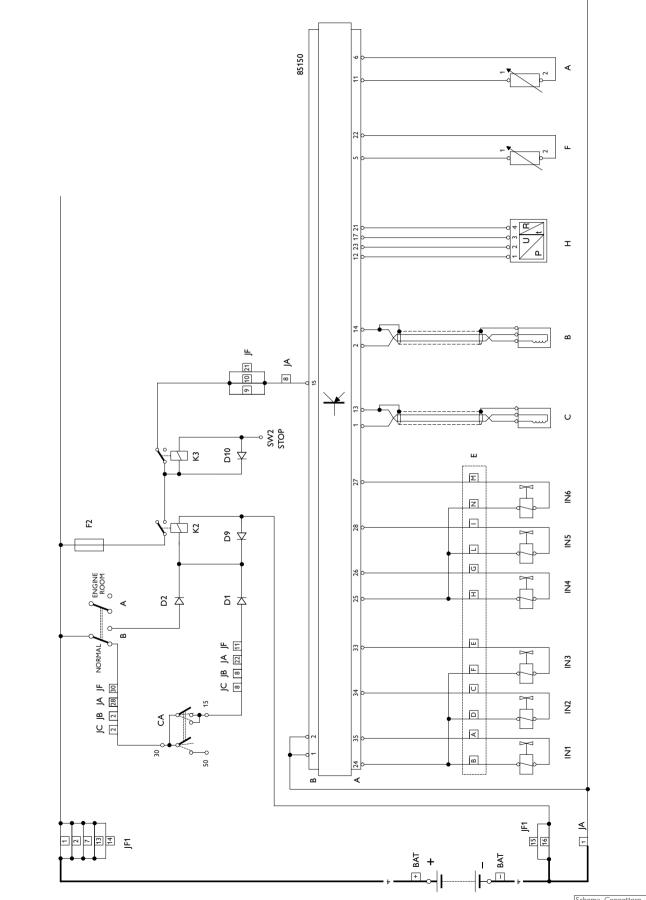
Fuses contained in the relay box

F1, F2 self restoring (not replaceables)

EDC connector **B**

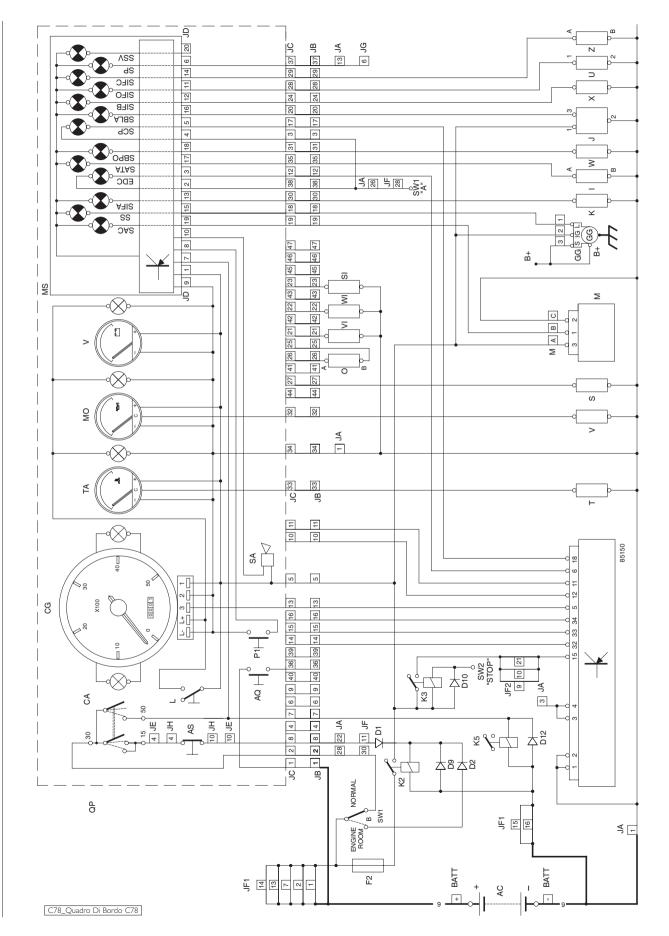


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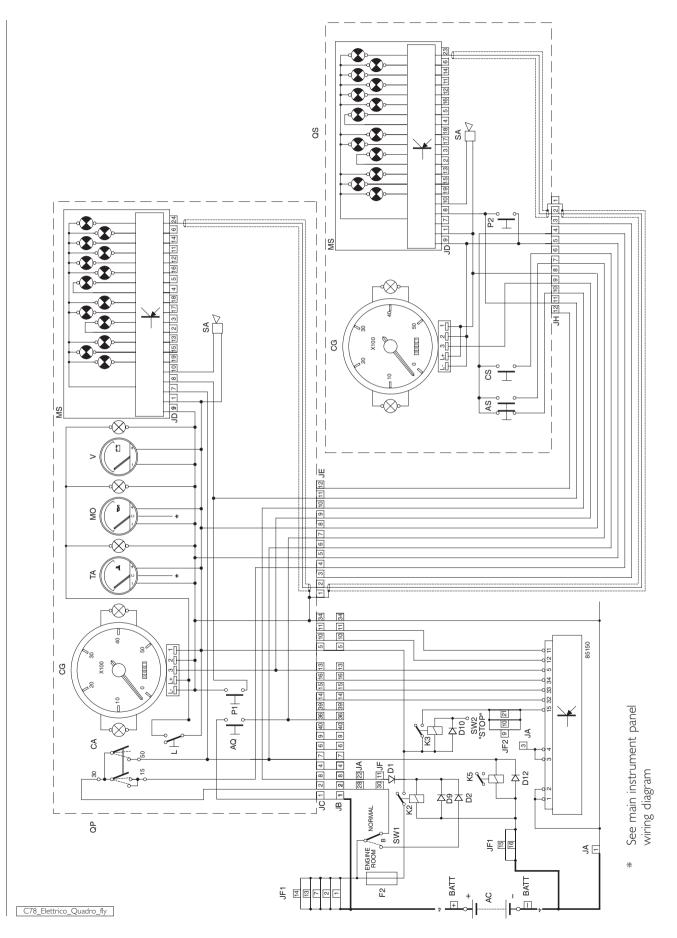


Schema_Connettore_A2°

Main analog instrument panel



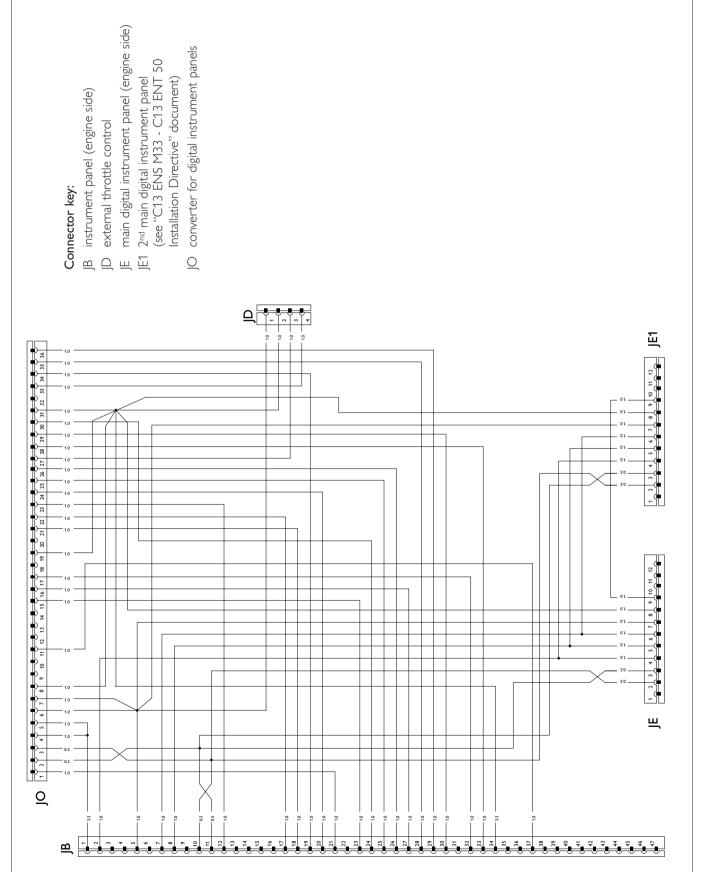
Secondary analog instrument panel





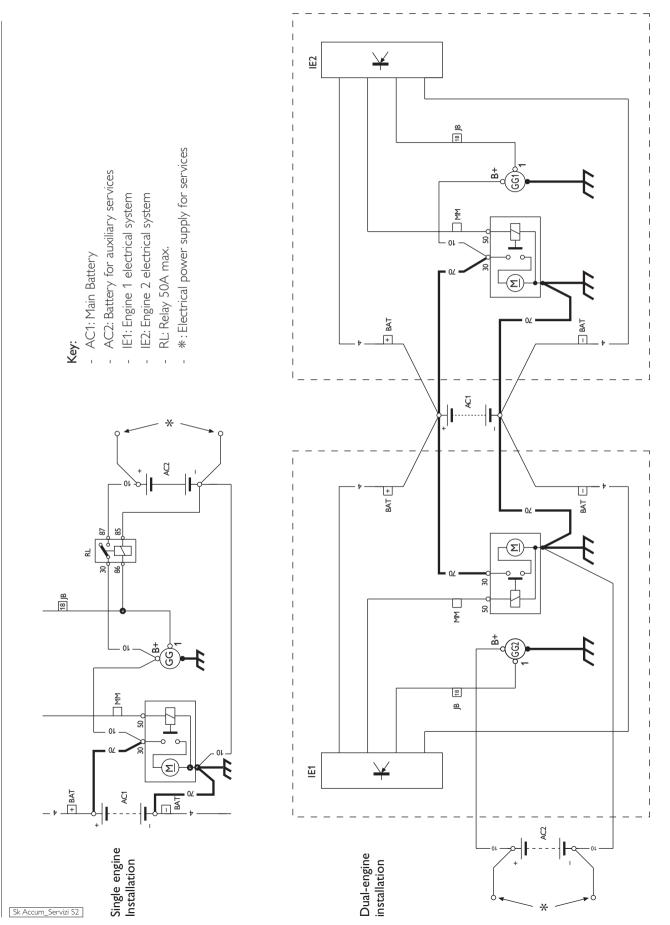


CAN - BUS converter module interface wiring



Sk_Cablag_Convert_C78

Supplementary services battery recharge



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SECTION 4

DIAGNOSTICS

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A correct diagnosis is achieved by using the competence acquired with years of experience and attendance at training courses.

When the user complains of poor performance or operating anomalies, due consideration must be given to his/her indications, deriving from them useful information to orient our actions.

After ascertaining the existence of the anomaly, we recommend starting troubleshooting operations by decoding the self-diagnosing data of the Central Electronic Unit of the EDC system.

The continuous operating tests on the components connected to it and the tests of the operation of the entire system conducted periodically in operation, provide an important diagnostic method, made available by decoding the "error/anomaly" codes issued by the blinking of the fault indicator light: the "blink-code".

Using computerized IVECO MOTORS-FPT instruments, IT 2000 and PT 01, two-way communications can be established with the central unit, enabling not only the decoding of the error codes but also to route the investigation in its memory to retrieve additional information required to determine the origin of the fault.

Every time a problem is notified and its existence is ascertained, you must query the electronic unit in one of the ways indicated and then proceed with troubleshooting via tests and measurements, to obtain a picture of the overall operating conditions and identify the real causes of the fault.

If the electronic unit provides no indications, proceed by using your acquired experience, adopting traditional diagnostic methods.

Technicians and maintenance personnel are recommended, in these cases, to check the ratings and technical data in the "C13 ENS M33 - C13 ENT M50 Installation Directive" document.

Partly in order to overcome service personnel's lack of experience on this new system, we have provided, in the pages that follow, a TROUBLESHOOTING GUIDE.

The guide comprises two distinct sections:

- The first, organized by Blink Code, concerns anomalies identified by the MS 6.2 unit, of mainly an electrical or electronic nature;
- The second, organized by symptoms, describes the possible anomalies not recognized by the electronic unit, frequently mechanical or hydraulic in nature.

For maintenance prescriptions, see the indications provided in Section 5.

ECU BEHAVIOUR

Anomalies indicator light

C13 ENS M33

C13 FNT M50

The ECU continuously monitors, with complex self-testing routines, its own operating condition as well as that of the engine and the components connected to it.

When anomalies are detected, the fault indicator light on the instrument panel is lighted in a manner that provides a first indication of the severity of the problem.

- Light off: No anomaly detected or slight anomaly that does not compromise operating safety;
- **Light on:** Significant anomaly, that allows to proceed to a service center;
- Blinking light: Severe anomaly requiring immediate repairs. If possible, shut the engine down.

Blink code

Emission of the anomaly codes detected during self-testing and stored in the ECU, starts after the "CHECK" push-button on the relay box panel is pressed and released - when the "BRIDGE - ENGINE ROOM" switch is in the "ENGINE ROOM" position.

The LED located at the side of the push-button and the EDC indicator light on the instrument panel will simultaneously signal, with two series of emissions at different frequencies, the blink codes that indicate the anomaly with decimal numbering.

Slow blinks identify the area of the anomaly (engine, injectors, ...), **fast blinks** identify a specific anomaly.

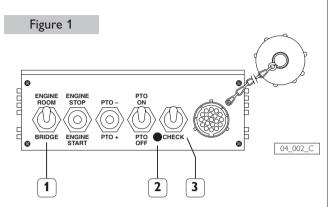
Every time the push-button is pressed and released, only one of the stored codes is emitted; therefore, the procedure must be repeated until an error indication identical to the first one is obtained, which means the entire error memory has been analyzed.

If no anomalies are stored, the light comes on when the push-button is pressed and comes off about 1 second after its release, without any subsequent blinking.

NOTE

The blink code diagnostic procedure provides indications about current anomalies as well as past anomalies that are no longer present when the diagnosis is carried out; therefore, it is absolutely mandatory, at the end of every repair operation, to erase the error memory to prevent future notification of repaired anomalies.

Error deletion procedure



- A. Shut the engine down and keep the key switch in the "OFF" position for 15 seconds (after run).
- B. Approach the relay box. Keeping the "CHECK" diagnostic push-button (3), move the adjacent "BRIDGE ENGINE ROOM" switch (1) to the "ENGINE ROOM", wait for the luminous indicator (4) to switch off position, while keeping the diagnostic push-button pressed for 8 more seconds.
- C. Release the push-button and move the "ENGINE ROOM" switch to the "BRIDGE" position

CAUTION

The error deleting procedure is intended to eliminate the information relating to the mistakes from the ECU memory, which happened during previous working periods. The errors will not be deleted unless the relating cause has been removed. Please remember that some anomalies can be detected by the ECU self-diagnosis only during a complete engine working cycle.

Confirmation that cancellation has been carried out is provided by a subsequent query of the blink code; the blink code light (2) should not give out any code.

Recovery

The recognition of significant or sever anomalies causes the adoption of strategies that allow to use the engine with complete safety, guaranteed by limiting performance within preset thresholds according to the severity of the malfunction.

These strategies cause the reduction of the maximum values of torque and power delivered by the engine.

In the case of intermittent anomalies, i.e. recognized by the ECU and subsequently no longer present, performance reduction will continue until the engine is shut down.

Normal operation will be restored only the next time the engine is started, while the anomaly data will be "saved" in the failure memory.

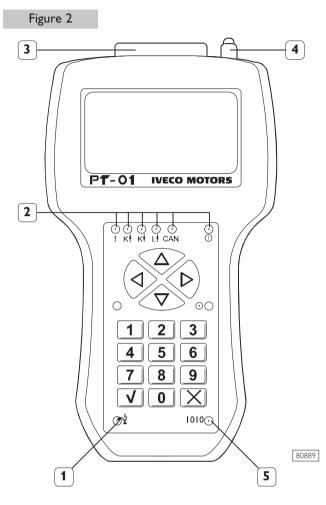
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BLINK CODE TABLE

Blinking Code	EDC Indicator light	Indicated Fault
Control area	a	
1.1	(on)	not significant in marine applications
1.2	(on)	not significant in marine applications
1.3	(off)	not significant in marine applications
1.4	on	throttle position sensor
1.5	(off)	not significant in marine applications
1.6	(on)	not significant in marine applications
1.7	(off)	not significant in marine applications
Engine area		
2.1	off	coolant temperature sensor
2.2	off	intake air temperature sensor
2.3	off	fuel temperature sensor
2.4	on	supercharge air pressure sensor
2.5	off	ambient pressure sensor (inside the unit)
2.6	(on)	not significant in marine applications
3.5	off	battery voltage
Injectors		
5.1	on	cylinder 1 injector fault
5.2	on	cylinder 2 injector fault
5.3	on	cylinder 3 injector fault
5.4	on	cylinder 4 injector fault
5.5	on	cylinder 5 injector fault
5.6	on	cylinder 6 injector fault
Engine rpm	sensor	
6.1	on	flywheel sensor
6.2	on	timing system sensor
6.4	blinking	overspeed engine
Electronic u	nit	
9.1	blinking	defective unit
9.2	on	incorrect EEPROM data
9.3	(blinking)	not significant in marine applications
9.4	on	main relay
9.5	on	erroneous engine shut-down procedure
9.6	on	unit data storage operation not completed

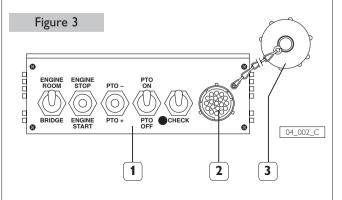
DIAGNOSIS WITH THE PT-01 INSTRUMENT

Engine diagnosis must be done with the IVECO MOTORS-FPT PT-01 instrument.



 USB Indicator light - 2. LEDs signalling communication between instrument and central unit, and correct power supply - 3. Connector to engine diagnosis outlet -4. Connector for outside power supply -5. Serial port indicator light.

Connect the instrument with the dedicated cable to the diagnosis connector J1 (2) on the relay box (Fig. 3).





The instrument is powered directly from the diagnosis outlet. In case of prolonged use with the engine off, the instrument can be powered externally through the connector (4) of Fig.2.

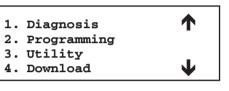
After establishing a connection between the instrument and the diagnosing outlet, the instrument displays available applications.

Functions of the Instrument

Through the numeric keypad (0 to 9) select the application and confirm it with the \checkmark key.

The second screen shows information about the software version of the selected application.

To start the actual diagnosis procedure, press the \checkmark key.



CAUTION

The two arrows $\uparrow \Psi$, when present, signal that other options are available but not displayed. To display them, use the $\uparrow \Psi$ arrows on the keypad.

To access the diagnosis procedure, press the ${\bf 1}$ key and confirm with the ${\bf \overline{V}}$ key.

The instrument displays the following options:

- 1. Identifier
- 2. Fault memory
- 3. Parameter reading
- 4. Active diagnostics

An operation is selected by pressing the associated numeric key and confirming it with the \mathbf{V} key.

To go back to the previous screen, press the \mathbf{X} key.

Identifier

This option allows to obtain the following information, related specifically to the central unit system:

- Operator code;
- Station type;
- Station number;
- Date programmed;
- Release;
- Type of ECU;
- ECU software version;
- Job Number;
- Engine type;
 - Original engine type;

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- Engine serial number;
- Alphanumeric code.

Fault Memory

This option allows to display the faults that occurred during operation. They are grouped in two categories:

- Intermittent;
- Present.

Faults indicated as intermittent occurred previously but are not present at the time the fault memory is read. Faults indicated as present are such or occurred during the last period of operation of the engine. In this case, shutting the engine down and starting it again will cause the indication to change to intermittent.

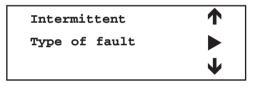
First screen



2. Intermittent

NOTE: When both types of fault are present.

Second screen



Use the arrows $\uparrow \downarrow$ to scroll through the list of present faults, while the symbol \blacktriangleright indicates the presence of additional information available for display with the \rightarrow key. This additional information is about system conditions (temperature, engine rpm, etc.).

Errors detectable by the system and that can be displayed with the instrument are:

Sensors

- Throttle;
- Water temperature;
- Supercharging air temperature;
- Fuel temperature;
- Supercharging pressure;
- Ambient pressure;
- Flywheel;
- Camshaft;
- Quantity of air taken in.

Engine

- Overspeed engine;
- Injectors;
- Pre-post heating control system.

Relays

- Main.

Power supply voltage

Indicator lights

- Pre-post heating;
- EDC.

Central Unit

- Invalid data set;
- Incorrect data storage;
- Internal fault (Gate Array);
- Sensors power supply;
- Internal fault (re-initialization);
- Incorrect engine shutdown;
- Defective EEPROM.

Parameter reading

Parameters available for display are grouped in two categories:

- Measurable;
- State.

List of measurable parameters

- Engine RPM;
- Injection advance;
- Ambient pressure;
- Battery voltage;
- Throttle lever position;
- Supercharging pressure;
- Supercharging air temperature;
- Cooling liquid temperature;
- Fuel temperature.

List of ECU state parameters

- Key set to run (+15);
- Idle switch (in throttle potentiometer);
- EDC indicator light;
- Blink Code push-button;
- Pre-post heating resistor relay (*);
- Pre-heating indicator light (*).

Active diagnostics

Active diagnostics consist of electrically commanding the components to verify their operating condition.

The components driven by the instrument are:

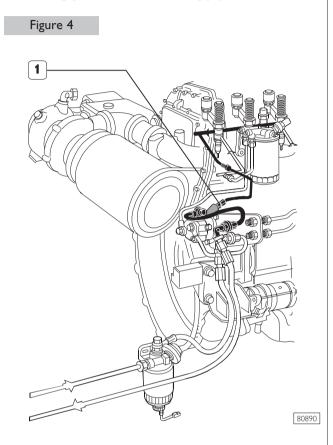
- Pre-post heating resistor relay (*);
- Pre-heating indicator light (*);
- EDC indicator light.

(*) When present.

MAJOR DIAGNOSTIC ACTIONS

The following is a description of the procedures to carry out the major instrumental measurements mentioned in the diagnostics guide.

Checking pressure in fuel supply line



To obtain reliable values, measurement on the line must be taken with a pressure gauge with 10 bar scale end with oil damped indicator. The gauge will be connected through a "T" joint inserted in point (1), upstream of the valve set present on the fuel supply pump. With the engine idling, pressure should be 3.5 bar, with a tendency to increase with engine RPM, until achieving a maximum value of over 5 bar. The measurement is reliable if taken under actual engine loading conditions, i.e. while underway.

Venting the fuel loop

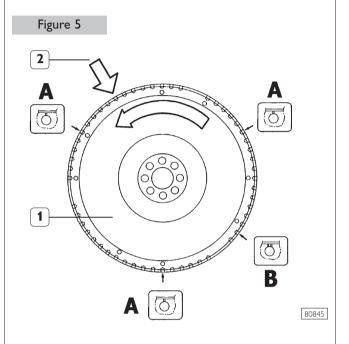
See Section 6.

Checking the keying of timing phonic wheel

See Section 6.

Checking the timing phase

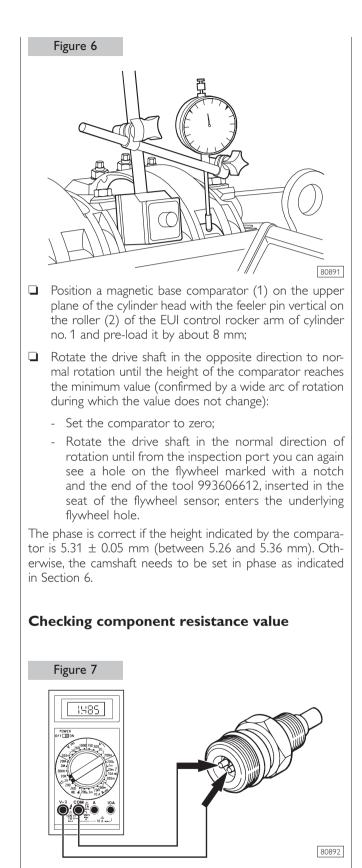
The camshaft is correctly in phase when, with the drive shaft in top dead center of the cylinder piston no. 1 at end of compression, the elevation measured on the roller of the rocker arm driving the injector of cylinder no. 1 is between 5.26 mm and 5.36 mm.



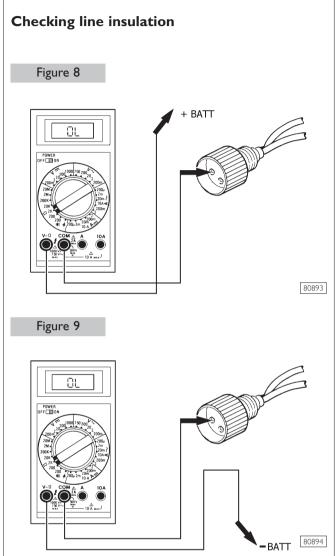
A. Holes marked with a notch - B. Hole marked with two notches - 1. Engine flywheel - 2. Flywheel position sensor.

Procedure

Rotate the drive shaft in the position corresponding at the piston of cylinder no. 1 to end of compression top dead center; from the inspection port below the flywheel case you will be able to see a hole marked with a notch (A) and simultaneously from the seat of the flywheel sensor, indicated with the arrow in the figure, you will be able to see the 11th hole of the sector (identifiable by rotating the flywheel in the normal direction of rotation of the engine, starting to count with no. 1 after the segment lacking holes).



Ensure that the system is not powered. The measurement must be taken on each individual component, isolated from its wiring or connected only to the instrument, set as ohmmeter on the appropriate end of scale value (see REFER- ENCE VALUE table in the pages that follow). At the end, restore the correct connection.



Ensure that the system is not powered. The measurement must be taken on each individual conductor, isolated from all the components to which it is normally connected. The measurement must be taken with the instrument set as ohmmeter on end of scale value \geq 200 k Ω , and it must be taken both towards the positive potential and the negative battery potential. At the end, restore the correct connection.

REFERENCE VALUES

For non hardwired sensors

Component	Test conditions	$\begin{array}{c} Minimum\ \Omega\\ value \end{array}$	$\begin{array}{c} Maximum\ \Omega\\ value \end{array}$	
Intake air temperature sensor	-10 °C	8100	10800	
	0 °C	5200	6750	
Coolant temperature sensor	20 °C	2300	2700	
	50 °C	730	950	
Fuel temperature sensor	80 °C	300	360	
Flywheel position and rotation sensor	20 °C	800	1000	
Camshaft position and rotation sensor	20 °C	800	1000	
Safety contact in	Lever in posi	tion 0	Open circuit	
throttle position sensor	Lever in posi	tion ≠ 0	1000	
Solenoid valve coil EUI Injector	-	0.5	0.6	
Electrical heating element (on request)	-	0.2	0.3	

CAUTION

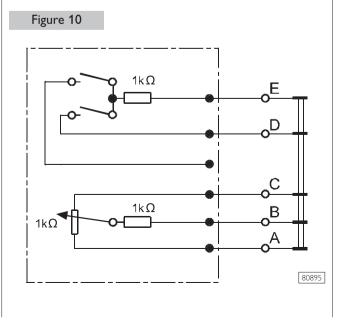
Measurements refer only to the reference component.

The actual measurement of small values of resistance requires use of instruments with the SELF-ZEROING function or, if these are not available, subtract from the read value the short-circuit value of the instrument prods.

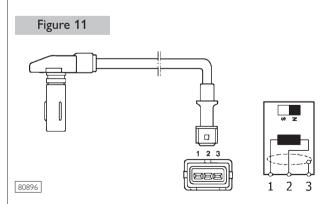
Measurements closest to reality are taken including the wiring from the ECU to the sensor.

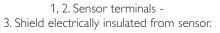
Always check the continuity of the SHIELD conductor from the sensor to the ECU and the latter's good insulation from the other signal conductors.

Throttle position sensor



Sensors wired with shielded wires





REFERENCE VALUES

For wired sensors powered by the ECU

Component	ECU connection	Test conditions	Minimum - maximum value
Combustion air temperature sensor signal	A17 A21	Panel key ON	0.5 to 4.5 Vcc
Coolant temperature sensor signal	A5 A22	Panel key ON	0.5 to 4.5 Vcc
Fuel oil temperature sensor signal	A6 A11	Panel key ON	0.5 to 4.5 Vcc
Flywheel position and rotation sensor signal	A1 A13	Engine running 600 rpm	> 0.8 Vac
Camshaft position and rotation sensor signal	A2 A14	Engine running 600 rpm	> 0.2 Vac
Combustion air absolute pressure sensor signal	A17 A12	Engine running 600 rpm	0.9 to 1.1 Vcc
Combustion air absolute pressure sensor power supply	A17 A23	Panel key ON	4.5 to 5.5 Vcc
Safety signal from	B17 B25	Lever in position 0	> 4 Vcc
throttle position sensor	DI/ DZJ	Lever in position $\neq 0$	< 1 Vcc
Throttle lever position sensor power supply	B16 B35	Panel key ON	4.5 to 5.5 Vcc
Position signal from	B23 B35	Lever in position 0	0.3 to 0.5 Vcc
throttle position sensor	רנם נזט	Lever in position \neq 0	0.3 to> 3 Vcc

GUIDE TO BLI	GUIDE TO BLINK CODE DIAGNOSIS			
Blink EDC Code light	System reactions	Possible cause	Recommended tests or action	Notes
1.1 On Unbalanced input anomaly	EDC indicator light on for no reason	The resistive load simulator is not detected	Check the integrity of the 3.3 k Ω resistance between pins A B25 and B29 of the EDC connector and the associated wiring.	A resistive load replaces a signal that is not used in this application
	Power reduction. Fast idling with the throttle lever in any position.	Idling switch (in throt- tle sensor) signal shorted or shorted to ground or shorted to positive or open circuit	Read measurable parameters with the diagnosis instrument to verify the idling switch does not work (switching ON-OFF). Using a multimeter on the component, check the integrity of the idling switch (switching ON-OFF). If the switch is integral, search for a break in the wiring between the throttle connector (wiring side) and the EDC connector pin B17 and B2.	
1.4 On Throttle position sensor anomaly	Power reduction. With the throttle lever at rest, the engine runs at fast idling speed. On moving the lever, the engine speed increases progressively and uncon- trollably	No throttle potentiometer signal. Shorted or shorted to ground or shorted to positive or open circuit or defective potentiometer	Read measurable parameters with the diagnosis instrument to verify the potentiometer does not work properly (signal doesn't change between 0% and 100%). Use a multimeter to check the integrity of the potentiom- eter (R.total = approx. 1 k\Omega). Check the linear change in resistance of the potentiometer between the minimum and maximum. If the potentiometer is integral, check the wiring between the potentiometer connector (wiring side) and EDC connector pin B16, B23 and B35.	
	Power reduction. Fast idling with the throttle lever in any position.	Throttle: implausible signal between the idling switch (safety contact) and the potentiometer or throt- tle potentiometer discon- nected	Read parameters with the diagnosis instrument to identify the defective part of the throttle (potentiometer or idling switch). a) Using a multimeter on the component, check the integrity of the idling switch (switching ON-OFF). If the switch is integral, search for a break in the wiring between the throttle connector (wiring side) and the EDC connector pin B17 and B2. b) Use a multimeter directly on the component to check the integrity of the potentiometer. If the potentiometer is integral, check the wiring between the potentiometer and the EDC connector.	

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GUIDE TO BLIF	GUIDE TO BLINK CODE DIAGNOSIS			
Blink EDC Code light	System reactions	Possible cause	Recommended tests or action	Notes
2.1 Off Engine coolant tem- perature sensor anomaly	Starting may be difficult with sub-zero tempera- tures, greater combustion noise even with the engine warm.	Water temperature sen- sor shorted or shorted to ground or shorted to positive or open circuit or defective sensor.	Read measurable parameters: with this error, the water tem- perature read in the control unit will be fixed at 0 °C. Using a multimeter, check the integrity of the sensor (R = approx. 2.5 kOhm at 20 °C) between its pins 1 and 2. If the sensor is integral, check the wiring between the sensor con- nector and EDC connector pin A5 - A22.	
2.2 Off Combustion air temperature sensor anomaly	No perceivable reaction	Air temperature sensor on intake manifold shorted or shorted to ground or shorted to positive or open circuit or defective sensor.	Read measurable parameters with the diagnosis instrument: with this error, the turbocharging air temperature will be fixed at 20 °C. Check the integrity of the sensor (R = approx. 2.5 kOhm at 20 °C) between its pins 1 and 2. If the sensor is integral, check the wiring between the sensor connector and EDC connector pin A17 - A21.	
2.3 Off Fuel temperature sensor anomaly	No perceivable reaction	Fuel temperature sen- sor shorted or shorted to ground or shorted to positive or open circuit or defective sensor.	Read measurable parameters: with this error, the fuel temperature will be fixed at 30 °C. Check the integrity of the sensor (R = approx. 2.5 kOhm at 20 °C). If the sensor is integral, check the wiring between the sensor connector and EDC connector pin A6 - A11.	
2.4 On Combustion air pressure sensor anomaly	Power reduction	Intake air pressure sen- sor shorted or shorted to ground or shorted to positive or open circuit or defective sensor.	Read measurable parameters with the diagnosis instrument: with this error, the turbocharging pressure will be fixed at 1600 mbar. Using a multimeter on the component, check the supply voltage (U = $5Y \pm 10\%$) and the output voltage U about 1V at idling. Check the wiring between the sensor connector (wiring side) and EDC connector pin A12 – A17 – A23.	If the electrics are in order, verify the turbo- compressor (and waste- gate valve if present) works properly.

4.79

EDC				
	System reactions	Possible cause	Recommended tests or action	Notes
Off ospheric air sure sensor anomaly iside unit)	No perceivable reaction	Ambient pressure sensor shorted or open circuit or defective sensor	Read measurable parameters with the diagnosis instrument: with this error, the ambient air pressure will be fixed at 970 mbar. The sensor is integrated in the EDC control unit and cannot be replaced separately.	Any paintwork on the engine/control unit without the due pre- cautions may jeopardize correct ambient pres- sure measurement.
3.5 Off Fa Battery voltage anomaly	Fast idling	Battery voltage too low	Read measurable parameters to check the supply voltage. Make the appropriate checks on the voltage regulator, bat- teries and charging system. If the difference between battery voltage and ECU supply voltage is high check supply wiring and components.	The voltage might not actually be too low, but recognized by the con- trol unit as low.
5.1 On The Injector failure cylinder 1	The engine runs on 5 cyl- inders	Cylinder 1 injector electrics shorted or circuit open	Check correct tightness to torque of the connectors on the injector solenoid valve (from 1.36 to 1.92 Nm). Check the integrity of the injector coil (R = 0.6 $\Omega \pm 10\%$) and replace the injector if defective. If the coil is integral, check the wiring between the solenoid valve and EDC connector pin A24 and A35	Immediately afterwards the engine might keep on turning on 3 cyl- inders as the injectors are controlled by two power stages.
5.2 On The failure cylinder 2	The engine runs on 5 cyl- inders	Cylinder 2 injector electrics shorted or circuit open	Check correct tightness to torque of the connectors on the injector solenoid valve (from 1.36 to 1.92 Nm). Check the integrity of the injector coil (R = 0.6 $\Omega \pm 10\%$) and replace the injector if defective. If the coil is integral, check the wiring between the solenoid valve and EDC connector pin A24 and A34	Immediately afterwards the engine might keep on turning on 3 cyl- inders as the injectors are controlled by two power stages.

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GUIDE T	O BLIF	GUIDE TO BLINK CODE DIAGNOSIS			
Blink Code	E D C light	System reactions	Possible cause	Recommended tests or action	Notes
5.3 Injector failure cylinder 3	o O O	The engine runs on 5 cyl- inders	Cylinder 3 injector electrics shorted or circuit open	Check correct tightness to torque of the connectors on the injector solenoid valve (from 1.36 to 1.92 Nm). Check the integrity of the injector coil (R = 0.6 $\Omega \pm 10\%$) and replace the injector if defective. If the coil is integral, check the wiring between the solenoid valve and EDC connector pin A24 and A33.	Immediately afterwards the engine might keep on turning on 3 cyl- inders as the injectors are controlled by two power stages.
5.4 Injector failure cylinder 4	O 4 4	The engine runs on 5 cyl- inders	Cylinder 4 injector electrics shorted or circuit open	Check correct tightness to torque of the connectors on the injector solenoid valve (from 1.36 to 1.92 Nm). Check the integrity of the injector coil (R = 0.6 $\Omega \pm 10\%$) and replace the injector if defective. If the coil is integral, check the wiring between the solenoid valve and EDC connector pin A25 and A26.	Immediately afterwards the engine might keep on turning on 3 cyl- inders as the injectors are controlled by two power stages.
5.5 Injector failure cylinder 5	on 5	The engine runs on 5 cyl- inders	Cylinder 5 injector electrics shorted or circuit open	Check correct tightness to torque of the connectors on the injector solenoid valve (from 1.36 to 1.92 Nm). Check the integrity of the injector coil (R = 0.6 $\Omega \pm 10\%$) and replace the injector if defective. If the coil is integral, check the wiring between the solenoid valve and EDC connector pin A25 and A28.	Immediately afterwards the engine might keep on turning on 3 cyl- inders as the injectors are controlled by two power stages.
5.6 Injector failure cylinder 6	O 9	The engine runs on 5 cyl- inders	Cylinder 6 injector electrics shorted or circuit open	Check correct tightness to torque of the connectors on the injector solenoid valve (from 1.36 to 1.92 Nm). Check the integrity of the injector coil (R = 0.6 $\Omega \pm 10\%$) and replace the injector if defective. If the coil is integral, check the wiring between the solenoid valve and EDC connector pin A25 and A27.	Immediately afterwards the engine might keep on turning on 3 cyl- inders as the injectors are controlled by two power stages.

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	System reactions	Possible cause	Recommended tests or action	Notes
6.1 On Flywheel sensor anomaly	Starting the engine takes longer than normal. Power reduction and noise increased.	Flywheel sensor: no signal or implausible signal	Check the sensor is clean and secured correctly. Check the integrity of the sensor (R = 900 $\Omega \pm 10\%$) and replace it if defective If the sensor is integral, check the wiring between the sensor and EDC connector pin A1 and A13.	The defect is not detected with the engine stationary.
6.2 On Distribution sensor anomaly	Starting the engine takes longer than normal. Power reduction.	Camshaft sensor: no signal or implausible signal	Check the sensor is clean and secured correctly. Check the integrity of the sensor (R = 900 $\Omega \pm 10\%$) and replace it if defective. If the sensor is integral, check the wining between the sensor and EDC connector pin A2 and A14.	The defect is not detect- ed with the engine sta- tionary.
6.1 with 6.2 Implausible flywheel and distribution signals	The engine doesn't run.	Flywheel and camshaft sig- nals electrically corrected but implausible in timing	Check the timing of phonic wheel of the camshaf.	The defect is not detected with the engine stationary. If the engine fails to start (or switches off if it was running), the phonic wheel of the cam- shaft might be out of step: disconnect the sensor con- nector to permit starting the engine (in an emergency)
6.4 Blinking Overspeed engine anomaly	No reaction perceivable, other than the light blinking.	Observed engine over- speed.	Delete the fault memory.	
9.1 Blinking Defective unit	The engine stops or fails to start. No diagnosis possible.	Electronic control unit fault.	Call IVECO MOTORS-FPT and follow their instructions to replace the control unit, if necessary.	Probably no diagnosis possible
9.2 On Incorrect data in EEPROM	Power reduction. Data is not saved on switching off the engine. The fault mem- ory is lost, it is possible to read solely the current faults and not the inter- mittent ones that occurred previously.	EEPROM fault.	Call IVECO MOTORS-FPT and follow their instructions to replace the control unit, if necessary.	Probably no diagnosis possible

Blink EDC System reactions Possible cc Code light The control unit is not sup- plied and the engine stops or fails to start. Main relay 9.4 On The control unit is always supplied and the indicator Main relay 9.4 On The control unit is always Main relay 9.4 On The control unit is always Main relay 9.4 On Power reduction Afterrun 9.5 On Power reduction Afterrun 9.6 On Power reduction Afterrun 9.6 On Power reduction Afterrun 9.6 Data save In the coction Afterrun 0.6 Power reduction Afterrun Afterrun	GUIDE TO BLINK CODE DIAGNOSIS		
On The control unit is not supplied and the engine stops or fails to start. Main relay On The control unit is always supplied and the indicator light stays on even with the key OFF, the batteries run down Mong engine shut-down Power reduction Data save Power reduction Data save Noncentrol unit is always	Possible cause	Recommended tests or action	Notes
On The control unit is always supplied and the indicator supplied and the indicator light stays on even with the key OFF, the batteries run down Mrong engine Nower reduction Mrong engine Power reduction Data save Nover reduction not complete not complete	Main relay broken	Check main relay, fuse and supply wirring.	
On Power reduction After-run often After-run often shut-down procedure On Power reduction Failure of procedure in the co time the e not complete	Main relay short-circuited on 30-87 leads	Try taking the EDC fuse out and putting it back in and delet- ing the fault memory. Check main relay, fuse and supply wiring.	Engine switches off normally with the key turned OFF.
On Power reduction Failure of procedure in the contral unit in the contral unit in the contral complete	After-run broken off too often	Check the Main Relay, wiring and connections for an uncer- tain contact.	The trouble is resolved on its own when switch- ing off correctly the next time with the key, unless there is a wiring problem or a defective relay.
	Failure of the internal test procedure that takes place in the control unit each time the engine stops.	Delete the fault memory and try again: if the error remains, call NECO MOTORS-FPT and follow their instructions to replace the control unit, if necessary.	The engine fails to stop in the preset time when the key is turned OFF.

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GUIDE -	GUIDE TO SYMPTOM DIAGNOSIS	SISC		
Blink Code	Symptom	Part	Possible cause	Recommended tests or action
0 Z	Engine does not start	Batteries	 Low charge Faulty terminal connections 	 Recharge (disconnecting system wiring) Clean, check, tighten terminals or replace them
OZ	Engine does not start	Electrical starter motor	- Malfunction - Faulty terminal connections	- Check - Clean, check, tighten terminals
0 Z	Engine does not start	Main relay	- Malfunction - Fuse	 Check supply wiring Check main relay, replace Check fuse, replace
OZ	Engine does not start	Fuel feed pump	- Priming incorrect (air leaking inside)	 Check seal on intake branch Check pressure
0 Z	Engine does not start	Fuel circuit	- Incorrect filling (air in fuel circuit)	- Check seal - Bleed circuit
OZ	Engine does not start	Fuel filter and pre-filter	- Filter and pre-filter clogged	- Check reservoir - Replace
9 Z	Engine does not start	Electrical grid heater (if present), at temperatures lower than 0 °C.	- Malfunction - Faulty terminal connections	 Check supply and earth connection Carry out active diagnosis

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GUIDE	GUIDE TO SYMPTOM DIAGNOSIS	SISC		
Blink Code	Symptom	Part	Possible cause	Recommended tests or action
0 Z	Engine overheats	Coolant level	- Below MIN level	- Check for leaks - Top up correct level
0 Z	Engine overheats	Coolant pump drive belt	- Loose tension - Wear	 Check tension Replace Verify liquid spillage on the belt
0 Z	Engine overheats	Coolant pump	- Malfunction	- Check belt tension - Replace
0 Z	Engine overheats	Thermostatic valve	- Locked, closed or only partially open	- Check coolant liquid - Replace
0 Z	Engine overheats	Coolant-sea water heat exchanger	- Clogged	- Clean or replace
O Z	Engine overheats	Air filter	- Clogged	 Check filter clogged indicator Replace filter
OZ	Engine overheats	Cylinder head gasket	- Compression leaking from cylinder head gasket	 Check water circuit pressure Replace head gasket

GUIDE	GUIDE TO SYMPTOM DIAGNOSIS			
Blink Code	Symptom	Part	Possible cause	Recommended tests or action
0 Z	Poor performance	Fuel circuit	 Reservoir net filter clogged Fuel prefilter clogged Fuel filter clogged Air in fuel circuit Fuel pressure too low Heavy fuel leakage 	 Replace clogged filters Check intake seals Check pressure relief valve on the fuel gear pump Check the integrity of the fuel gear pump
OZ	Poor performance	Injectors	- Malfunction - Fuel leaking from seal rings	 Check for fuel presence in engine Call IVECO MOTORS-FPT and follow their instructions to replace the injectors
0 Z	Poor performance	Air filter	- Clogged	 Check filter clogged indicator Replace filter
0 Z	Poor performance	Gas exhaust system	- Leaks from exhaust manifold	- Check and remove cause of leak
0 Z	Poor performance	Turbocompressor	 Blades inefficient Bearings inefficient 	- Check parts and lubrication circuit - Replace
0 Z	Poor performance	Control cams	- Wear - Incorrect timing	- Check, replace - Check, restore
O Z	Poor performance	Valves	- Excessive or no clearance	- Check, restore correct clearance
0 Z	Poor performance	Intake air pressure sensor	- Output signal too low (below to the pressure value)	 Using a multimeter on the component, check the output voltage and refer to a manometer
0 Z	Poor performance	 Intake air temperature sensor Water temperature sensor Fuel temperature sensor 	- Output signal too high	- Using a multimeter on the component, check the resistance and refer to a thermometer

Blink Code	Symptom	Part	Possible cause	
Oz	The engine emits grey- white smoke	Water in cylinders	 Leakages from cylinder gasket Leakages from injector sleeves Water in intake system Water in fuel 	 Check level and pressurization of water circuit Check fuel tank, clean as required Check water in fuel sensor
O Z	The engine emits blue smoke	Oil in cylinders	 Excessive oil consumption Oil leaking in turbocompressor Oil leaking from valve guides 	- Check lubrication oil consumption - Overhaul
Q	Engine stops	Fuel reservoir	- Fuel reservoir empty	- Refill and bleed fuel circuit
OZ	Engine stops	Net filter Prefilter Fuel filter	- Filter clogged	- Clean, replace
O Z	Engine stops	Fuel circuit	- See item "Poor performance"	- See item "Poor performance"
O N	Engine stops	Main relay	- Malfunction	- Check main relay, fuse and supply wiring

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SECTION 5

MAINTENANCE

	Page
PERIODICITY OF CHECKS AND MAINTENANCE OPERATIONS	91
PREPARING THE ENGINE FOR LONG IDLE PERIODS	93
ENGINE'S FIRST START/RESTORING NORMAL OPERATING CONDITIONS	93

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PERIODICITY OF CHECKS AND MAINTENANCE OPERATIONS

Execution of the operations indicated below requires competence and compliance with the safety regulations enforced in various Countries.

Checks can be performed by the user of the vessel and/or by workshop personnel.

Periodic maintenance operations must be performed by qualified personnel and require the use of tools, work instruments, and suitable protection means.

Extraordinary maintenance operations must be performed by IVECO MOTORS-FPT authorized workshop personnel with adequate training and sufficient technical information.

Checks

Periodicity

		Every start	150 hours	300 hours	600 hours	900 hours	1200 hours	Annual (2)
Check engine lubricating oil level								
Check engine coolant level								
Check oil level in the gearbox								
Inspect exhaust duct(s)								
Drain water from fuel pre-filter(s)	(1)							
Check battery terminal tightening and cleanliness								
Check electrolyte level in batteries	(1)							
Check condition of oil vapor filter with clogging indication (with the engine running)	tor							

Periodic maintenance operations		Periodicity						
		Every start	150 hours	300 hours	600 hours	900 hours	1200 hours	Annual (2)
Clean air filter(s)	(1)							
Check belt tension and conditions								
Check zinc anode corrosion condition	(4)							
Restore battery electrolyte level								
Drain/draw water and condensations from tank(s)	(1)							
Replace engine lubricating oil								
Replace oil vapor filter	(8)							
Replace fuel pre-filter(s)	(1) (3)				Max			
Replace fuel filter(s)	(1) (3)				Max			
Replace oil filter(s)								
Replace gearbox(es) oil (see data provided by the m	nanufacturer)							
Check seal of one-way valve in pre-lubrication system (as required)								-
Clean turbocompressor								
Inspect sea water intake	(1)							
Check wear of sea water pump impeller								
Adjust valve-rocker arm clearance								

Extraordinary maintenance operations (5) Periodicity 600 150 300 900 1200 Every Every 3 hours hours hours hours hours years (7) start Clean heat exchangers (6) Check pre-post heating system operating condition (as required) Replace water pump and alternator drive belt Inspect damper in drive shaft front pulley

- (1) The periodicity of these operations may vary depending on engine use and environmental conditions of operation.
- (2) These operations must be conducted annually even if the specified number of operating hours is not reached.
- (3) Maximum time interval for high quality fuel; This may be reduced depending on contamination. The filter is provided with a clogging sensor; if a clogging indication occurs, replace the filter. The pre-filter is provided with a water presence detector; if the presence of water is detected, drain the water from the appropriate drain and if the light stays lighted, replace the filter.
- (4) If zinc corrosion exceeds 50% of its volume, replace it.
- (5) Instructions provided in Section 6.
- (6) Combustion air/sea water exchanger: clean air side and water side. Engine coolant/sea water exchanger: clean the sea water side. Gearbox oil/sea water exchanger (if provided): clean sea water side.
- (7) These operations must be performed every three years even if the specified operating hours are not reached.
- (8) On every engine oil replacement.

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PREPARING THE ENGINE FOR LONG IDLE PERIODS

To prevent oxidation of the internal parts of the engine and of some components of the injection system, if idle periods exceeding two months are expected, the engine needs to be prepared, **with six-months periodicity**, proceeding as follows:

- 1. Drain the lubricating oil from the sump, after heating the engine;
- Pour 30/M protective oil (alternatively, oil conforming with MIL 2160B Type 2 specifications) into the engine to the "minimum" level marked on the dipstick. Start the engine and let it run for about 5 minutes;
- 3. Drain the fuel from the injection line, from the filter and from the ducts in the cylinder heads. To do so, loosen the drain cap in the front part of the cylinder head and the fuel inlet junction with the cylinder head, taking care to prevent the fuel from coming in contact with the auxiliaries belt;
- 4. Connect the fuel line to a tank containing CFB protective liquid (ISO 4113) and assist the inflow of the liquid by pressurizing the line and turning the engine over for about 2 minutes, after excluding the operation of the injection system. The required operation may be carried out by directly polarizing the terminal 50 of the electric starter motor with positive voltage 24 V, using a conductor prepared for the occasion;
- 5. Nebulize 30/M protective oil at the rate of about 130 g (10 g per liter of displacement) into the turbocompressor intake, while the engine is turning over as described above;
- 6. Close with suitable stoppers or seal with adhesive tape all engine intake, exhaust, aeration and venting ports;
- Drain the residual 30/M protective oil from the sump; it may be re-used for 2 more engine preparation operations;
- 8. Apply tags with the inscription "ENGINE WITHOUT OIL" on the engine and onboard panel;
- 9. Drain the coolant, if it has not been mixed with antifreeze and corrosion inhibiting agents, affixing tags to indicate that the operation has been carried out.

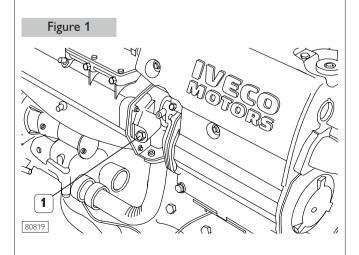
If external parts of the engine are to be protected, spray protective liquid OVER 19 AR onto unpainted metal parts, such as flywheel, pulleys and others; avoid spraying belts, connector cables and electrical equipment.

ENGINE'S FIRST START/RESTORING NORMAL OPERATING CONDITIONS

- 1. Drain the residual protective oil type 30/M from the sump;
- 2. Pour lubricating oil into the engine, as provided by the specifications and in the quantities set out in the Table of Refills;
- 3. Drain the CFB protective liquid from the fuel line, completing the operations set out in item 3. of "PREPARING THE ENGINE FOR LONG IDLE PERIODS";
- 4. Remove the caps and/or the seals from the engine's intake, exhaust, aeration and vent ports, restoring normal operating conditions. Connect the turbocompressor intake to the air filter;
- 5. Attach the fuel lines to the vessel's fuel tank, completing the operations set out in item 4. of "PREPARING THE ENGINE FOR LONG IDLE PERIODS". During the filling operations, attach the fuel tank return pipe to a collecting container to prevent residues of CFB protective liquid from flowing into the vessel's fuel tank;
- 6. Verifiy the quantity of cooling liquid and refill as provided by the specifications;
- 7. In order to enable the sea water pump priming it is necessary to input water into the forcing circuit. Remove the sacrifical anode (1 of Figure 1), introduce 1.5 litres of water into the hole; reassemble the anode and tighten it as required. WARNING

If the engine is activated after a long time, it is necessary to repeat the operations mentioned in item 7.

- 8. Start the engine and keep it running until idling speed has completely stabilized;
- 9. Shut the engine down and delete the "errors" which may have been stored in the injection system ECU during the operation stabilization phases. For reset operation, see "Blink code" paragraph in Section 4;
- 10. Remove the tags with the inscription "ENGINE WITH-OUT OIL" from the engine and from the panel.



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SECTION 6

SERVICING OPERATIONS ON INSTALLED ENGINE

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FOREWORD

Many of the procedures for carrying out the instructions that follow depend on the contion of the housing on the vessel and on the configuration of the installation components.

Prescriptions and cautions for use, handling and technical assistance are provided in Section 11.

Technicians and maintenance personnel are reminded of the need to comply with **safety rules**.

The checks necessary at the completion of an installation or re-embarkation are described in the "C13 ENS M33 - C13 ENT M50 Installation Directive" document.

Spare parts will be supplied only if the following data are provided:

- Engine technical code and serial number;
- Part number as per spare parts catalog.

The information provided below refers to engine characteristics that were current as of the publishing data.

The manufacturer reserves the right to make changes at any time and without advance notice, to comply with technical or commercial requirements or to adapt to legal requirements in different Countries.

The manufacturer shall not be liable for any errors and omissions.

The IVECO MOTORS-FPT Technical Assistance Network is always at the Customer's side with its competence and professionalism.

The successful outcome of repair work is assured by the operator's experience and ability and by compliance with the following instructions.

Before performing work involving components of the injection system, take note of the content of the ECU fault memory with the appropriate IVECO MOTORS-FPT diagnosis equipment, writing the results down or printing them.

- □ Replacement of the ECU MS6.2 must be authorized by IVECO MOTORS-FPT after specific agreements with the Technical Assistance Service;
- □ The electro-injectors cannot be overhauled; their replacement must be authorized by IVECO MOTORS-FPT with the specific agreement of the Technical Assistance Service; for disassembly, follow the indications provided in the specific paragraph of this Section;
- □ Keep parts and components clean, making sure that during handling and assembly (starting with the simple replacement of filter and pre-filter) no sludge or foreign matter is allowed to enter the lines, with particular attention to the fuel supply line in the segment downstream of the filter;
- Maintain the proper polarization of all electrical connections;
- □ Tighten the threaded connections to the prescribed torque;
- □ Ensure that the flywheel and camshaft sensors are positioned so they abut, ensuring they are as close to perpendicular as possible with the bearing surface.

CAUTION

- □ Do not disconnect electrical connections without removing power from the circuits first;
- Do not proceed with operating simulations with unsuitable tools and instruments;
- Do not force measuring probes or mechanical tools into the electrical connections;
- Do not proceed with arc welding without first disconnecting electronic system units.

To proceed with the overhaul of the engine or its parts, you must disconnect the electrical connections of the injection system's components and of the sensors providing indications on the control panel.

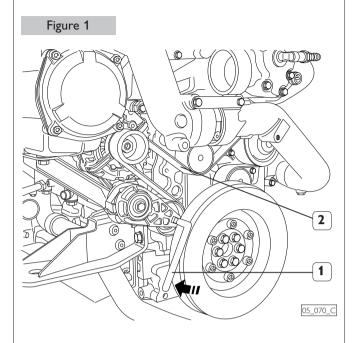
To proceed as indicated, we provide below the procedure to avoid the risk that the ECU of the injection system may detect and store errors or system faults.

- □ Set the key switch to the STOP position;
- □ Wait 10 sec. and disconnect the battery terminals;
- Disconnect the connections according to the prescriptions set out in Section 3;
- Remove, if necessary, the entire wiring harness from the retaining bracket;
- Remove, if necessary, the complete electronic unit after disconnecting the multipolar connectors.

C13 ENS M33

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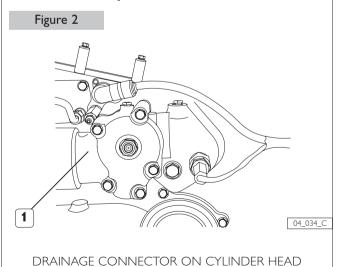
REPLACING BELT



❑ With the tool (1) loosen the tensioning device acting in the direction indicated by the arrow. Extract the auxiliary organ drive belt (2), insert the new belt verifying that it is correctly set onto the pulleys. Release the tensioning device. The automatic tensioning device requires no further adjustment.

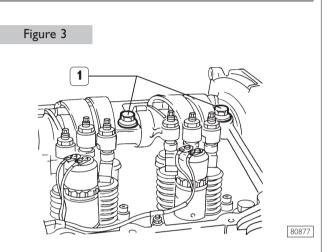
REPLACING EUI PUMPING UNITS

EUI Disassembly

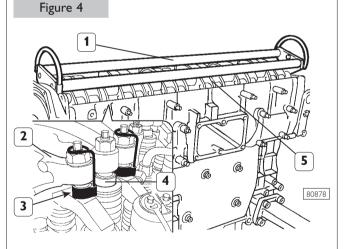


CAUTION

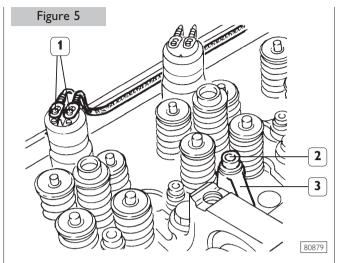
Before extracting the EUI you must empty the fuel inflow and recirculation channels machined in the cylinder head, to prevent the liquid from dripping into the underlying combustion chamber machined in the piston crown. To do so, loosen the drainage cap (1 in Figure 2) located in the front part of the cylinder head and the cylinder head fuel inlet connector. Avoid spilling fuel into the environment and coming into contact with the auxiliary organ belt.



□ After removing the timing lid, unscrew the rocker arm shaft fastening screws (1).

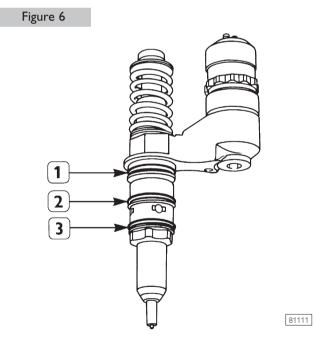


- □ With the tool 99360144 (3) secure the blocks (4) to the rocker arms (2);
- Apply the tool 99360553 (1) to the rocker arm shaft (5) and remove the shaft (5) from the cylinder head.

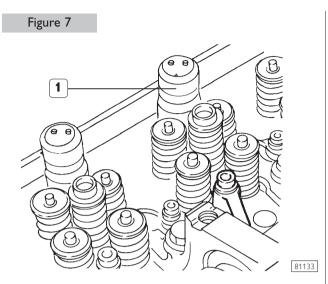


- Unscrew the screws and remove the electrical connections (1) from the units to be removed;
- Unscrew the screws (2) fastening the injector brackets (3).
- Extract the injectors.

EUI Assembly



Mount the seal rings (1) (2) (3) on the injectors. Grease the rings with Vaseline to ease a correct positioning in their seats.



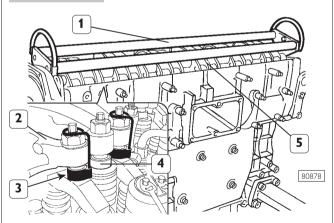
- Carefully position the injectors (1) into the seats and use a torque wrench to tighten the bracket screws at the torque of 26 Nm;
- Mount the braces on the valve stems all oriented with the larger hole on the same side.

CAUTION

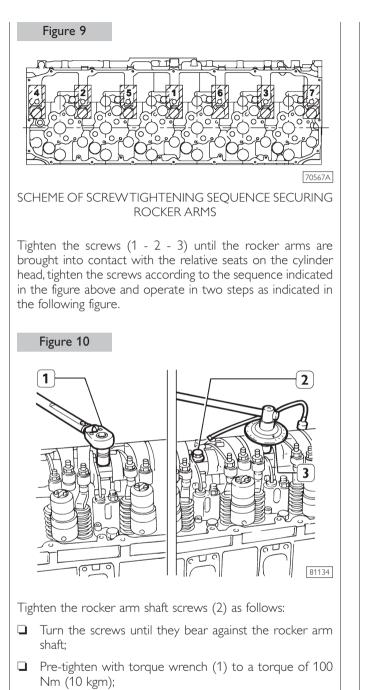
Before reassembling the rocker arm shaft assembly, ensure that all adjustment screws have been completely unscrewed.

Rocker arm shaft assembly

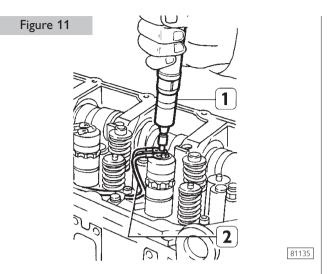
Figure 8



- □ Use the tool 99360144 (3) to fasten the blocks (4) to the rocker arms (2);
- Apply the tool 99360553 (1) to the rocker arm shaft (5) and mount the shaft on the cylinder head.

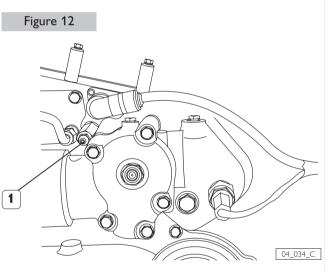


Tighten with tool 99395216 (3), at an angle of 60°.



□ Mount the electrical wiring harness (2), fastening its terminals to the injector solenoid valves, by means of a torque screwdriver (1), at a torque of 1.36 to 1.92 Nm.

VENTING THE AIR FROM THE FUEL FEED LOOP



^{1.} Purge fitting on cylinder head.

To complete venting the air from the fuel feed loop, act on the hand pump of the prefilter or with the aid of a dedicated electrical pump.

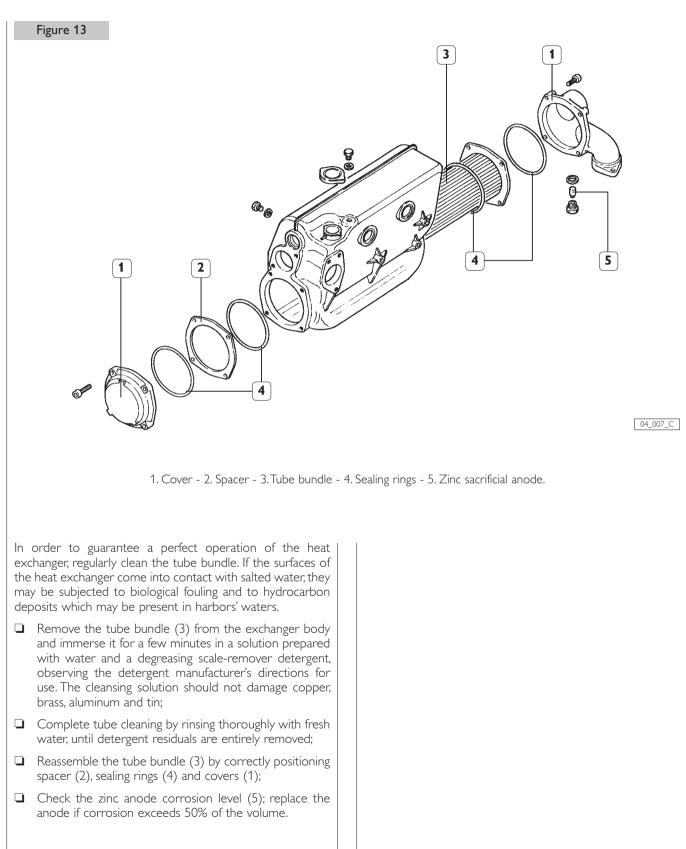
The venting air points are fitted on the pre-filter supplied by IVECO MOTORS-FPT, after the main filter, on the cylinder head near the injectors solenoid valves connector. (see Figure 12). Loosen the vent fitting on the pre-filter and operate the pump until only fuel without air flows out.

Tighten the vent fitting and complete the purge operation on the vent fitting placed on the cylinder head during the initial start-up phases.

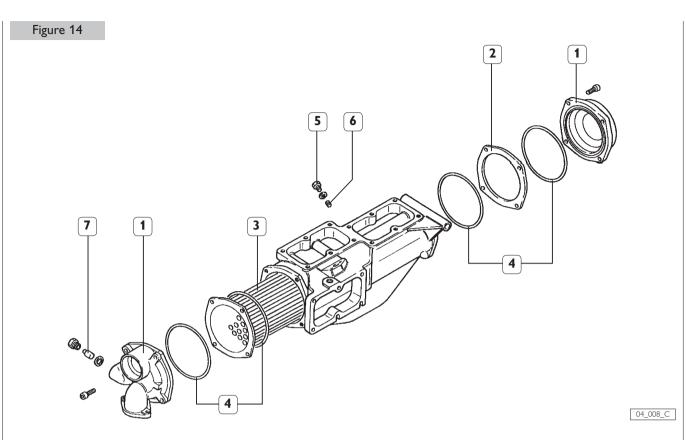
CAUTION

Make sure that the fuel that flows out of the fitting does not come in conctact with the auxiliaries drive belt and is not dispersed in the environment.

CLEANING THE ENGINE COOLANT/SEA WATER HEAT EXCHANGER



CLEANING THE AIR/SEA WATER HEAT EXCHANGER (Not present on the C13 ENS M33 engine)



1. Cover - 2. Spacer - 3. Tube bundle - 4. Sealing rings - 5. Plug - 6. Tube bundle fixing screw - 7. Zinc sacrificial anode.

In order to guarantee a perfect operation of the heat exchanger, regularly clean the tube bundle. If the surfaces of the heat exchanger come into contact with salted water, they may be subjected to biological fouling and to hydrocarbon deposits which may be present in harbors' waters; surfaces coming into contact with combusting air are subject to oil deposits resulting from the fumes exhausted at the base and sucked downstream of the air filter.

- Remove tube bundle fixing plugs (5) and screws (6);
- Remove the tube bundle (3) from the exchanger body and immerse it for a few minutes in a solution prepared with water and a degreasing scale-remover detergent, observing the detergent manufacturer's directions for use. The cleansing solution should not damage copper, brass, aluminum and tin;
- Complete tube cleaning by rinsing thoroughly with fresh water, until detergent residuals are entirely removed;
- Reassemble the tube bundle (3) by correctly positioning spacers (2), sealing rings (4) and covers (1);
- Reassemble screws (6) in order to suitably secure the tube bundle and relevant plugs (5);
- □ Check the zinc anode corrosion level (7); replace the anode if corrosion exceeds 50% of the volume.

ADJUSTMENTS

Adjusting camshaft phase

This consists of ensuring the precise angular position of the camshaft relative to a precise angular position of the drive shaft.

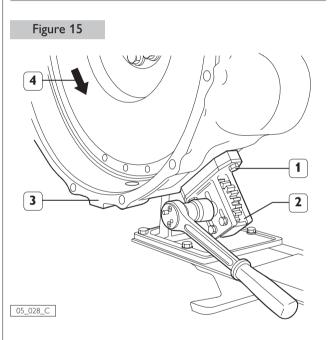
CAUTION

The procedure described below presumes that the initial position of the two shafts is already approximately correct.

Otherwise, during rotation there could be collisions between the valves and the piston crowns.

CAUTION

With engine mounted, the precise drive shaft position references always require checking the timing to identify the phase of operation.

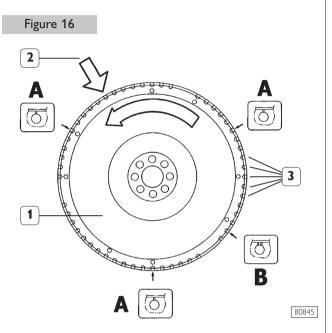


Apply the tool 99360321 (2) and the spacer 99360325 (3) to the gearbox (1). The arrow (4) shows the direction of rotation of the engine when running.

CAUTION

The procedures described require rotating the drive shaft in such a position as to bring pairs of pistons to the top dead center.

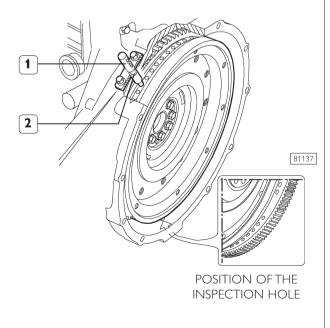
These positions can be identified from the inspection hole below the flywheel case where a hole marked with a notch will be visible (A in Figure 16) and simultaneously from the seat of the flywheel sensor indicated by the arrow where the 11th hole of the sector will be visible (identifiable during the rotation of the flywheel in the normal direction of rotation of the engine starting to count with no. 1 after the segment without holes). The camshaft is correctly in phase when, with the drive shaft in the top dead center position of cylinder piston no.1 at compression end, the elevation figure measured on the roller of the rocker arm controlling the pumping injector cylinder no.1 ranges between 5.26 mm and 5.36 mm.



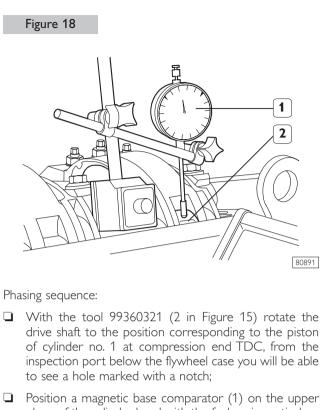
1.Engine flywheel - 2. Flywheel sensor position -3. Radial holes

A. One notch punching for TDC identification - B. Two notch punching to correlate flywheel and cam signal phase.

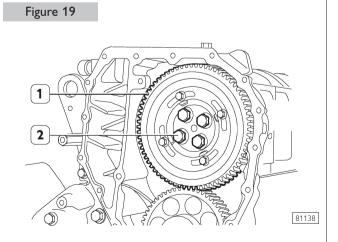
Figure 17



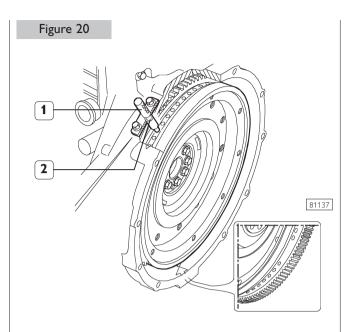
Positioning the tool 99360612 (1) through the seat of the flywheel sensor (2) in the hole on the engine flywheel.



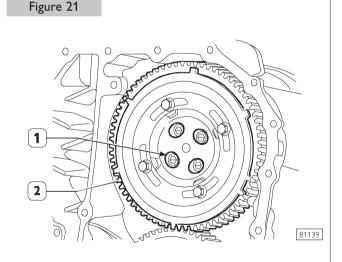
- Position a magnetic base comparator (1) on the upper plane of the cylinder head with the feeler pin vertical on the roller (2) of the pumping injector control rocker arm of cylinder no. 1 and pre-load it by about 6 mm;
- □ Rotate the drive shaft in the opposite direction to normal rotation until the height of the comparator reaches the minimum value (confirmed by a wide arc of rotation during which the value does not change);
- □ Set the comparator to zero;
- □ Rotate the drive shaft in the normal direction of rotation until the comparator shows the value of 5.31 mm.



□ Remove the 4 screws (2) and the gear wheel (1).



- □ Slowly rotate the drive shaft in the normal direction of rotation until the end of the pivot pin 99360612 (1), inserted into the seat of the flywheel sensor (2), enters the underlying 11th hole of the flywheel, locking it;
- □ From the inspection hole verify the presence of a hole on the flywheel marked with a notch, corresponding to the piston of cylinder no. 1 at compression end TDC.



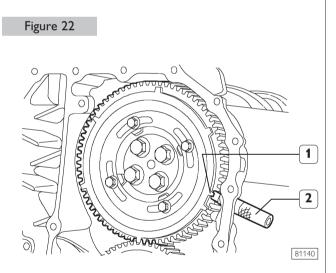
- Mount the gear wheel (2) on the camshaft positioning it with the slot (1) in symmetrical position relative to the holes for the fastening screws;
- □ Tighten to the prescribed value the 4 screws that fasten the gear wheel, checking the stability of the value indicated by the comparator;
- Remove the pivot pin from the sensor seat and proceed with the next phase verification operation.

Checking the timing phase

- □ Rotate the drive shaft in the position corresponding to the piston of cylinder no. 1 at end of compression top dead center;
- Position the comparator as described above, verifying its zeroing by rotating the drive shaft in the direction opposite normal rotation;
- Rotate the drive shaft in the normal direction of rotation until from the inspection hole you can again see the presence of a hole on the flywheel marked with a notch and the end of the pivot pin enters the 11th hole of the flywheel;
- $\hfill \hfill \hfill$
- □ If this is not the case, you must repeat the phasing operations and subsequent check.

Timing shaft phonic wheel keying

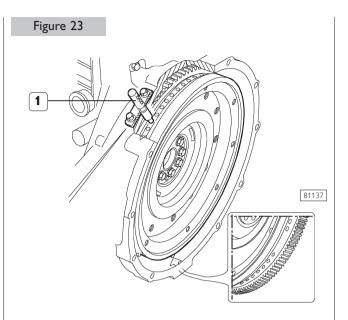
This consists of assuring an appropriate angular position of the phonic wheel relative to the camshaft, thus allowing the associated sensor to provide the ECU with precise phase and drive shaft information.



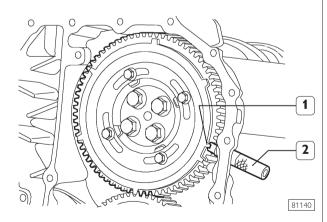
The phonic wheel of the camshaft is correctly in phase when, with the engine flywheel in angular position of 54° before compression end TDC of the piston of cylinder no. 1, the asymmetric tooth of the phonic wheel (1) exactly coincides with the position determined by the tool 99360613 (2).

Alignment sequence:

- Rotate the drive shaft to the position corresponding to the piston of cylinder no. 1 at compression end TDC;
- □ Rotate the drive shaft in the direction opposite normal rotation for about 90°.



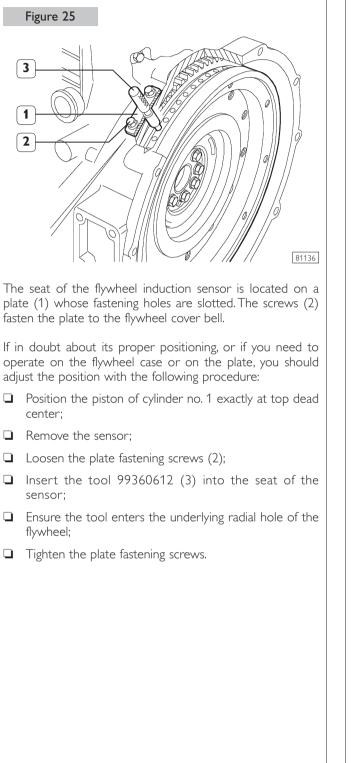
- □ Again rotate the drive shaft in the normal direction of rotation until from the inspection hole below the flywheel case you see the hole marked with two notches and simultaneously from the seat of the flywheel sensor the 2nd hole of the sector is visible (identifiable during the rotation of the flywheel in the normal direction of engine rotation, starting to count with no. 1 after the segment lacking holes);
- □ Insert the tool 99360612 (1) into the seat of the flywheel sensor, with the end in the underlying hole of the flywheel to lock it.
 - Figure 24



□ In this position, the fork tool 99360613 (2), inserted into the seat of the camshaft sensor, must be inserted exactly into the asymmetrical tooth of the phonic wheel (1).

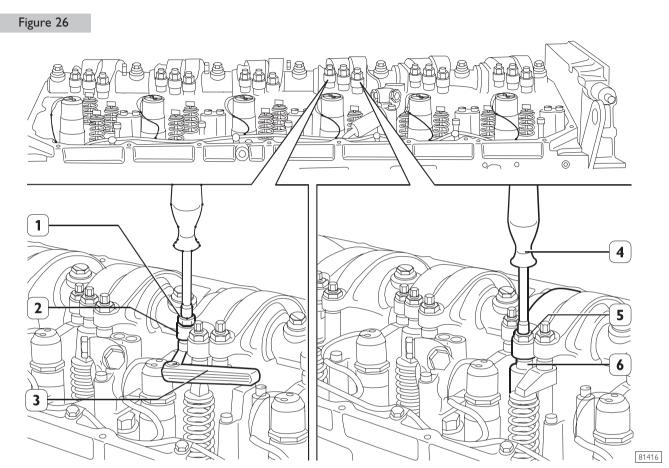
If the tooth is not positioned correctly, remove the 4 screws that fasten the phonic wheel, correct the position and tighten the screws treated with thread damper to the prescribed value.

Flywheel sensor seat position



Adjusting valve clearance and EUI pump position

The operations described herein must be carried out thoroughly and carefully to assure the integrity and regular operation of the engine.



Bring the piston of the cylinder whose clearance is to be adjusted to the compression end TDC; the valves of this cylinder will be closed while both valves of the symmetrical cylinder will be open.

The pairs of symmetrical cylinders are: 1 - 6 2 - 5 3 - 4.

Strictly adhere to directions and data given below and on the table in the following page.

Adjusting valve clearance

The specified clearance value, with the engine cold, is:

0,40 mm (0,35 to 0,45 mm) intake 0,60 mm (0,55 to 0,65 mm) exhaust.

Sequence:

- Bring the drive shaft to the proper position for the valves to be adjusted;
- Loosen the locking nut (1) of the adjustment screw;
- □ Insert the blade of the thickness gauge (3) between the rocker arm plate (2) and the valve control bridge;

- □ Act on the adjustment screw to obtain a sliding with slight friction of the blade of the thickness gauge;
- □ Tighten the locking nut (1) keeping the adjustment screw stationary.

Position of the EUI pump

Sequence:

- Bring the drive shaft to the proper position for the valves to be adjusted;
- Loosen the locking nut of the adjustment screw of EUI
 (6) control rocker arm (5);
- □ With the wrench (4) screw the register bringing the pumper to abut against the stop;
- □ Tighten the adjustment screw with a torque wrench to a torque of 5 Nm;
- Unscrew the adjustment screw by 180 to 270° (1/2 to 3/4 of a turn);
- □ Tighten the locking nut keeping the adjustment screw stationary.

Combustion sequence 1 - 4 - 2 - 6 - 3 - 5

Rotate with normal direction	Balanced valves cylinder number	Check valve clearance cylinder number	Check EUI clearance pumper number
Cylinder 1 at compression end	6	1	5
+ 120°	3	4	1
+ 120°	5	2	4
+ 120°	1	6	2
+ 120°	4	3	6
+ 120°	2	5	3

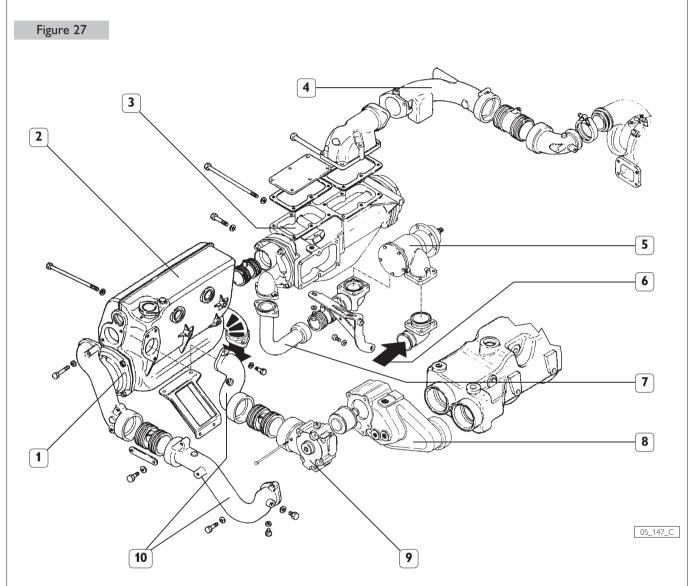
CAUTION

In order to properly carry out the above-mentioned adjustments, follow the sequence specified in the table, checking the exact position in each rotation phase by means of pin 99360612, to be inserted in the 11th hole in each of the three sectors with 18 holes each.

UNCOUPLING MARINE PARTS

The operations described below can all be completed aboard the vessel. If they take place at an overhaul center, secure the engine to an adequate support. Extract the liquids from the engine: fuel, lubricating oil and engine coolant, disposing of them according to the procedures prescribed by current regulations.

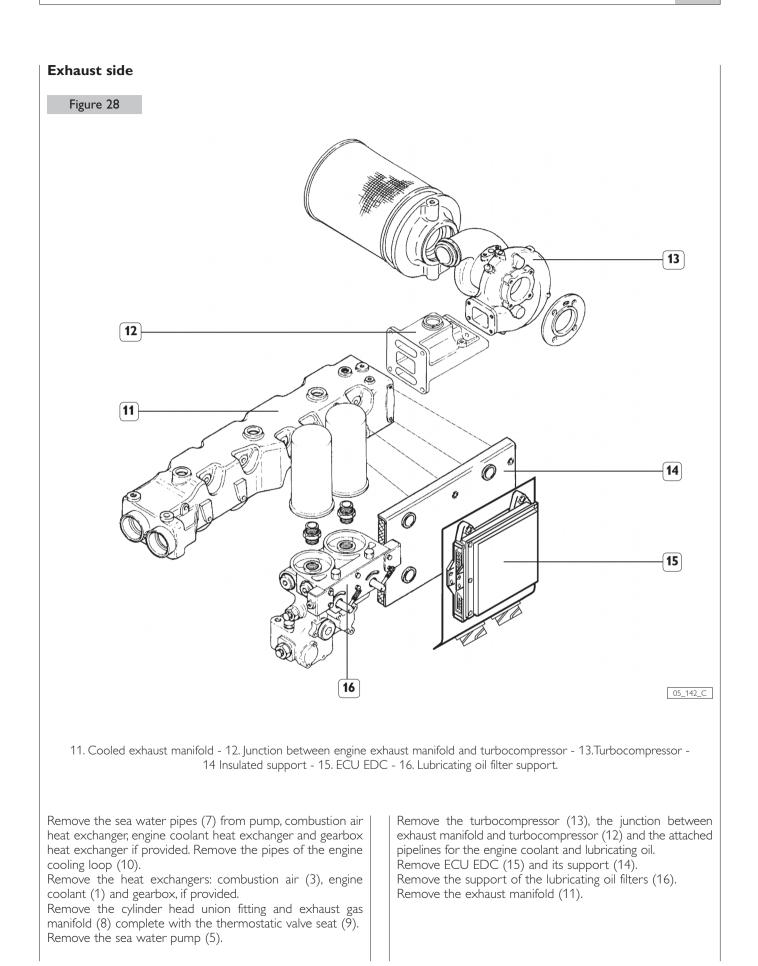
Intake side



Sea water/engine coolant heat exchanger - 2. Coolant tank - 3. Combustion air heat exchanger (not present on the C13 ENS M33 engine) - 4. Junction lines between the turbocompressor and the combustion air heat exchanger - 5. Sea water pump Sea water inlet - 7. Sea water loop lines - 8. Cylinder head - cooled exhaust manifold union fitting - 9. Seat of the engine cooling thermostatic valve - 10. Engine cooling loop lines (fresh water loop).

Disconnect all connectors of electrical components on the engine and remove the complete electronic unit. Remove the electrical pump for pre-lubrication, its bracket, the oil pipelines and the dipstick. Remove the fuel filter support and associated pipelines. Remove the intake air filter and the exhaust gas terminal. Remove junction lines between the turbocompressor and the combustion air heat exchanger (4).

6.111



INSTRUCTIONS FOR DISEMBARKING THE ENGINE

The following is a description of the recommended sequence of operations to be completed before extracting the engine from the vessel.

- ❑ After the key switch has been in the OFF position for at least 10 seconds, disconnect the battery terminals and disconnect the connectors from the relay box;
- Disconnect from the engine the power wiring harness terminals (battery positive and negative);
- Loosen and remove the fuel pipelines and the pipes of the gearbox heat exchanger, if provided;
- □ Loosen and remove the sea water inlet pipes, engine exhaust pipes, and, if separate, the sea water loop discharge;
- Remove the pipeline from the engine coolant expansion vessel;
- Loosen and remove engine anchor bolts;
- □ Uncouple the gearbox;
- □ Hitch the engine following the prescriptions provided below.

Handling

The engine must be handled by experienced personnel, using the prescribed tool or a rocker arm that keeps the lifting lines parallel and with adequate equipment in terms of capacity and size.

The two eyebolts (provided exclusively for lifting the engine) must always be used simultaneously.

SECTION 7

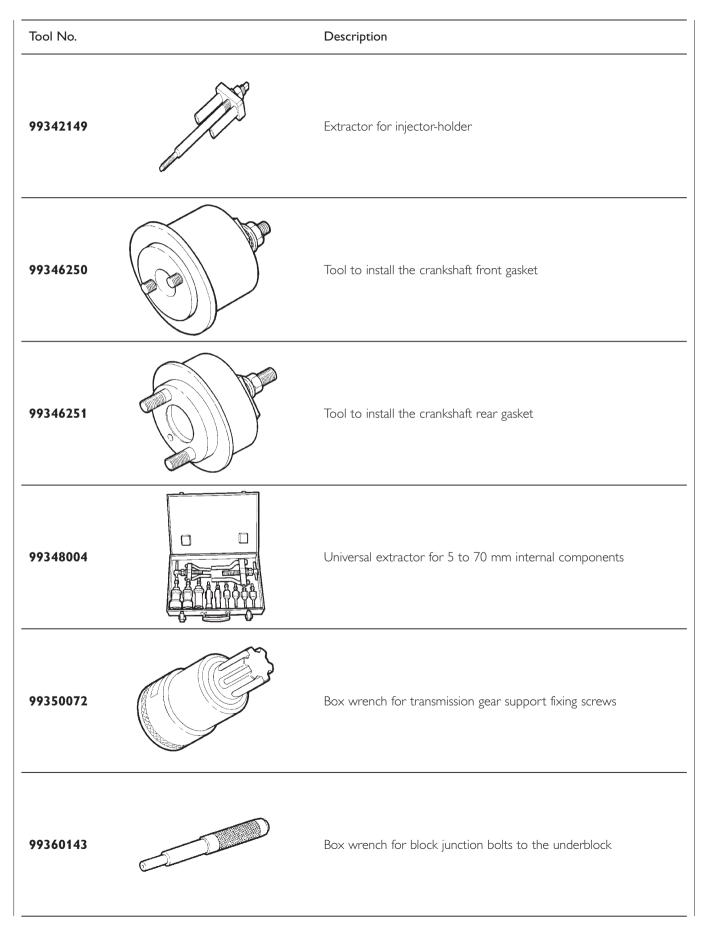
TOOLS	
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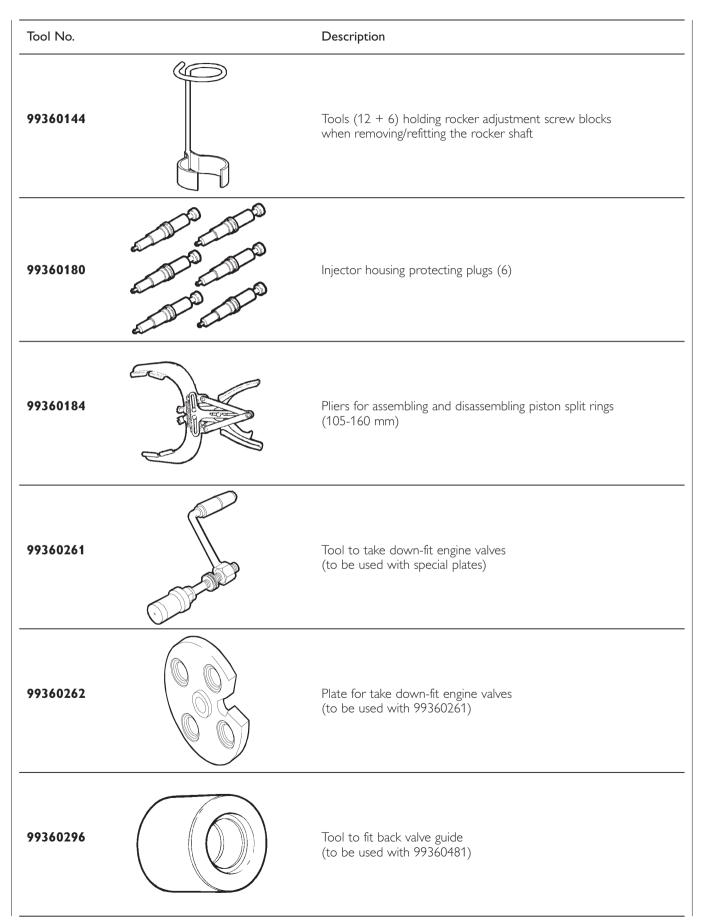
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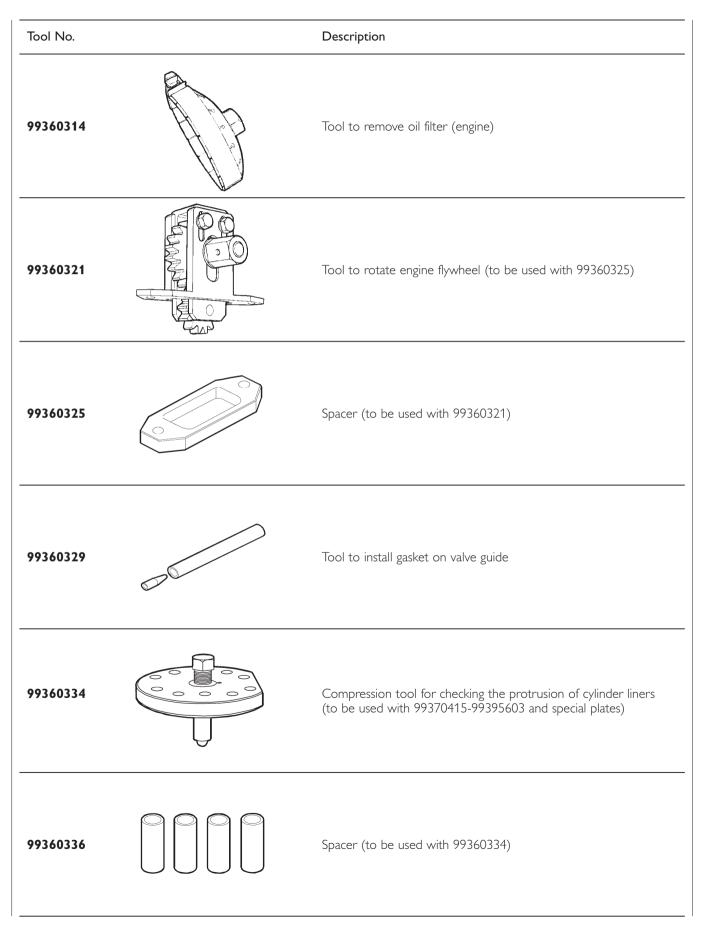
Tool No.	Description
99305019	Full-optional tool-kit to rectify valve seat
99305047	Equipment for spring load check
99322230	Rotary telescopic stand
99340053	Extractor for crankshaft front gasket
99340054	Extractor for crankshaft rear gasket
99340205	Percussion extractor











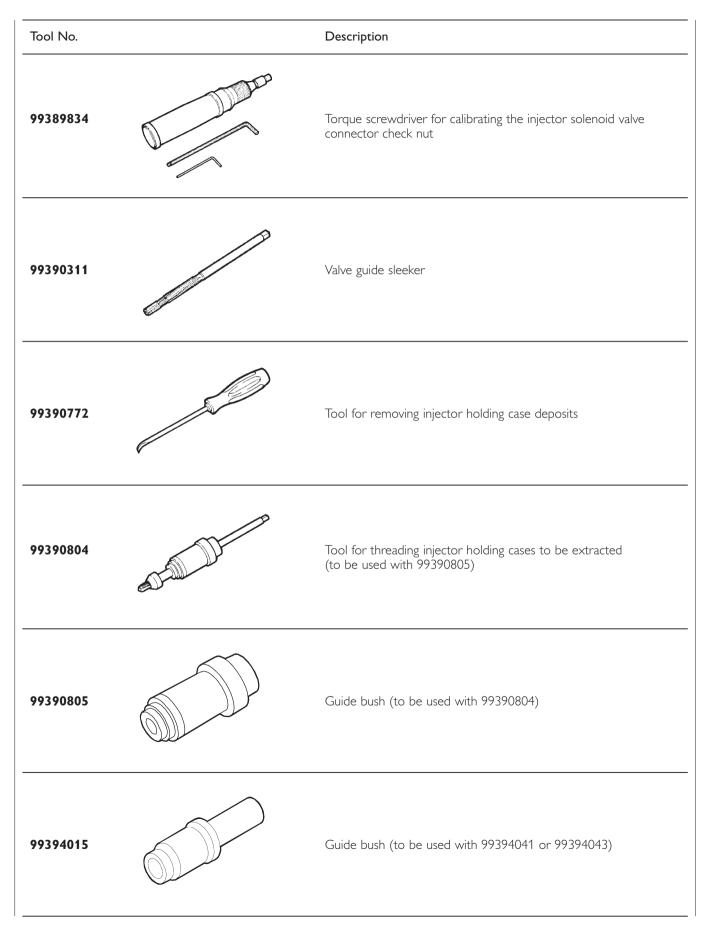
C13 ENS M33 C13 ENT M50 7.119

Tool No.	Description
99360337	Cylinder liner compression plate (to be used with 99360334-99360336)
99360351	Tool to stop engine flywheel
99360499	Tool to take down and fit back camshaft bushes
99360500	Tool to lift crankshaft
99360551	Bracket to take down and fit engine flywheel
99360553	Tool for assembling and installing rocker arm shaft

Tool No.	Description
99360585	Swing hoist for engine disassembly assembly
99360605	Belt to insert piston in cylinder liner (60 - 125 mm)
99360612	Tool for positioning engine P.M.S.
99360613	Tool for timing of phonic wheel on timing gear
99360703	Tool to stop cylinder liners
99360706	Tool to extract cylinder liners (to be used with specific rings)

Tool No.	Description
99360726	Ring (125 mm) (to be used with 99360706)
99361035	Brackets fixing the engine to rotary stand 99322230
99365054	Tool for injector holder heading
99370415	Base supporting the dial gauge for checking cylinder liner protrusion (to be used with 99395603)
99378100	Tool for printing engine identification plates (to be used with special punches)
99378101 (A) to 99378106 (F)	Punches (B) for printing engine identification plates (to be used with 99378100)

7 4 2 2	C13 ENS M33
7.122	C13 ENT M50

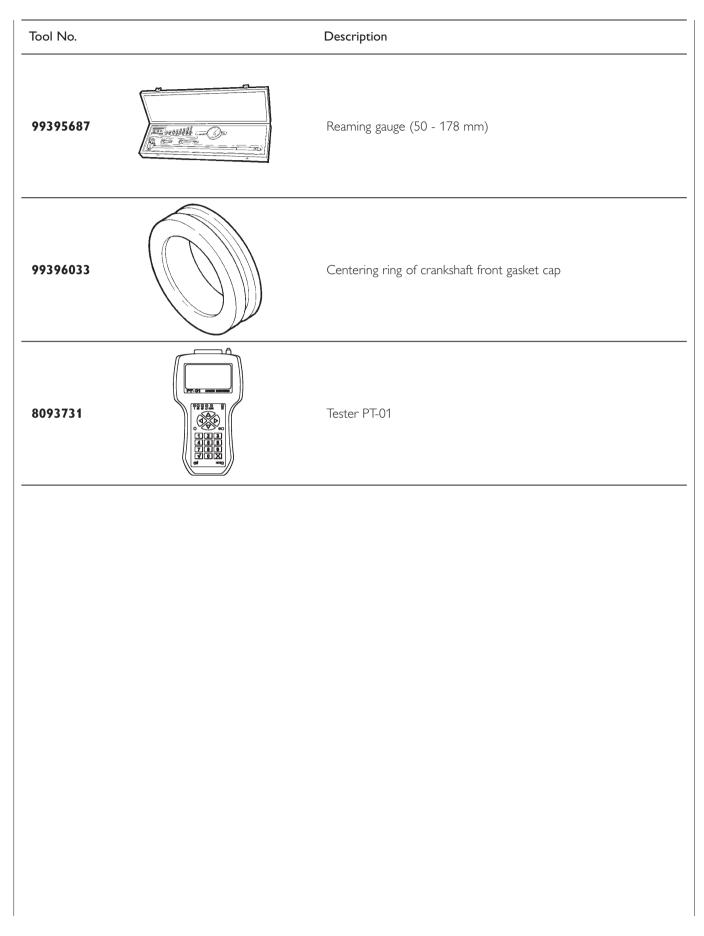


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Tool No.		Description
99394041		Cutter to rectify injector holder housing (to be used with 99394015)
99394043		Reamer to rectify injector holder lower side (to be used with 99394015)
99395216	6	Measuring pair for angular tightening with 1/2'' and 3/4'' square couplings
99395218	0	Gauge for defining the distance between the centres of camshaft and transmission gear
99395363		Complete square to check connecting rod squaring
99395603		Dial gauge (0 - 5 mm)



C13 ENS M33 C13 ENT M50



SECTION 8

OVERHAUL

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Graph and symbols

<u> </u>	Surface for machining Machine finish
Ś	Interference Strained assembly
	Thickness Clearance
	Intake
	Exhaust
$\langle \neg \rangle$	Operation
6	Compression ratio
	Preload
>	Oversized Higher than Maximum, peak
<	Undersized Less than Minimum
Â	Selection Classes Oversizing
IVECO PARTS	Replacement Original spare parts

GENERAL CHARACTERISTICS

	Engine	C13 ENS M33 C13 ENT M50
		mm
Å	Cycle	Diesel 4 strokes
Λ	Air feeding	Turbocharged with aftercooler
	Injection	Direct
	N. of cylinders	6 in-line
	Diameter mm	135
	Stroke mm	150
	Total displacement cm ³	12880
6	Compression ratio	16.5 ± 0.8 : 1
A	Valve timing	
	opens before TDC A	17°
	closes after BDC B	30°
	opens before BDC D	50°
	closes after TDC C	9°
	For timing check	
	(mm	-
	X { mm	-
	Running	
	(mm	0.35 to 0.45
	X { mm	0.55 to 0.65

ASSEMBLY CLEARANCE DATA

	Engine	C13 ENS M33	C13 ENT M50
Cylinder block and crank mech	anism components	mm	
Ø 1	Cylinder sleeve bore		
	wpper Ø 1	153,500 to 15	53,525
	lower	152,000 to 15	52,025
	Cylinder liners: outer diameter:		
	wpper Ø 2	153,461 to 15	53,486
Ø 2	lower length L	151,890 to 15 -	51,915
	Cylinder sleeve - crankcase bore: upper	0,014 to 0,	039
-+ +-	lower	0,085 to 0,	
	Outside diameter Ø 2	-	
Ø 3	Cylinder sleeve	425.000 + 42	NF 042
×	inside diameter Ø 3	135,000 to 13	
	B* Protrusion X	135,011 to 13 0,045 to 0,	
	* Available dia. class		
	Pistons : measuring dimension X outside diameter Ø 1 A* outside diameter Ø 1 B** pin bore Ø 2	20 134,881 to 13 134,892 to 13 54,010 to 54	34,904
Ø 2	* Class A pistons supplied as spares. ** Class B pistons are fitted in production only and are not supplied as spares.		
	Piston - cylinder sleeve * Available dia. class	0,107 to 0, 0,107 to 0,	
PARTS	Piston diameter Ø 1	-	
	Pistons protrusion X	0,12 to 0,	42
Ø 3	Gudgeon pin Ø 3	53,994 to 54	1,000
	Gudgeon pin - pin housing	0.010 to 0.	024

	Engine	C13 ENS M33	C13 ENT M50
		mn	1
	Piston ring grooves X1* X2 X3	3.445 to 3.05 to 5.02 to	3.07
	* Measured on Ø of 112 mm		
$\square \square \blacksquare \begin{pmatrix} S & 1 \\ S & 2 \\ S & 3 \end{pmatrix}$	Piston rings: trapezoidal seal S1* lune seal S2 milled scraper ring with slits and internal spring S3 * Measured on Ø of 112 mm	3.296 to 2,970 ÷ 4.970 to	2,990
	Piston rings - grooves 2 3	0.081 to 0.060 to 0.030 to	0.100
NECO	Piston rings	-	
$\left\{\begin{array}{c} \times 1 \\ \times 2 \\ \times 3 \end{array}\right\}$	Piston ring end gap in cylinder liners: X1 X2 X3	0.40 to 0.65 to 0.40 to	0.80
Ø 1	Small end bush housing \emptyset 1Big end bearing housing \emptyset 2Selection classes \emptyset 2 $\begin{cases} 1\\ 2\\ 3 \end{cases}$	59.000 to Rated value 94.000 to 94.000 to 94.011 to 94.021 to	94.030 94.010 94.020
	Small end bush diameter outside Ø 4 inside Ø 3 Big end bearing shell S Red Green Yellow * * Fitted in production only and not supplied as spares	59.085 to 54.019 to 1.965 to 1.976 to 1.986 to	54.035 1.975 1.985
	Small end bush - housing	0.055 to	0.110
	Piston pin - bush	0.019 to	0.041
	Big end bearing shells	0.127 - 0.25	4 - 0.508
\bigcirc	Connecting rod weight	g	
	Class B C	4661 to 4695 to 4729 to	4728

	Engine	C13 ENS M33 C13 ENT M50
		mm
	Measuring dimension X Max. connecting rod axis misalignment tolerance	125 0.08
	Main journalsØ 1Selection class1CrankpinsØ 2Selection class1Selection class1Main bearing shellsS1RedS1GreenYellow *Big end bearing shellsS2RedGreenYellow **Fitted in production onlyand not supplied as spares	Rated value 99.970 to 100.000 99.970 to 99.979 99.990 to 100.000 99.990 to 100.000 99.970 to 90.000 Rated value 89.970 to 89.979 89.980 to 89.989 89.990 to 90.000 3.110 to 3.120 3.121 to 3.130 3.131 to 3.140 1.965 to 1.975 1.986 to 1.995
Ø 3	Main bearing housings Ø 3 Selection class	Rated value 106.300 to 106.330 106.300 to 106.309 106.310 to 106.319 106.320 to 106.330 106.320 to 106.330
	Bearing shells - main journals	0.060 to 0.100
	Bearing shells - big ends	0.050 to 0.090
PARTS	Main bearing shells Big end bearing shells	0.127 - 0.254 - 0.508 0.127 - 0.254 - 0.508
	Main journal, thrust bearing X1	47.95 to 48.00
	Main bearing housing, thrust bearing X2	40.94 to 40.99
X 3	Thrust washer halves X3	3.38 to 3.43
	Driving shaft shoulder	0.11 to 0.30
	Alignment Ovality Taper $\left\{ \begin{array}{c} = 1 - 2 \\ 0 & 1 - 2 \\ > 1 - 2 \end{array} \right.$	≤ 0.025 0.010 0.010

	Engine		C13 ENS M33	C13 ENT M50
Cylinder heads - valve train			m	m
	Valve guide housings in cylinder head	Ø 1	15.980 t	o 15.997
	Valve guide	Ø 2 Ø 3	10.015 t 16.012 t	
с\$ Р	Valve guides - housings in the cylinder heads		0.015 t	o 0.045
	Valve guide			
	Valves:	Ø 4 α Ø 4 α	9.960 ti 60° 30' 7.970 ti 45° 30'	± 7' 30'' o 7.985
	Valve stem and its guide	2	0.040 t	o 0.070
Ø 1	Housing in head for valve seat:	Ø 1 Ø 1	49.185 t 46.985 t	
a	Outside diameter of valvangle of valve seat in cylinder head:	ve seat; Ø 2 a Ø 2 a	49.260 tr 60° 47.060 tr 45°	- 30' o 47.075
×	Recessing to valve	× ×	0.54 t 1.75 t	
Ś	Between valve seat and head		0.040 t	o 0.090

C13 ENS M33 C13 ENT M50 8.133

	Engine	C13 ENS M33	C13 ENT M50
		mr	n
Ω,	Valve outside spring height:		
	free height H	72.4	40
	under a load of: N 454 ± 22 H1 N 840 ± 42 H2	58	
×	Injector protrusion X	0.53 to	1.34
	Camshaft bush housing fitted in the cylinder head:		
	1 → 7 Ø	88.000 tc	88.030
	Camshaft journal diameter:		
	1 → 7 Ø	82.950 to	82.968
Ø	Camshaft bushing outer diameter Ø	88.153 tc	88.183
Ø	Camshaft bushing inner diameter Ø	83.018 tc	83.085
Ś	Bushings and housings in engine block	0.123 to	0.183
	Bushings and journals	0.050 to	0.135
н	Cam lift:	9.23	
		9.56	
	Ę	11.2	16
	Rocker shaft Ø 1	41.984 to	42.000

mm Bushing housing in rocker arms: 45.000 to 45.016 45.000 to 45.016 45.000 to 45.016 45.000 to 45.016 46.000 to 46.016 Bushing outer diameter for rocker arms: 45.090 to 45.130 45.090 to 45.130 45.090 to 45.130 45.090 to 45.130 46.066 to 46.091 Bushing inner diameter for rocker arms: 42.025 to 42.041 42.025 to 42.041 42.025 to 42.041 42.025 to 42.041 42.015 to 42.071 Between bushings and housings: 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.050 to 0.091 Between rocker arms and shaft: 0.025 to 0.057	3 ENT M50	C13 ENS M33 C13 EN	Engine
in rocker arms: 45,000 to 45,016 45,000 to 45,016 46,000 to 45,016 46,000 to 45,016 46,000 to 45,016 46,000 to 45,010 45,090 to 45,130 45,090 to 45,130 46,066 to 46,091 8ushing inner diameter for rocker arms: 42,025 to 42,041 42,025 to 42,041 42,025 to 42,041 42,025 to 42,041 42,015 to 42,071 8etween bushings and housings: 0,074 to 0,130 0,074 to 0,130 0,050 to 0,091 8etween rocker arms and shait: 0,025 to 0,057		mm	
↓↓ </td <td></td> <td></td> <td>Bushing housing in rocker arms:</td>			Bushing housing in rocker arms:
Image: Constraint of the second sec		45.000 to 45.016	
Bushing outer diameter for rocker arms: 45.090 to 45.130 Image: Constraint of the second s		45.000 to 45.016	
for rocker arms: 45.090 to 45.130 45.090 to 45.130 46.066 to 46.091 Bushing inner diameter for rocker arms: 42.025 to 42.041 42.025 to 42.041 42.015 to 42.071 Between bushings and housings: 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.050 to 0.091 Between rocker arms and shaft: 0.025 to 0.057		46.000 to 46.016	
↓↓ </td <td></td> <td></td> <td>Bushing outer diameter for rocker arms:</td>			Bushing outer diameter for rocker arms:
Image: Constraint of the second s		45.090 to 45.130	↓
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for rocker arms: 42.025 to 42.041 42.025 to 42.041 42.015 to 42.071 Between bushings and housings: 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.050 to 0.091 Between rocker arms and shaft: 0.025 to 0.057		46.066 to 46.091	
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42.015 to 42.071 Between bushings and housings: 0.074 to 0.130 0.074 to 0.130 0.074 to 0.130 0.050 to 0.091		42.025 to 42.041	
Between bushings and housings: 0.074 to 0.130 0.074 to 0.130 0.050 to 0.091 Between rocker arms and shaft: 0.025 to 0.057		42.025 to 42.041	
and housings: 0.074 to 0.130 0.074 to 0.130 0.050 to 0.091 Between rocker arms and shaft: 0.025 to 0.057		42.015 to 42.071	
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0.050 to 0.091 Between rocker arms and shaft: 0.025 to 0.057		0.074 to 0.130	
Between rocker arms and shaft: 0.025 to 0.057		0.074 to 0.130	
and shaft: 0.025 to 0.057		0.050 to 0.091	
0.025 to 0.057			
		0.025 to 0.057	
0.025 to 0.057		0.025 to 0.057	
0.015 to 0.087		0.015 to 0.087	

TIGHTENING TORQUES

Part		Torque	
		Nm	kgm
Capscrews, undercrankcase ⁻	to crankcase (see fig. 1): ◆		
Outside screws 12x1.75	First phase: preliminary tightening	30	3
nner screws M 18x2	Second phase: preliminary tightening	120	12
nner screws	Third phase: angle locking	61	О°
nner screws	Fourth phase: angle locking	5.	5°
Outer screws	Fifth phase: angle locking	60)°
Piston cooling nozzle union	◆	35 ± 2	3.5 ± 0.2
Heat exchanger fixing screw	s to the block (see fig. 7): ◆		
	preliminary tightening	11.5 ± 3.5	1.15 ± 0.35
	tightening	19 ± 3	1.9 ± 0.3
Spacer and oil sump fixing so	crews (see fig. 8) ♦	50	5
Gearbox fixing screws to the	e block M 12x1.75	63 ± 7	6.3 ± 0.7
Cylinder head fixing screws	(see fig. 2): ◆		
First phase	preliminary tightening	60	6
Second phase	preliminary tightening	120	12
Third phase	angle locking	90	О°
Fourth phase	angle locking	65°	
Rocker shaft fixing screws (s	ee fig. 3): ◆		
First phase	preliminary tightening	100	10
Second phase	angle locking)°
Lock nut for rocker adjustme	ent screw 🔶	39 ± 5	3.9 ± 0.5
njector blocking brackets sc	rews 🔶	26	2.6
Engine support bracket faste	ening screws to cylinder head	19 ± 3	1.9 ± 0.3
Screw fastening the engine s	supporting bracket to the cylinder head:		
First phase	preliminary tightening	120	12
Second phase	angle locking	4.	5°
Camshaft gear capscrews: ♦			
First phase	preliminary tightening	60	6
Second phase	angle locking	60)°
Phonic wheel fastening screw	vs to distribution gear	8.5 ± 1.5	0.85 ± 0.15
Exhaust manifold fixing screv	∧s (see fig. 4): ▲		
5	preliminary tightening	40 ± 5	4 ± 0.5
	tightening	70 ± 5	7 ± 0.5
Connecting rod cap fixing sc	rews: 🔶		
First phase	preliminary tightening	60	6
Second phase		60	

• Lubricate with UTDM oil before installation

▲ Lubricate with graphitized oil before installation

TIGHTENING TORQUES

Part	Tor	que
	Nm	kgm
Engine flywheel fixing screws M16x1.5x58: ◆ First phase preliminary tightening Second phase angle locking	120	12 0°
	90	J
Engine flywheel fixing screws M16x1.5x110: First phase preliminary tightening Second phase angle locking	70	7 0°
ntermediate gear pin fixing screws: Intermediate First phase preliminary tightening Second phase angle locking	30	3 0°
dle gear link rod fastening screw	24.5 ± 2.5	2.4 ± 0.25
Dil pump fastening screw	24.5 ± 2.5	2.4 ± 0.25
Dil pump suction rose fastening screw	24.5 ± 2.5	2.4 ± 0.25
Front cover fastening screw to cylinder block $iglet$	19 ± 3	1.9 ± 0.3
Supply pump fastening screw to gearcase \blacklozenge	19 ± 3	1.9 ± 0.3
Tuel filter support fastening screw to cylinder head $iglet$	37 ± 3	3.7 ± 0.3
Furbo-compressor fastening screws and nuts (see fig. 5) \blacktriangle		
Water pump fastening screw to cylinder block	25 ± 2.5	2.5 ± 0.25
Pulley fastening screw to hub First phase preliminary tightening Second phase angle locking	70	7 0°
Rocker cap fixing screws (see fig. 9)	9	0.9
Thermostat box fastening screws to cylinder head	24.5 ± 2.5	2.4 ± 0.2
Automatic tightener fastening screws to cylinder block	45 ± 5	4.5 ± 0.5
ixed tightener fastening screws to cylinder block	105 ± 5	10.5 ± 0.5
Starter fastening screws	74 ± 4	7.4 ± 0.4
Alternator support fastening screw to cylinder block M $10 \times 1.5 - I = 60 \text{ mm}$	44 ± 4	4.4 ± 0.4
Alternator bracket fastening screw to cylinder block M 10x1.5 - $I = 35$ mm	30 ± 3	3 ± 0.3
-lywheel rev sensor fastening screw	8 ± 2	0.8 ± 0.2
Camshaft rev sensor fastening screw	8 ± 2	0.8 ± 0.2
P.E solenoid connector fastening screw	1.62 ± 0.3	0.16 ± 0.03
Overboost pressure sensor fastening screw	8 ± 2	0.8 ± 0.2
Absolute pressure sensor fastening screw	22.5 ± 2.5	2.2 ± 0.2

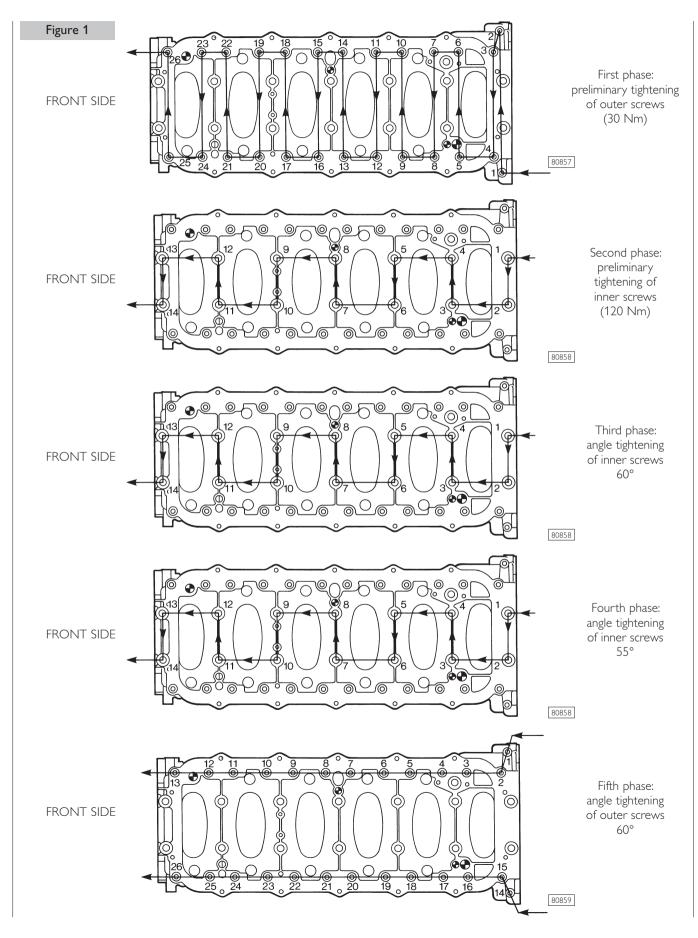
• Lubricate with UTDM oil before installation

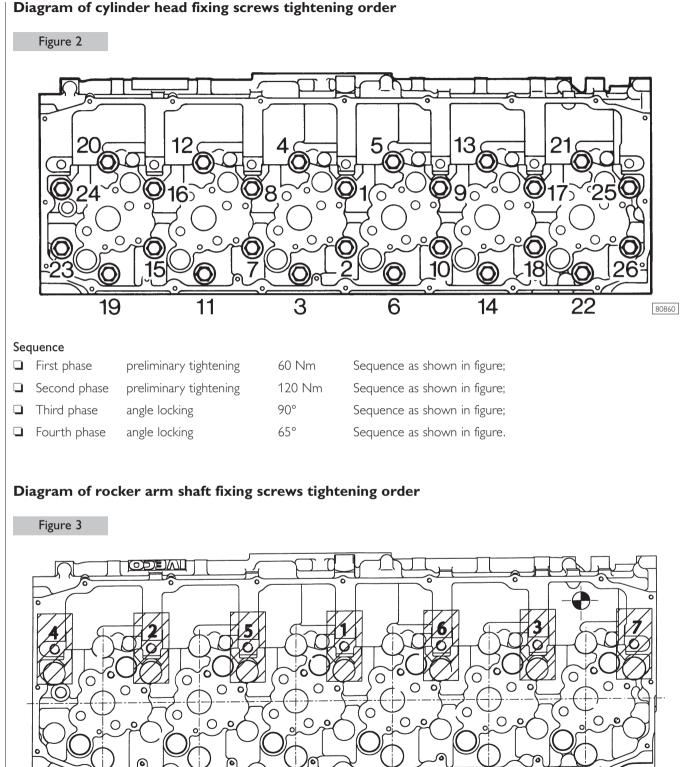
▲ Lubricate with graphitized oil before installation

TIGHTENING TORQUES

Part	Tor	que
	Nm	kgm
Fuel temperature sensor	35	3.5
Coolant temperature sensor	35	3.5
Filter clogging sensor	55 ± 5	5.5 ± 0.5
Oil temperature switch	25 ± 1	2.5 ± 0.1
Oil pressure sensor	25 ± 1	2.5 ± 0.1
Oil filter clogging sensor	55 ± 5	5.5 ± 0.5
Electric wire fastening screw	8 ± 2	0.8 ± 0.2

Underblock fixing screws tightening order





Sequence

□ First phase tighten the screws 1-2-3 until they bear down on the rocker arm shaft;

100 Nm

Second phase

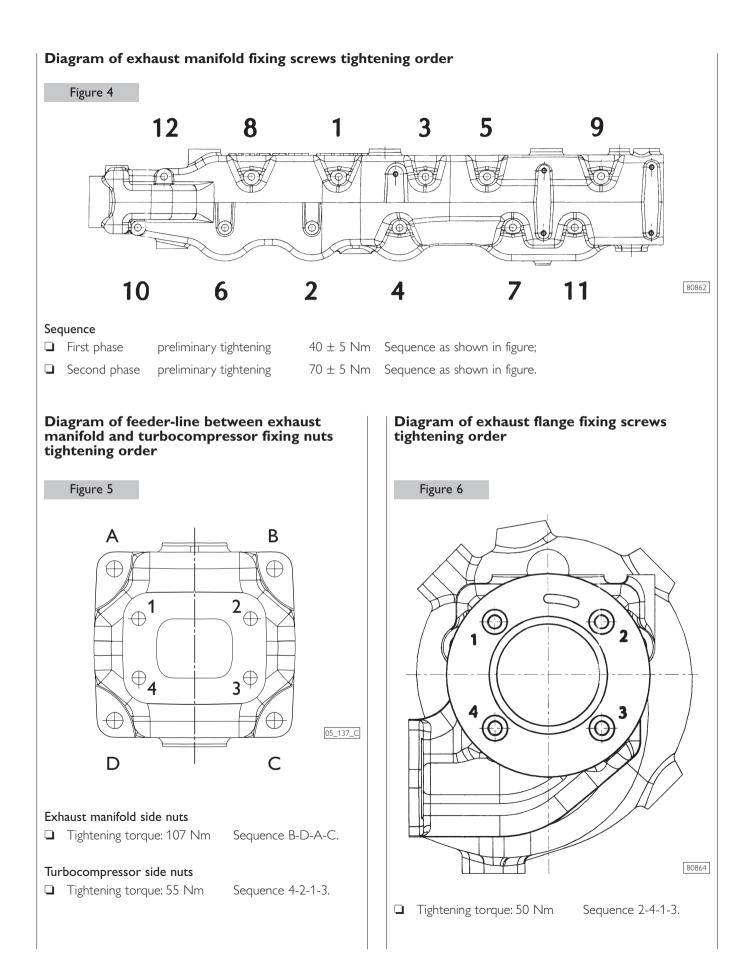
Third phase

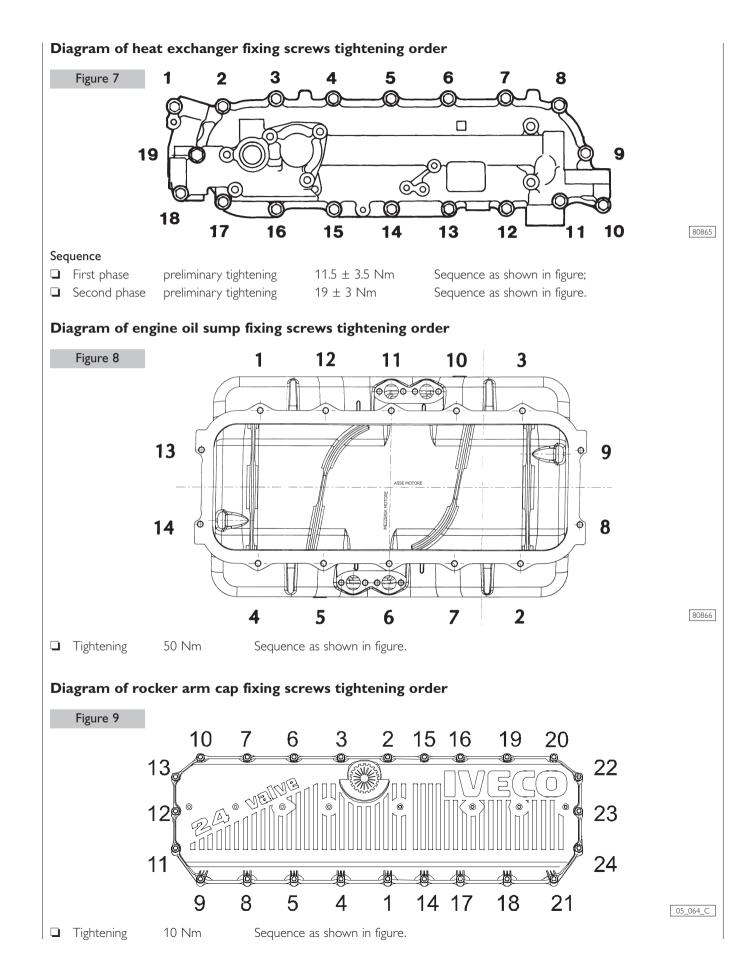
preliminary tightening

angle locking

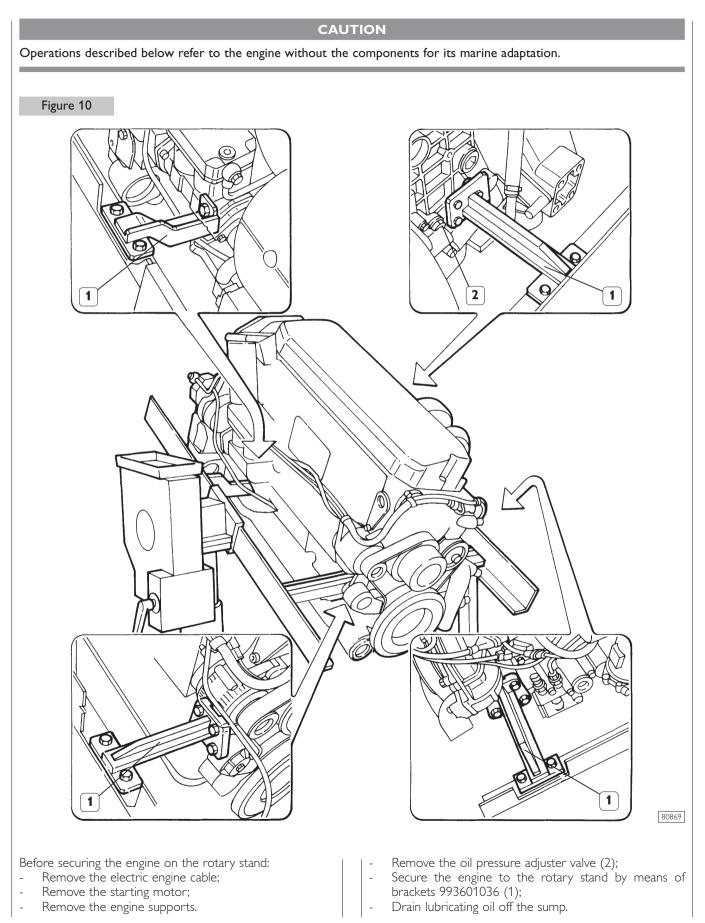
- 60°
- Sequence as shown in figure; Sequence as shown in figure.

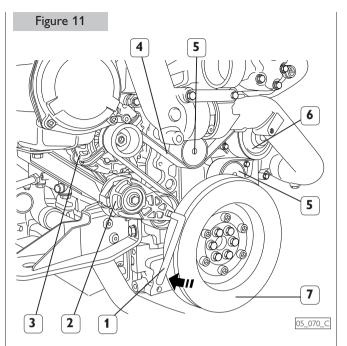
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ENGINE DISASSEMBLY AT THE BENCH



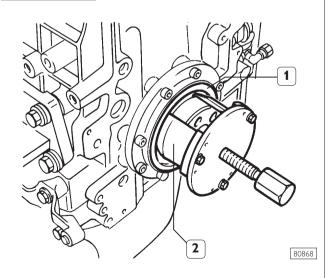


Using an appropriate tool (1), operate in the direction of the arrow, and remove the belt (4) driving the water pump and alternator.

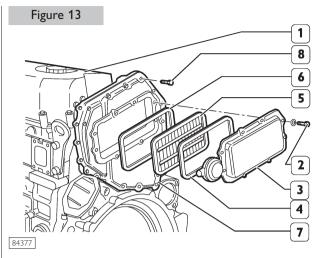
Remove the following components:

- Automatic belt tightener support (2);
- Alternator (3);
- Fixed tightener (5);
- Water pump (6) and piping;
- Damping flywheel (7);
- Disconnect all electric connections and the sensors;
- Remove fuel pump and piping and oil heat exchanger.

Figure 12



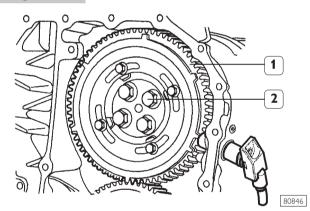
Fit the extractor 99340053 (2) and remove the engine crankshaft seal gasket (1), remove the cover.



Remove the rocker arm cover (1), take off the screws (2) and remove: the cover (3), the filter (5) and the gaskets (4 and 6).

Take off the screws (8) and remove the blow-by case (7).

Figure 14

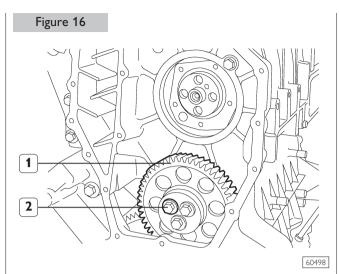


Unscrew the screws (2) and remove the gear (1) with the phonic wheel.

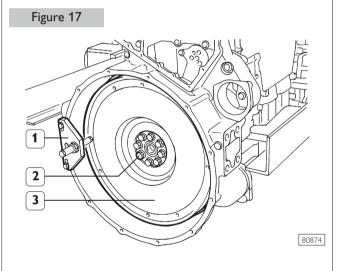
Figure 15

Unscrew the screws (1); tighten a screw in a reaction hole and remove the shoulder plate (3), remove the sheet gasket..

8.144 C13 ENS M33 C13 ENT M50

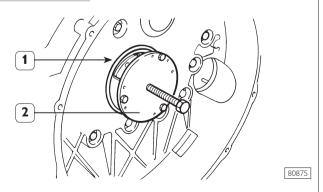


Unscrewthe screws (2) and remove the transmission gear (1).

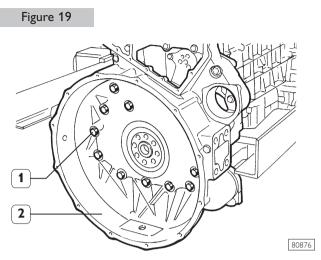


Stop the engine flywheel (3) rotation by means of tool 99360351 (1), untighten the fixing screws (2) and remove the engine flywheel.

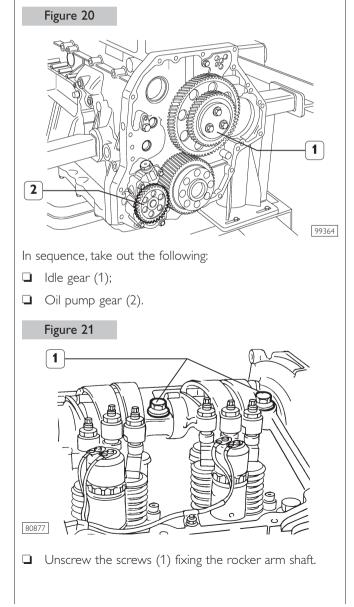


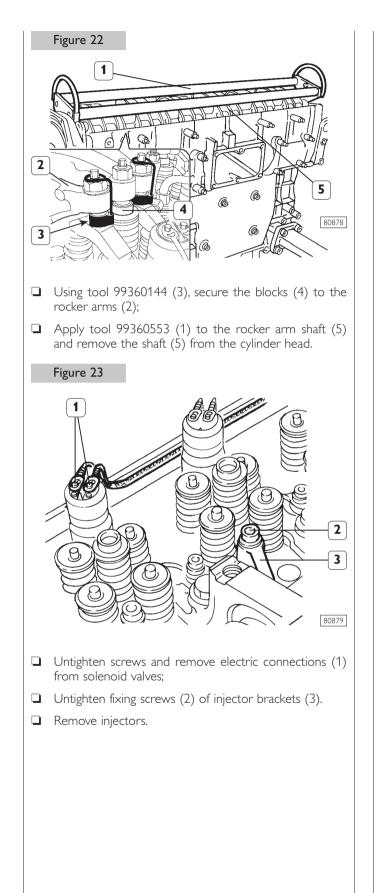


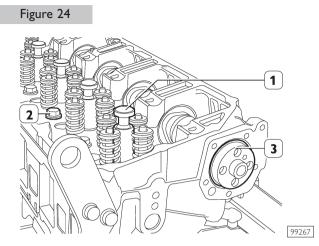
Apply extractor 99340054 (2) and pull out the seal gasket (1).



Untighten the screws (1) and take down the flywheel housing (2).

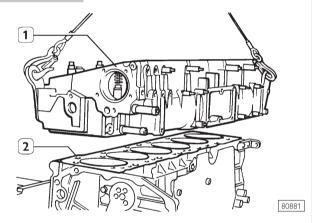






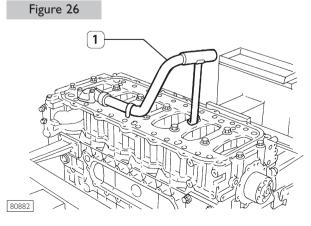
- Fit the plugs 99360180 (1) in place of the injectors;
- □ Take out the camshaft (3);
- □ Take out the screws (2) fixing the cylinder head.

Figure 25

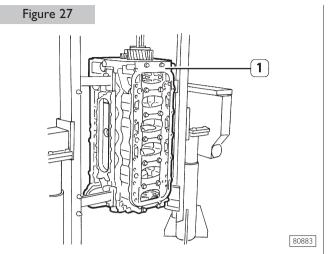


□ By means of wire ropes, lift the cylinder head (1) and remove seals (2).

Untighten screws and remove the engine oil sump.

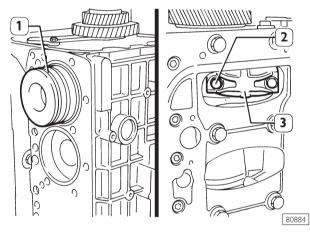


Untighten screws and remove suction rose (1).

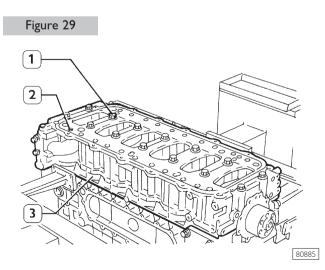


Rotate the block (1) to the vertical position.

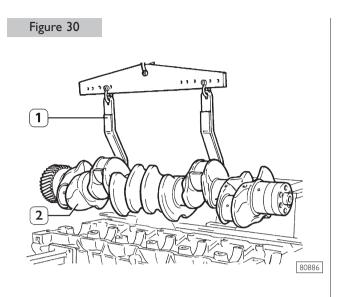




Untighten screws (2) fixing the connecting rod cap (3) and remove it. Remove the connecting rod-piston assembly from the upper side. Repeat these operations for the other pistons.

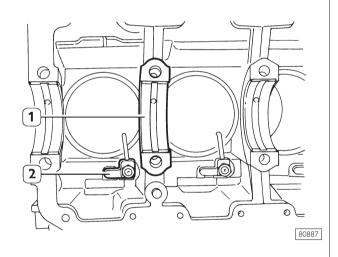


By means of proper and splined wrenches, untighten the screws (1) and (2) and remove the under-block (3).



Remove the crankshaft (2) by means of tool 99360500 (1).





Remove the crankshaft half-bearings (1), untighten the screws and remove oil spray nozzles (2).

Take down cylinder liners as specified in the relative paragraph.

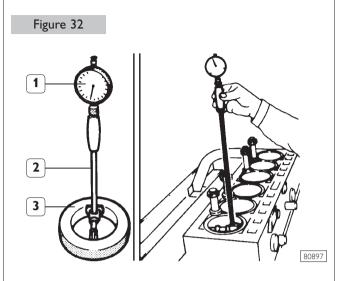
CAUTION

After disassembling the engine, thoroughly clean disassembled parts and check their integrity.

Instructions for main checks and measures are given in the following pages, in order to determine whether the parts can be re-used.

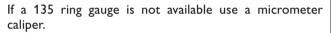
CYLINDER BLOCK

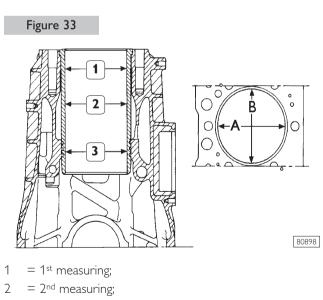




Internal diameter of the cylinder liners is checked for ovalization, taper and wear, using a bore dial (1) centesimal gauge 99395687 (2) previously reset to ring gauge (3), diameter 135 mm.

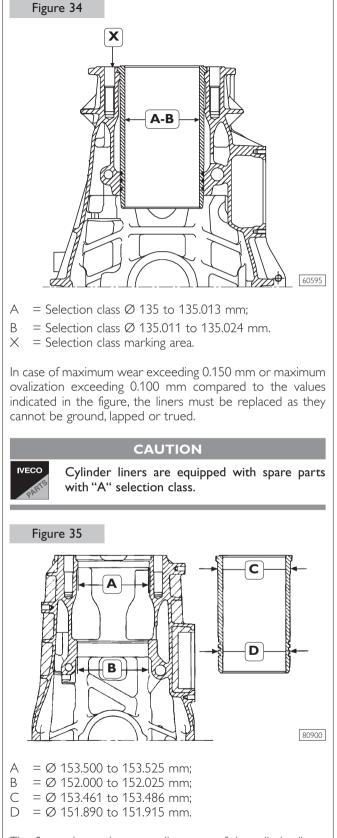
CAUTION





 $3 = 3^{rd}$ measuring.

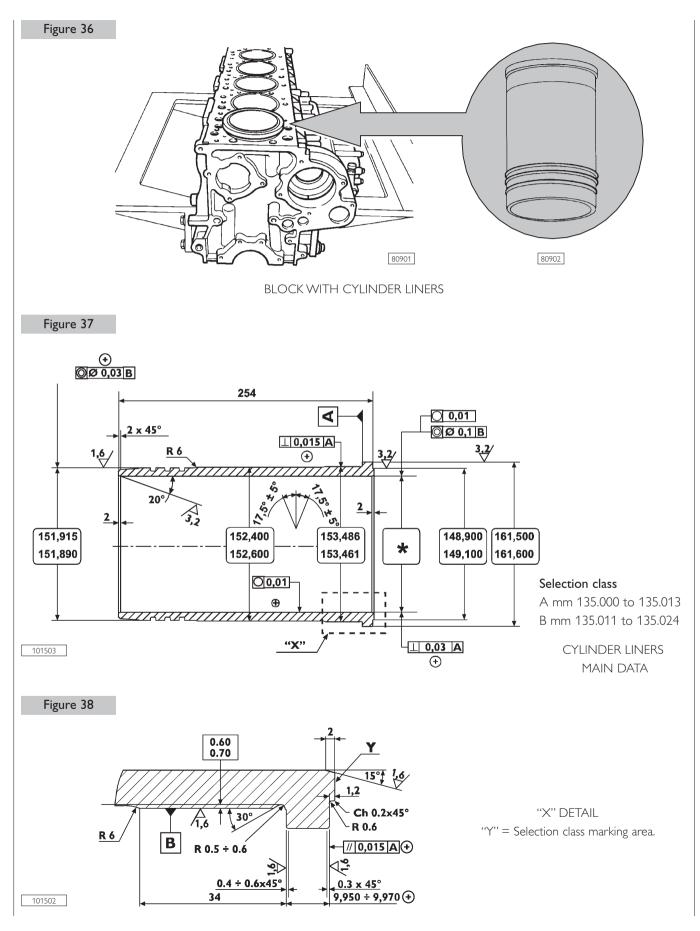
Carry out measurings on each cylinder liner at three different levels and on two (A-B) surfaces, to one another perpendicular, as shown in the figure above.

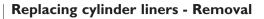


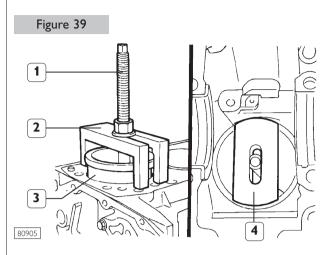
The figure shows the outer diameters of the cylinder liners and the relative seat inner diameters.

The cylinder liners can be extracted and installed several times in different seats, if necessary.

CYLINDER LINERS



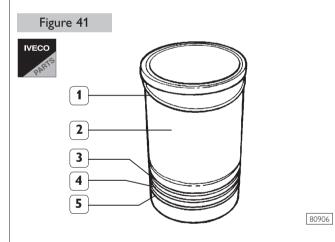




Place components 99360706 (1 and 2) and plate 99360728 (4) as shown in the figure, by making sure that the plate (4) is properly placed on the cylinder liners.

Tighten the screw nut (1) and remove the cylinder liner (3) from the block.

Fitting and checking protrusion

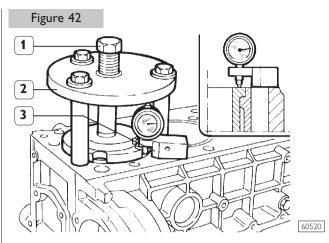


Always replace water sealing rings (3, 4 and 5). Install the adjustment ring (1) on the cylinder liner (2); lubricate lower part of liner and install it in the cylinder unit using the proper tool.

CAUTION

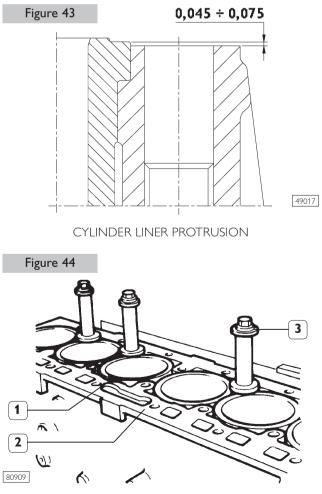
IVECO

The adjustment ring (1) is supplied as spare parts in the following thicknesses: 0.08 mm - 0.10 mm - 0.12 - 0.14 mm.



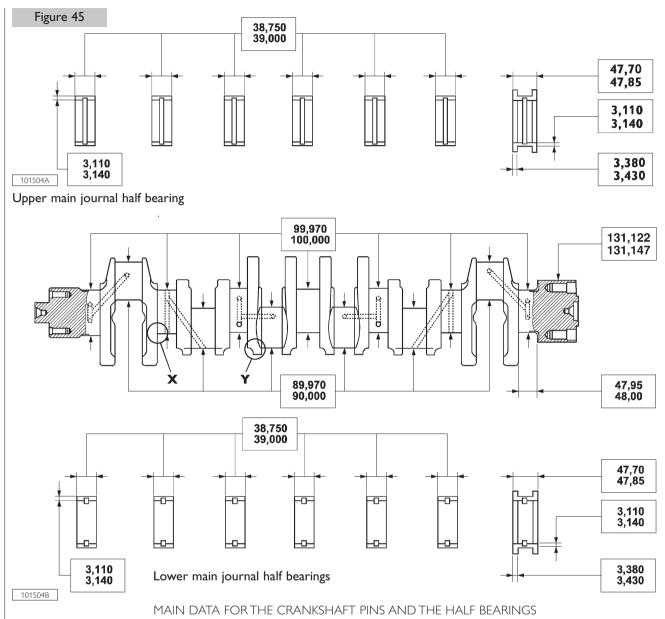
Check the protrusion of the cylinder liners with tool 99360334 (2) and tightening the screw (1) to a torque of 225 Nm.

Using the dial gauge 99395603 supplied as standard with the dial gauge base 99370415 (3), check that the protrusion of the cylinder liner over the supporting face of the cylinder head is 0.045 - 0.075 mm (Figure 43); if this is not so, replace the adjustment ring (1, Figure 41), supplied as a spare part with several thicknesses.

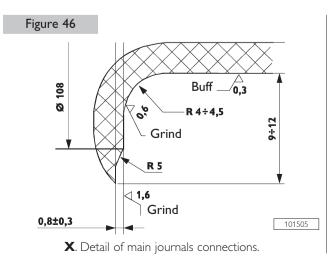


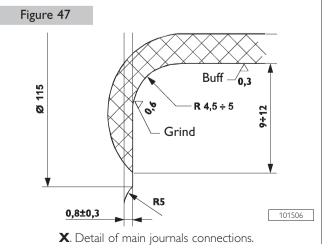
When the installation is completed, block the cylinder liners (1) to the block (2) with studs 99360703 (3).

CRANKSHAFT



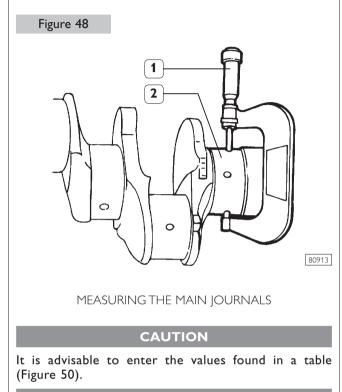
Check the condition of the journals and the big end pins; there must no be signs of scoring, ovalization or excessive wear. The data given refer to the normal diameter of the pins.

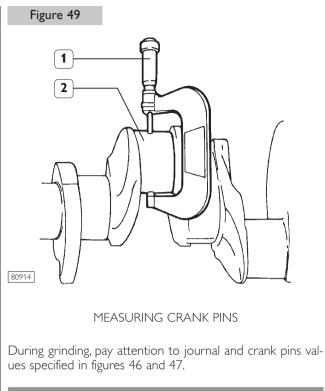




Measuring main journals and crankpins

Before grinding the crank pins using a micrometer (1), measure the main journals and the crank pins (2) and decide, on the basis of the undersizing of the bearings, the final diameter to which the pins are to be ground.

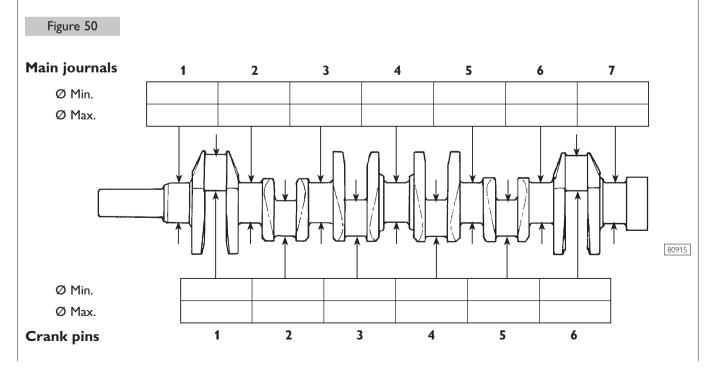




CAUTION

All journals and crank pins must also be ground to the same undersizing class, in order to avoid any alteration to shaft balance.

Fill in this table with the measurements of the main journals and the crank pins.



PRELIMINARY MEASUREMENT OF MAIN AND BIG END BEARING SHELL SELECTION DATA

For each journal and crankpin, the following operations must Determining the diameter class of the block housing be carried out: Two series of numbers are marked on the front side of the block, in the position specified (Figure 51, top). Journals □ A four-digit number representing the coupling number Determine the diameter class of the block housing; of block to the relevant underblock; Determine the diameter class of the main journal; □ Each of the following seven digits represents the Select half-bearing class to be installed. diameter class of the housing they refer to (Figure 51, bottom); Crankpins Each of these digits may be **1**, **2** or **3**. Determine the diameter class of the connecting rod; Determine the diameter class of the big end pin; Select half-bearing class to be installed. Figure 51 Class Main bearing housing nominal diameter (mm) 1 106.300 to 106.309 = 106.310 to 106.319 2 = 3 = 106.320 to 106.330 \cap Ο С Ō Ō $\overline{}$ Ō \overline{O} O, 7/6/1

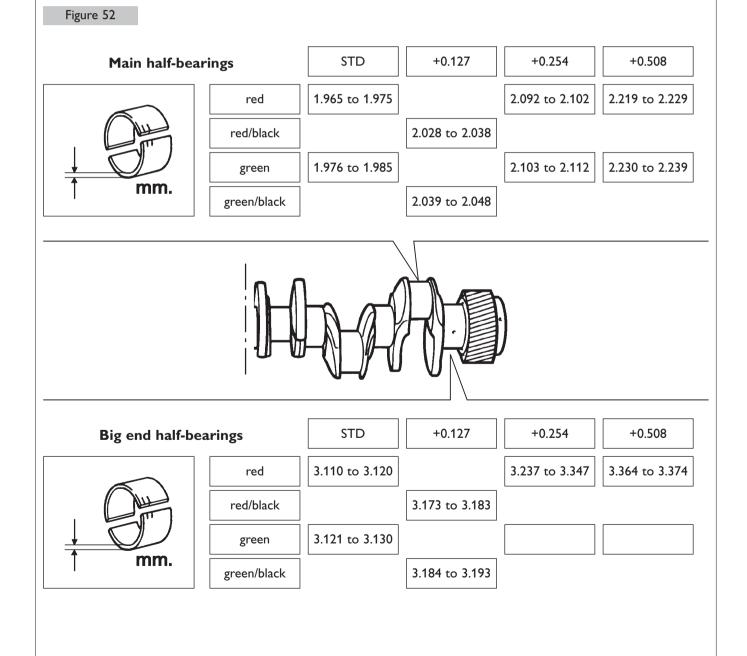
Selecting the main and big end bearing shells

CAUTION

In order obtain the required assembly clearances, main half-bearings and big end half-bearings must be selected as specified below.

This operation makes it possible to identify the most suitable half-bearings for each journal (half-bearings can belong to different classes for the individual journals). Depending on half-bearing thickness, tolerance classes are selected by colors (red-green- red/black - green/black).

Figure 52 shows the characteristics of main half-bearings and big end half-bearings supplied as spares in standard measures (STD) and admissible oversizing (+0.127, +0.254, +0.508).

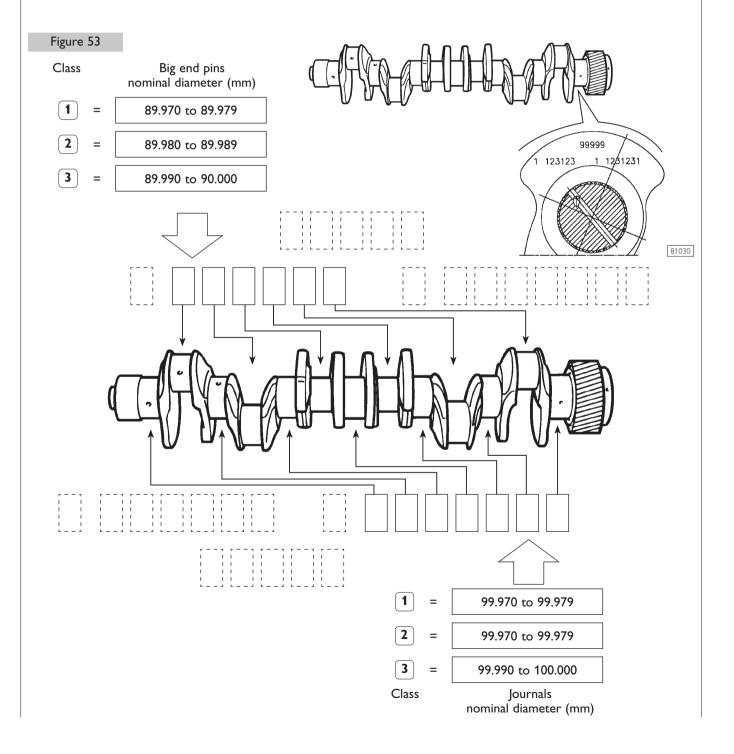


Selection of main half-bearings (nominal diameter pins)

Main journals and crank pins: determining the journal and pin diameter class

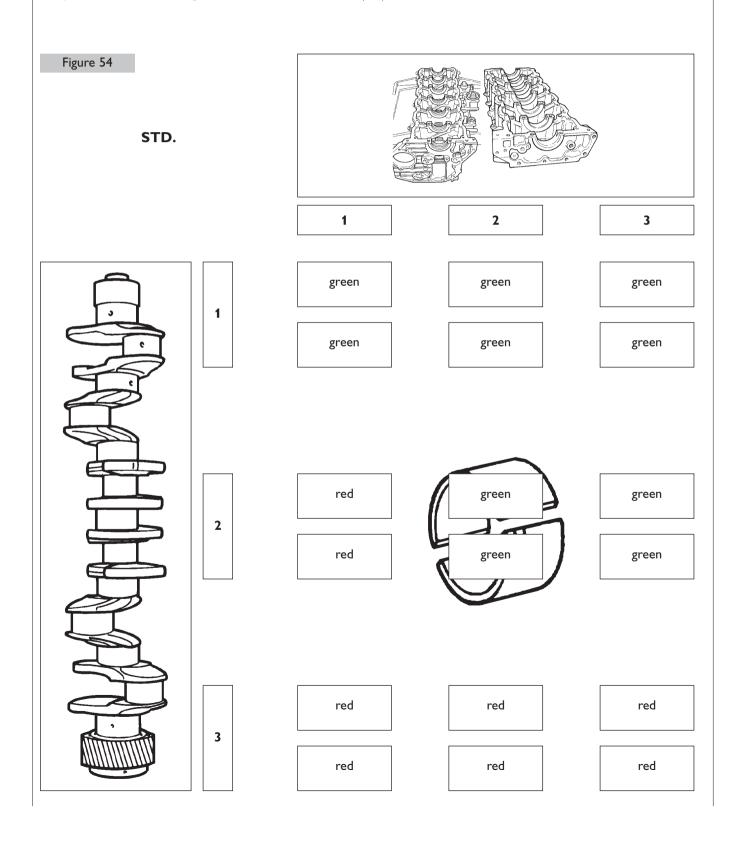
Three series of numbers are specified on the driving shaft, in the position specified (Figure 53 top, right):

- A five-digit number representing the shaft serial number;
- □ Under this number on the left, a six-digit number refers to big end pins and is preceded by a single digit, which indicates pin status (1 = STD, 2 = -0.127); each of the following six digits represents the diameter class of each big end pin it refers to (Figure 53, top, left);
- □ The seven-digit series, on the right, refers to the journals and is preceded by a single digit, which indicates journal status (1 = STD, 2 = -0.127); each of the following seven digits represents the diameter class of the journal it refers to (Figure 53, bottom).

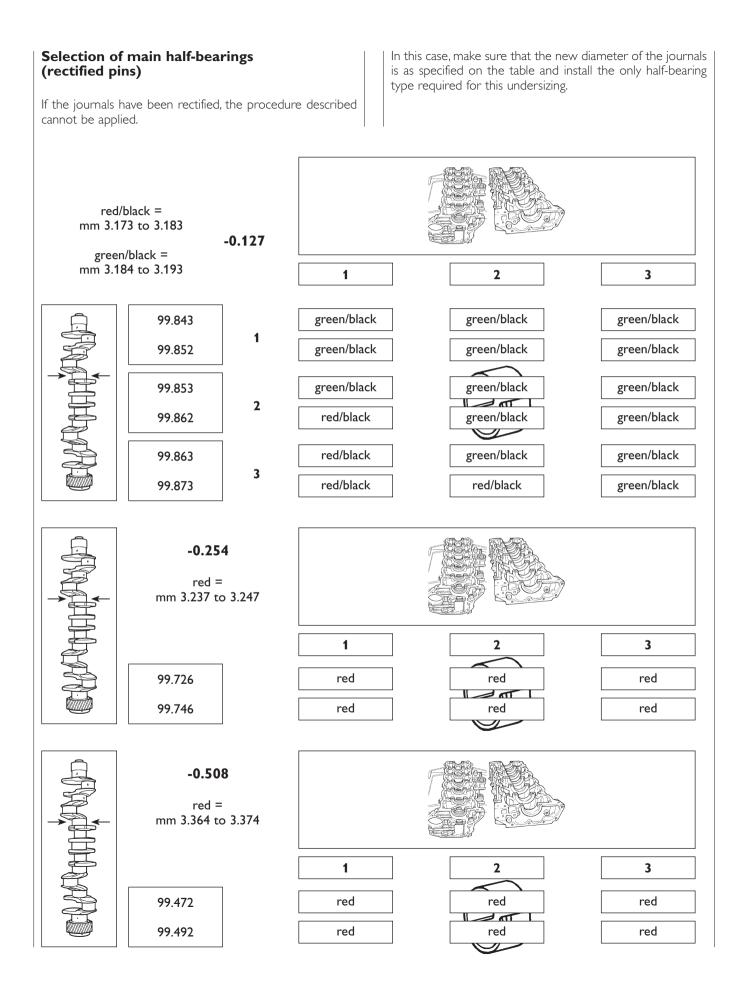


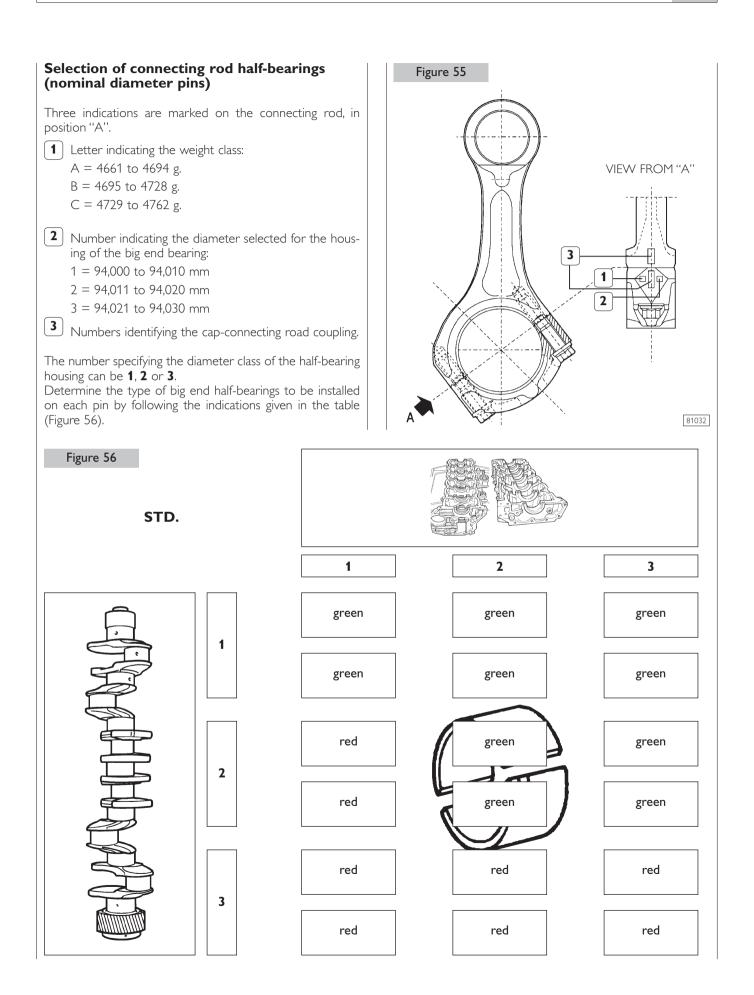
Selection of main half-bearings (nominal diameter pins)

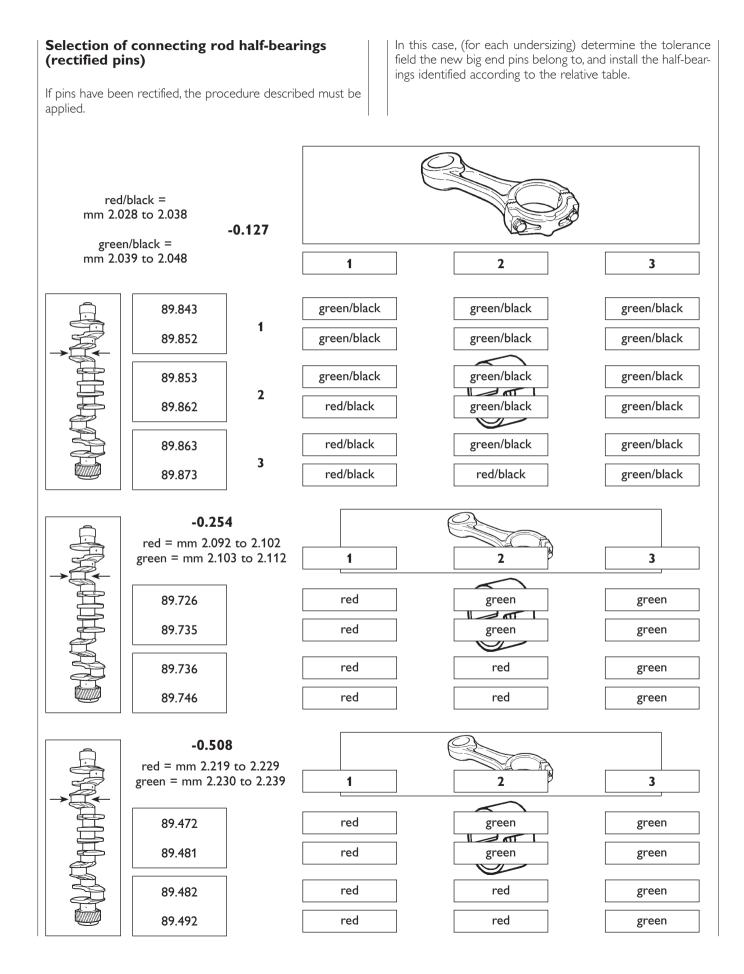
After detecting, for each journal, the necessary data on block and crankshaft, select the type of half-bearings to be used, in compliance with the following table:



8.156

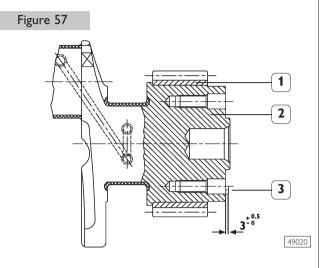






Replacing the timing control gear and the oil pump

Check that the teeth of the gears are not damaged or worn, otherwise remove them using the appropriate extractor.

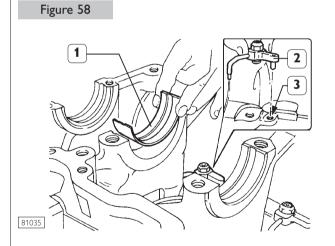


When fitting gear (1) onto drive shaft (2), the gear must be heated for 2 hours max. in a furnace, at a temperature not higher than 180°C.

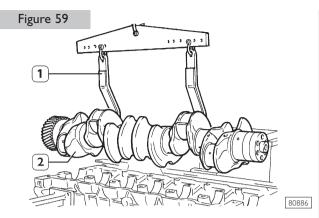
Let them cool down after the installation.

If changing the pin (3), after fitting it on, check it protrudes from the crankshaft as shown in the figure.

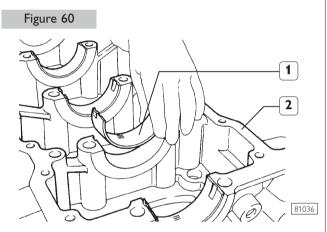
Checking main journal installation clearance



Install the oil spray nozzles (2) and have the dowel coincide with the block hole (3). Install the half-bearings (1) on the main bearings.

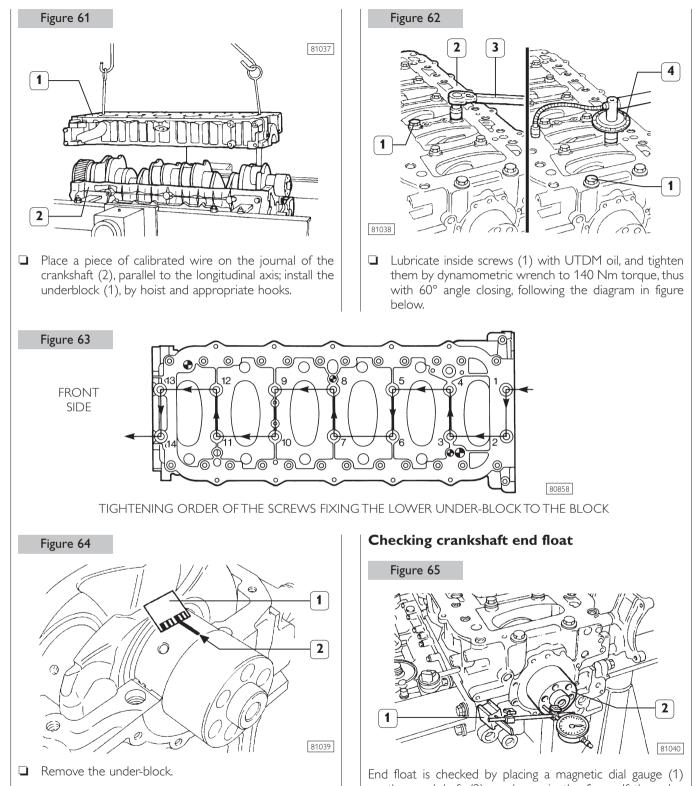


Using the hoist and hook 99360500 (1) mount the driving shaft (2).



Install the half-bearings (1) on the main bearings in the underblock (2).

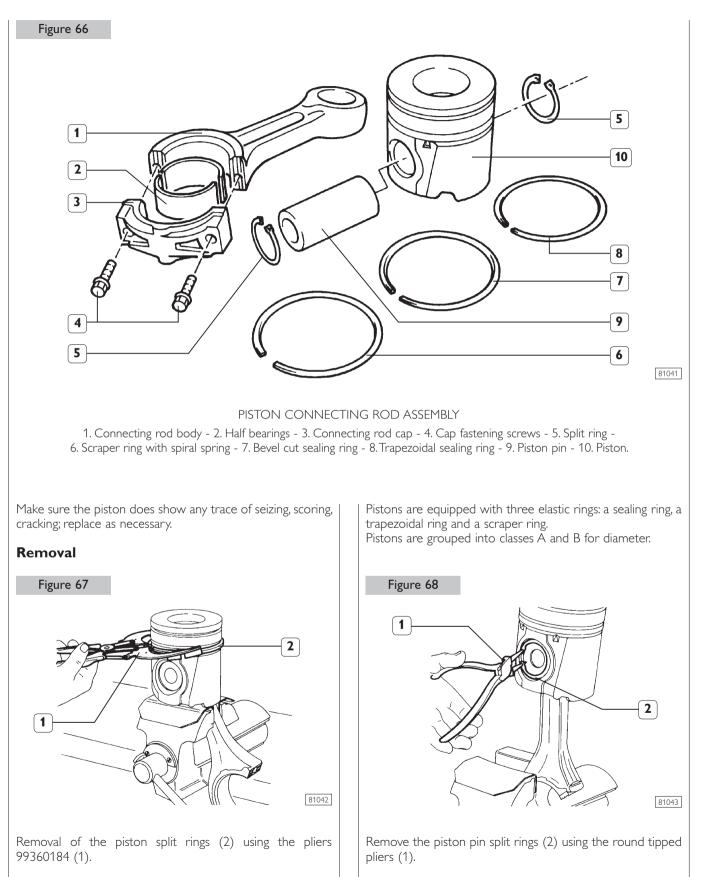
Check the installation clearance between the main journals and the relative bearings as follows:

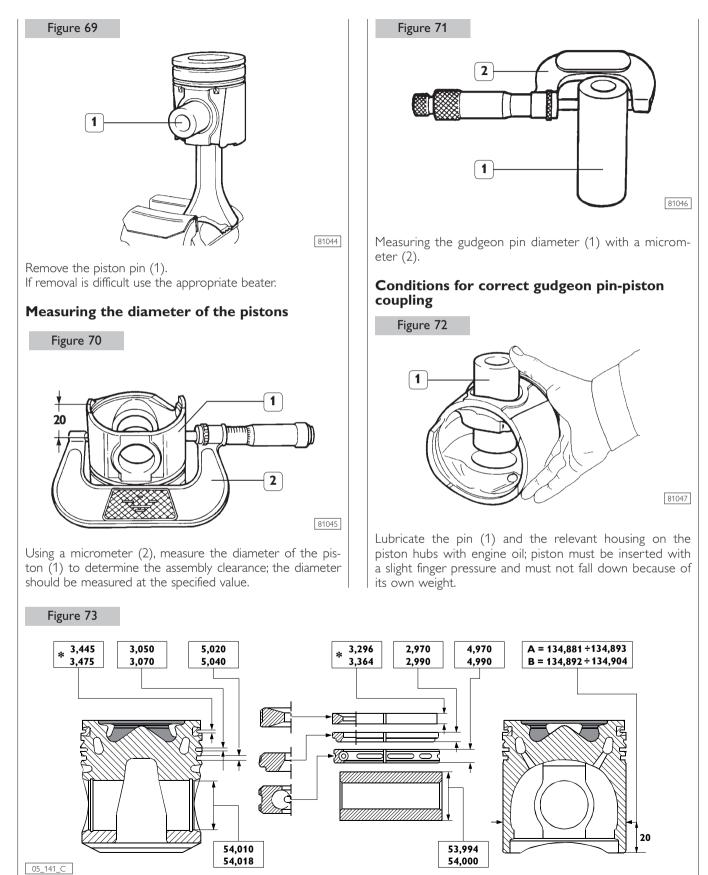


The clearance between the main bearings and the journals is obtained by comparing the calibrated wire length (2) at the maximum deflection point, with the calibrated scale on the coating (1) containing the calibrated wire.

Numbers shown on the scale specify the clearance in coupling millimeters. If the clearance obtained is different from the clearance required, replace the half-bearings and repeat this check. End float is checked by placing a magnetic dial gauge (1) on the crankshaft (2), as shown in the figure. If the value obtained is higher than specified, replace the rear thrust half-bearings and repeat this check.

PISTON CONNECTING ROD ASSEMBLY

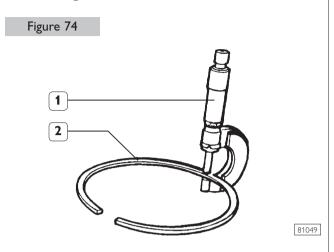




MAIN DATA ON PISTONS, AND PISTONS RINGS

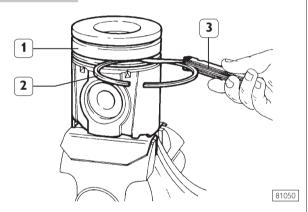
* Values are determined on Ø of 130 mm.

Piston rings

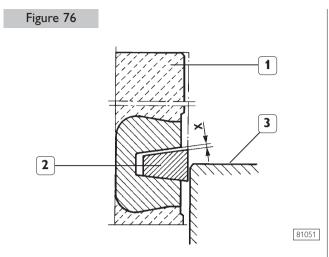


Check the thickness of the piston ring (2) using a micrometer (1).

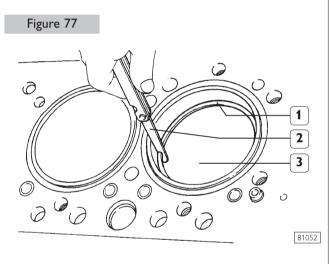
Figure 75



Check the clearance between the sealing rings (2) and the relative piston housings (1) using a thickness gauge (3).



The sealing ring (2) of the 1st cavity is trapezoidal. Clearance " \mathbf{X} " between the sealing ring and its housing is measured by placing the piston (1) with its ring in the cylinder barrel (3), so that the sealing ring is half-projected out of the cylinder barrel.



Check the opening between the ends of the sealing rings (1), using a thickness gauge (2), entered in the cylinder barrel (3).

If the distance between ends is lower or higher than the value required, replace split rings.

VIEW FROM "A"

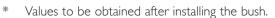
81032

71716

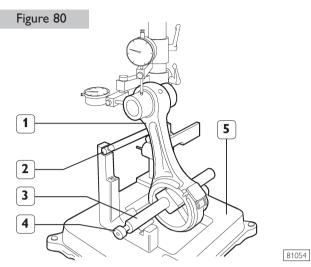
1

CONNECTING ROD

Data concerning the class section of connecting rod housing Figure 78 and weight are stamped on the big end. CAUTION When installing connecting rods, make sure they all belong to the same weight class. Diagram connecting rod marks **1** Letter indicating the weight class: A = 4.661 to 4.694 g. B = 4.695 to 4.728 g. C = 4.729 to 4.762 g. **2** Number indicating the selection of diameter for the big end bearing housing: 1 = 94.000 to 94.010 mm 2 = 94.011 to 94.020 mm 3 = 94.021 to 94.030 mm **3** Numbers identifying cap-connecting rod coupling. Figure 79 59,000 59,030 59,085 54,019 53,994 * 59,110 54,035 54,000 1,965 1,995 94,000 94,030 _____ MAIN DATA - BUSH, CONNECTING ROD, PIN AND HALF-BEARINGS





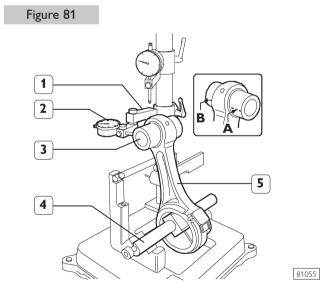


Checking axis alignment

Check the alignment of the axes of the connecting rods (1) with device 99395363 (5), proceeding as follows:

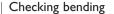
- □ Fit the connecting rod (1) on the spindle of the tool 99395363 (5) and lock it with the screw (4);
- □ Set the spindle (3) on the V-prisms, resting the connecting rod (1) on the stop bar (2).

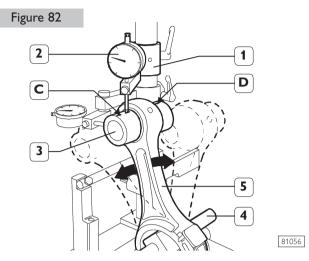
Checking torsion



Check the torsion of the connecting rod (5) by comparing two points (**A** and **B**) of the pin (3) on the horizontal plane of the axis of the connecting rod.

Position the mount (1) of the dial gauge (2) so that this preloads by approx. 0.5 mm on the pin (3) at point **A** and zero the dial gauge (2). Shift the spindle (4) with the connecting rod (5) and compare any deviation on the opposite side **B** of the pin (3): the difference between **A** and **B** must be no greater than 0.08 mm.





Check the bending of the connecting rod (5) by comparing two points C and D of the pin (3) on the vertical plane of the axis of the connecting rod.

Position the vertical mount (1) of the dial gauge (2) so that this rests on the pin (3) at point C.

Swing the connecting rod backwards and forwards seeking the highest position of the pin and in this condition zero the dial gauge (2).

Shift the spindle with the connecting rod (5) and repeat the check on the highest point on the opposite side D of the pin (3). The difference between point C and point D must be no greater than 0.08 mm.

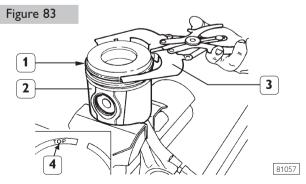
Mounting the connecting rod-piston assembly

Carry out the steps for removal described on page 161 in reverse order.

CAUTION

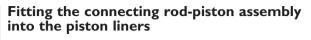
The connecting rod screws can be reused as long as the diameter of the thread is not less than 13.4 mm.

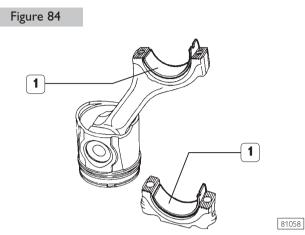
Mounting the piston rings



To fit the piston rings (1) on the piston (2) use the pliers 99360184 (3).

The rings need to be mounted with the word "TOP" (4) facing upwards. Direct the ring openings so they are staggered 120° apart.

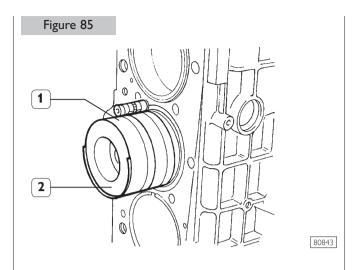




Install half-bearings (1), selected as specified from page 152, on both the connecting rod and the cap.

CAUTION

As spares, class A pistons are provided and can be fitted also to cylinder barrels belonging to class B.

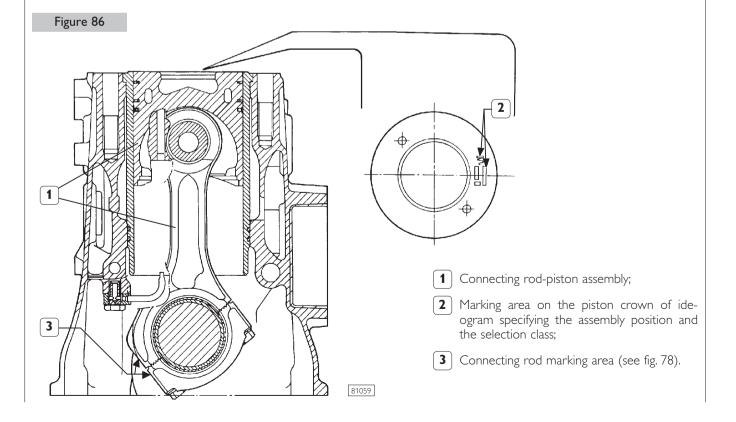


Fit the connecting rod-piston assemblies (1) into the piston liners (2) using band 99360605 (1, Figure 85). Check the following:

- □ The openings of the split rings are offset by 120°;
- All pistons belong to the same class, A or B;
- □ Ideogram stamped on the piston crown is placed toward the engine flywheel, or the cavity located on the piston skirt corresponds to the position of the oil spray nozzles.

Piston protrusion check

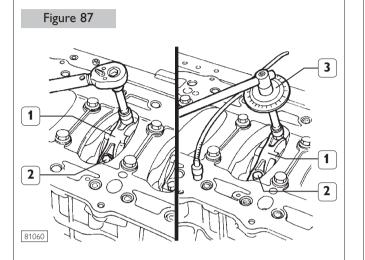
Once assembly is complete, check piston protrusion from cylinder barrels: it must be 0.12 to 0.42 mm.



Checking assembly clearance of big end pins

To check the clearance proceed as follows:

□ Connect the connecting rods to the relative main journals, place a length of calibrated wire on the latter;

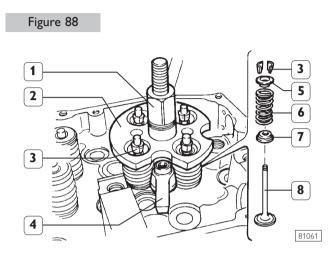


- □ Install the connecting rod caps (1) with half-bearings; tighten the connecting rod cap fixing screws (2) to 60 Nm (6 Kgm) torque. By tool 99395216 (3), tighten the screws further at 60° angle;
- □ Remove the caps and check the clearance by comparing the width of the calibrated wire with the scale calibration on the envelope containing the wire.

CYLINDER HEAD

Before taking down the cylinder head, check the seal using the appropriate tool; in case of leakage replace the cylinder head.

Valve removal



Install and fix tool 99360264 (2) with bracket (4); tighten by lever (1) until cotters are removed (3); remove the tool (2) and the upper plate (3), the spring (6) and the lower plate (7).

Repeat the operation on all the valves. Turn the cylinder head upside down and remove the valves (8).

Checking the planarity of the head on the cylinder block

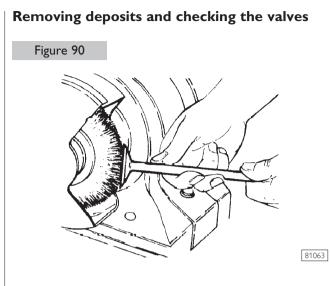
Figure 89

The planarity (1) is checked using a ruler (2) and a thickness gauge (3). If deformations exist, surface the head using proper surface grinder; the maximum amount of material to be removed is 0.2 mm.

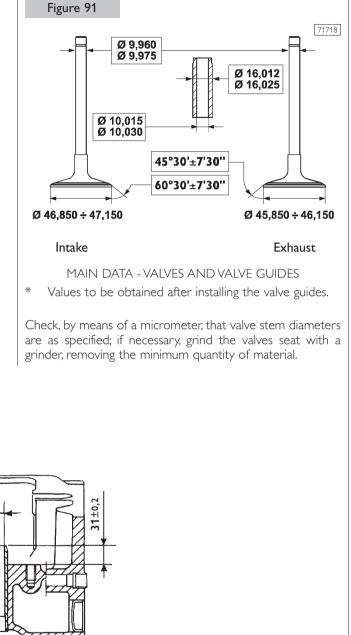
CAUTION

After leveling, make sure that valve sinking and injector protrusion are as described in the relative paragraph.

VALVES

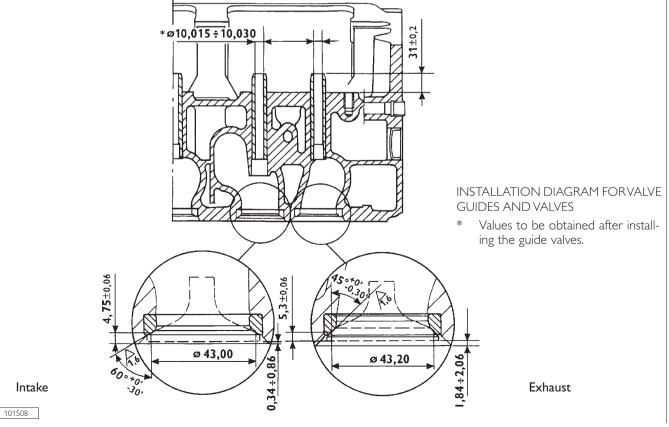


Remove carbon deposits using the metal brush supplied. Check that the valves show no signs of seizure or cracking. Check the diameter of the valve stem using a micrometer (see fig. 92) and replace if necessary.



Valve guides





REPLACING INJECTOR HOLDER CASES

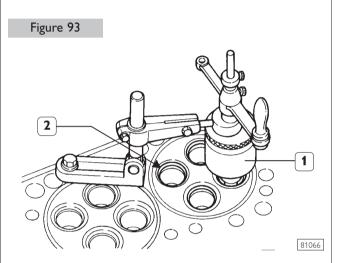
Replacing of valve guides

Remove valve guides by means of tool 99360143. Install by means of tool 99360143 equipped with part 99360296, which determines the exact installation position of valve guides into the cylinder heads; if they are not available, install the valve guides in the cylinder head so that they project out by mm 30.8 to 31.2 (fig. 92).

After installing the valve guides, smooth their holes with sleeker 99390310.

Replacing - Reaming the valve seats

To replace the valve seats, remove them using the appropriate tool.



Ream the valve seats (2) on cylinder head using tool 99305019 (1).

CAUTION

Valve seats must be reamed whenever valves or valve guides are replaced or ground.

Check the valve seats (2). If you find any slight scoring or burns, regrind themwith tool 99305019 (1) according to the angles shown in Figure 92. If it is necessary to replace them, using the same tool and taking care not to affect the cylinder head, remove as much material as possible from the valve seats so that, with a punch, it is possible to extract them from the cylinder head.

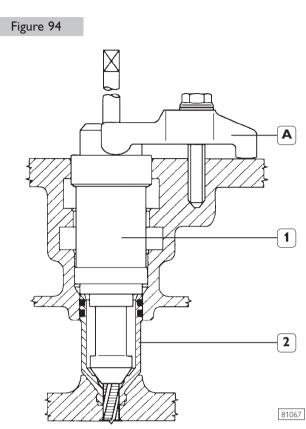
Heat the cylinder head to 80 - 100°C and, using a drift, fit in the new valve seats (2), chilled beforehand in liquid nitrogen.

Using tool 99305019 (1), regrind the valve seats according to the angles shown in Figure 92.

After regrinding the valve seats, using tool 99370415 and dial gauge 99395603, check that the position of the valves in relation to the plane of the cylinder head is:

- □ -0.54 -0.85 mm (recessing) intake valves
- □ -1.75 -2.05 mm (recessing) exhaust valves.

Removal



To replace the injector case (2), act as follows:

□ Thread the case (2) with tool 99390804 (1).

Carry out operations described in figs. 94-97-98-99 by fixing tools to the cylinder head by means of bracket A.

1

2

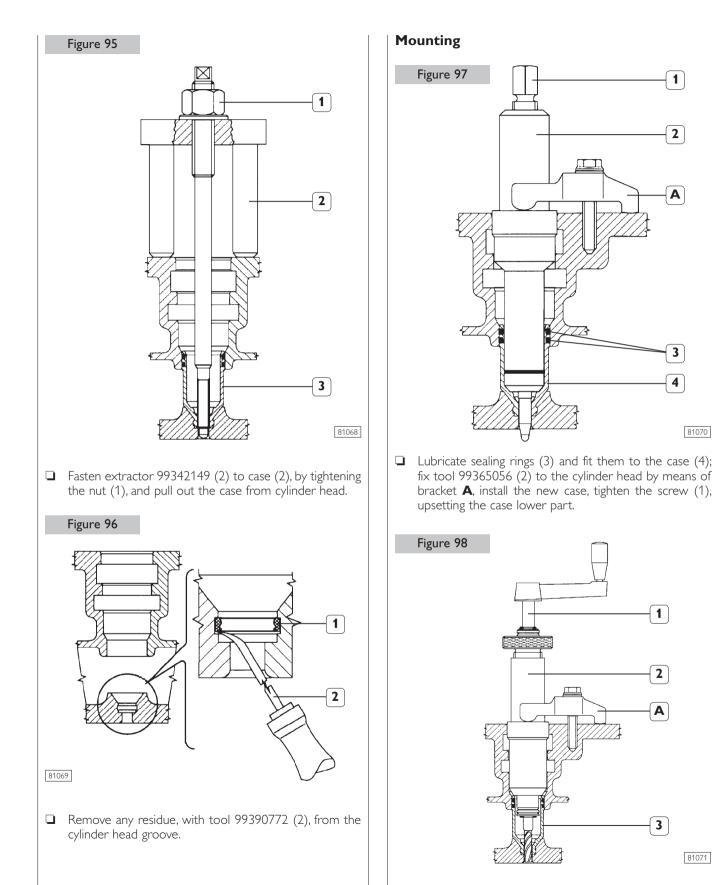
Α

3

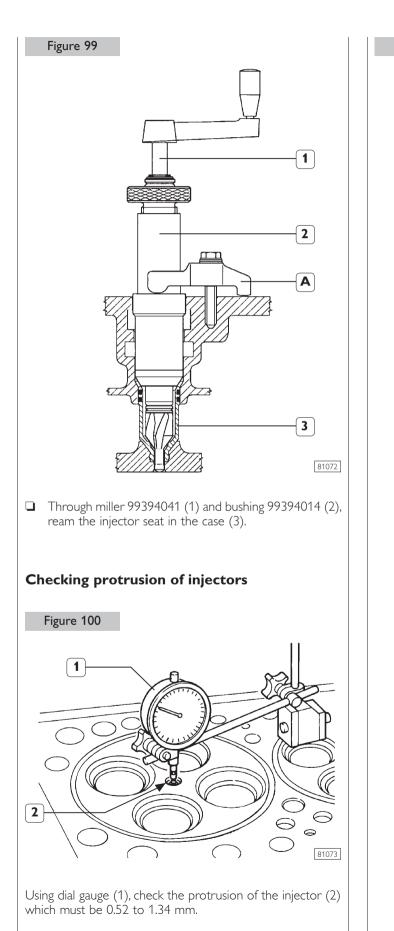
4

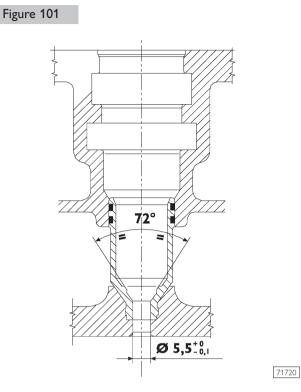
81070

81071



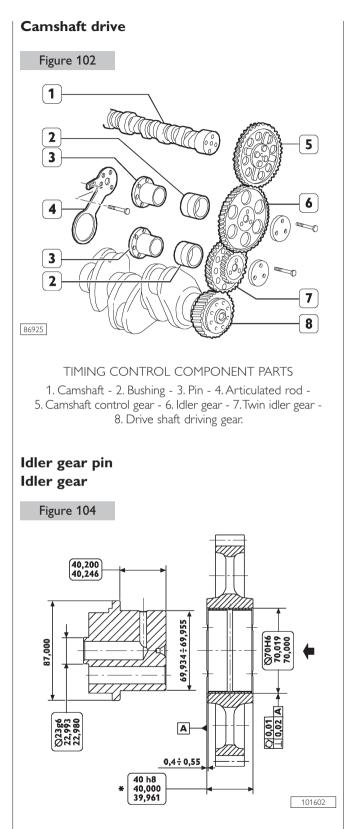
Adjust the casing hole (3) with borer 99394043 (1) and guide bushing 99394014 (2).



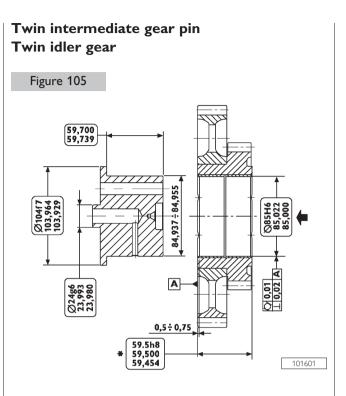


INSTALLATION DIAGRAM FOR INJECTOR CASE

TIMING GEAR



Rated assembling play between idler gear bushings and pins: 0.040 to 0.080 mm.



* This measurement is obtained after assembling.

Replacing the bushings

Bushings (2, Figure 102) can be replaced when they are worn. Put up the bushing, then bore it to obtain the diameter shown on Figure 104 or Figure 105.

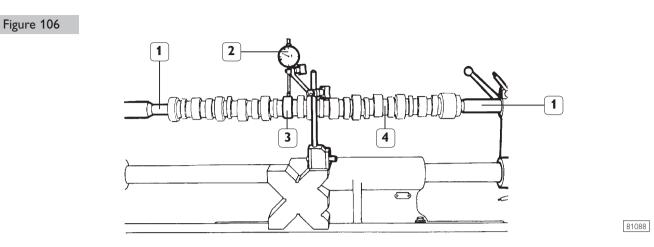
CAUTION

The bushing must be driven into the gear by following the direction of the arrow and setting the latter to the dimension shown on Figure 104 or Figure 105.

Rated assembling play between gear bushings and pins:

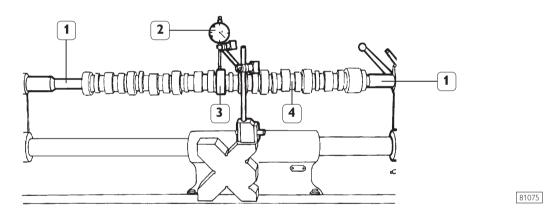
- Figure 104 0.045 to 0.085 mm
- Figure 105 0.045 to 0.085 mm.

Checking cam lift and pin alignment



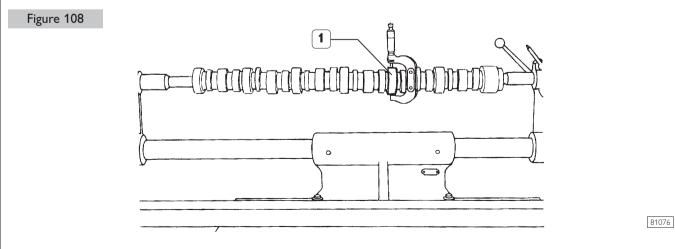
Place the camshaft (4) on the tailstock (1) and check cam lift (3) using a centesimal gauge (2); values are shown in table on page 133.

Figure 107



When the camshaft (4) is on the tailstock (1), check alignment of supporting pin (3) using a centesimal gauge (2); it must not exceed 0.030 mm.

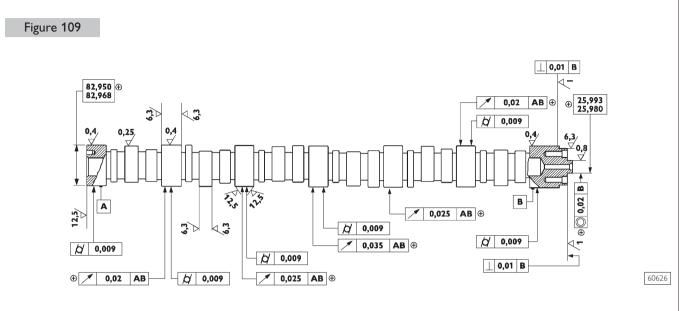
If misalignment exceeds this value, replace the shaft.



In order to check installation clearance, measure bush inner diameter and camshaft pin (1) diameter; the real clearance is obtained by their difference.

If clearance exceeds 0.150 mm, replace bushes and, if necessary, the camshaft.

Camshaft



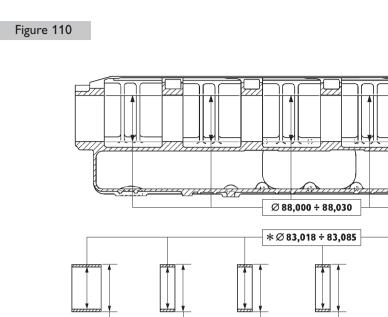
MAIN DATA - CAMSHAFT AND TOLERANCES

The surfaces of shaft supporting pin and cams must be extremely smooth; if you see any sign of seizing or scoring, replace the shaft and the relative bushes.

Tolerances	Tolerance characteristic	Symbol	
Orientation	Perpendicularity	Ţ	
Position	Concentricity or coaxial alignment	Ô	
Oscillation	Circular oscillation	1	
Importance class assigned to product characteristics		Symbol	
Critical		©	
Important		\oplus	
Secondary		\ominus	

/∕₽

BUSHES



60627

MAIN DATA - CAMSHAFT BUSHES AND RELATIVE BLOCK SEATS

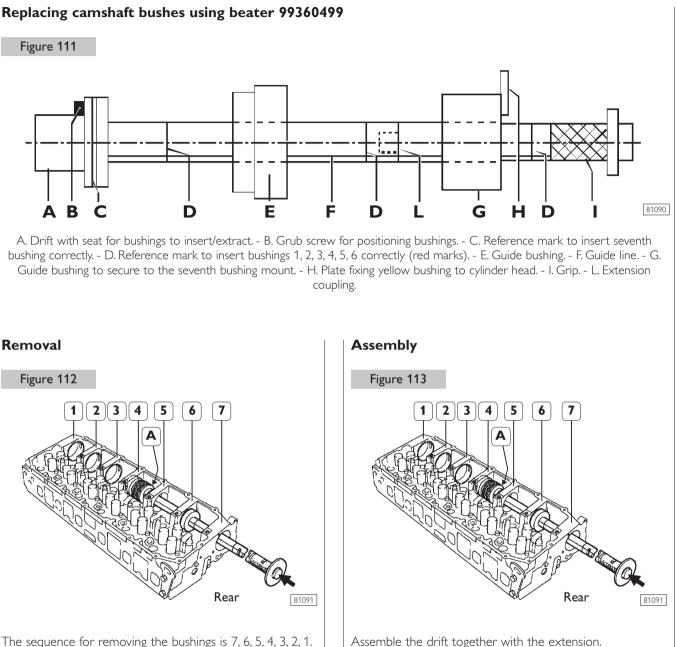
Ø 88,153 ÷ 88,183

₹**A**ZZZ

* Bush inner diameter after installation.

The bush surfaces must not show any sign of seizing or scoring; if they do replace them.

Measure the bush inner diameters with a baremeter and replace them, if the value measured exceeds the tolerance value. To take down and fit back the bushes, use the proper tool 99360499.



The sequence for removing the bushings is 7, 6, 5, 4, 3, 2, 1. The bushings are extracted from the front of the single seats.

Removal does not require the drift extension for bushings 5, 6 and 7 and it is not necessary to use the guide bushing. For bushings 1, 2, 3 and 4 it is necessary to use the extension and the guide bushings.

Position the drift accurately during the phase of removal.

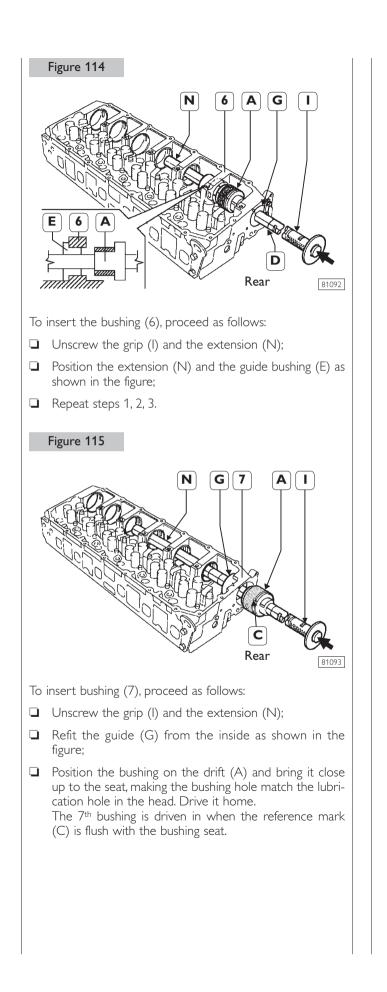
Position the bushing to insert on the drift (A) making the grub screw on it coincide with the seat (B) (Figure 111) on the bushing;

To insert bushings 1, 2, 3, 4 and 5, proceed as follows:

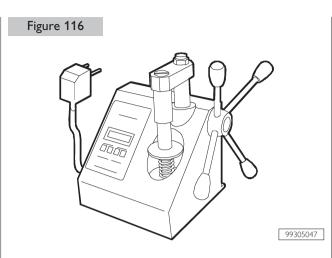
Position the guide bushing (E) and secure the guide bushing (G) (Figure 111) on the seat of the 7th bushing with the plate (H);

While driving in the bushing, make the reference mark (F) match the mark (M). In this way, when it is driven home, the lubrication hole on the bushing will coincide with the oil pipe in its seat.

The bushing is driven home when the 1^{st} red reference mark (D) is flush with the guide bushing (G).

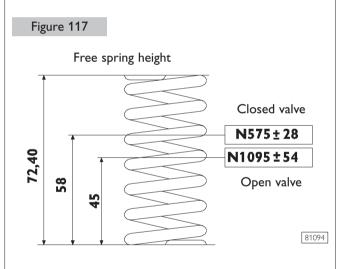


VALVE SPRINGS

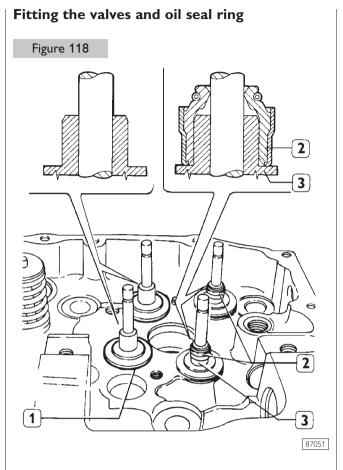


Before assembly, the flexibility of the valve springs has to be checked with the tool 99305047.

Compare the load and elastic deformation data with those of the new springs given in the following figure.

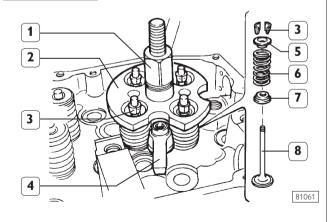


MAIN DATA TO CONTROL INTAKE AND EXHAUST VALVE SPRING



Lubricate the valve stem and insert the valves in the respective valve guides; fit the lower caps (1). Use tool 99360329 to fit the oil seal (2) on the valve guides (3) of the exhaust valves; then, to fit the valves, proceed as follows.

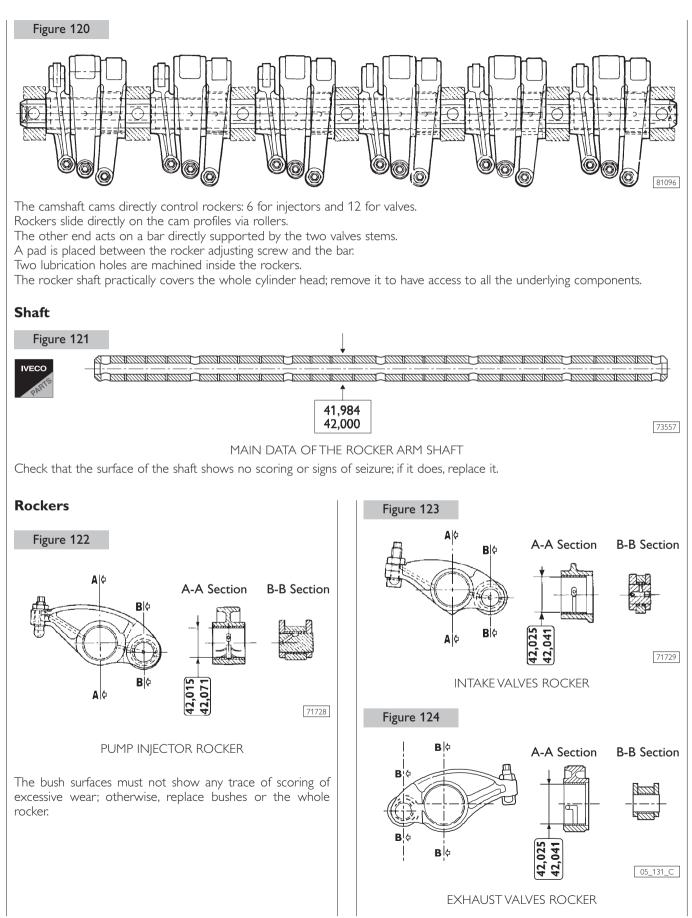
Figure 119



□ Fit springs (6) and the upper plate (5);

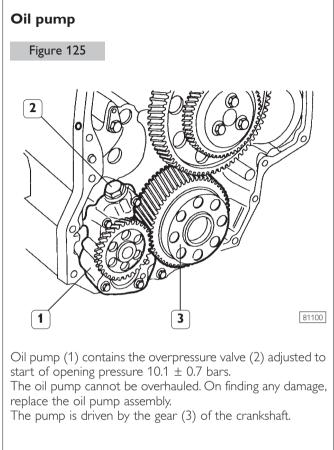
❑ Apply tool 99360263 (2) and block it with bracket (4); tighten the lever (1) until cotters are installed (3), remove tool (2).

ROCKER SHAFT

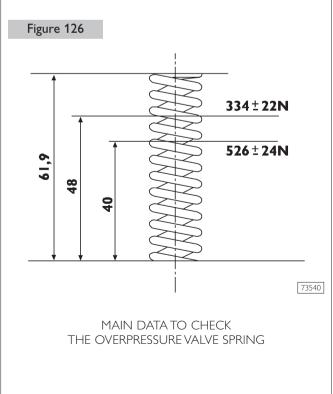


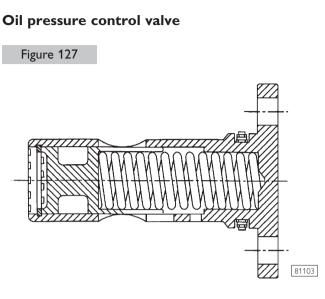
LUBRICATION SYSTEM COMPONENTS

Description and operation on Section 1.

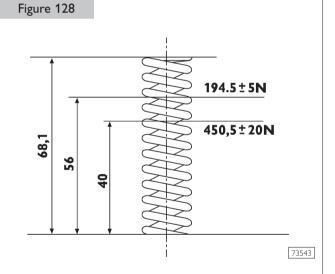


Overpressure valve



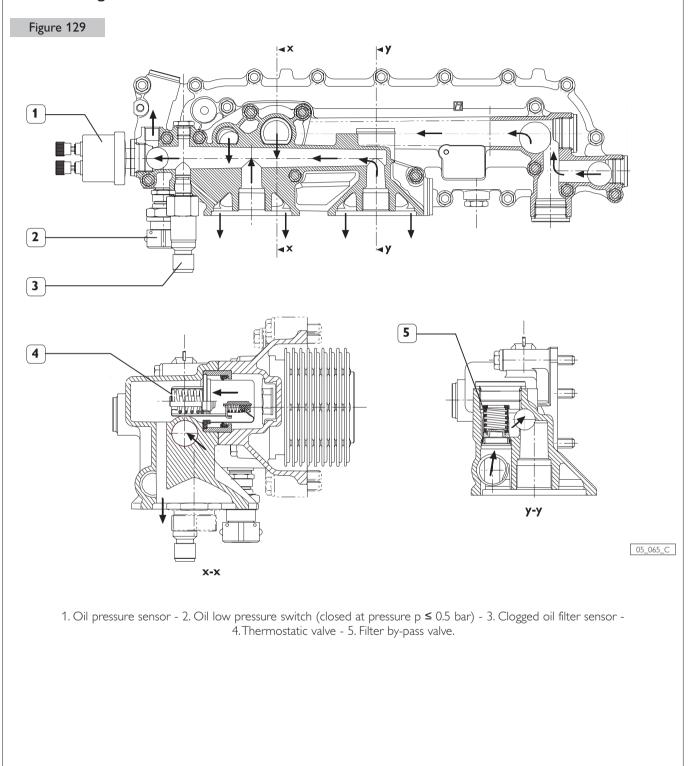


The oil pressure control valve is located on the left-hand side of the crankcase on the right side of oil heat exchanger. Start of opening pressure 5 bars.

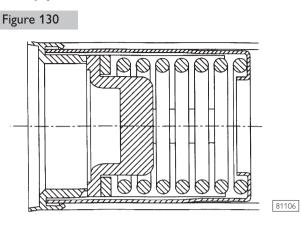




Heat exchanger

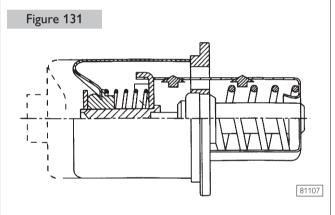


Filter by-pass valve



The valve assures the flow of lubricating oil to the engine even under heavily or totally clogged filter conditions and it is calibrated to start opening at a pressure of 3 bar.

Thermostatic valve



The valve allows the flow of low temperature oil within a direct channel to the outlet, thus avoiding heat transfers. In the presence of high temperature oil, the valve shuts the channel, switching the flow into the elements of the heat exchanger with the engine coolant, to stabilize its temperature. It is calibrated to start closing with a travel of 0.1 mm at a temperature of 82 \pm 2 °C and its total travel is 8 mm at the temperature of 97 °C.

Oil filter

When mounting the filters, keep to the following rules:

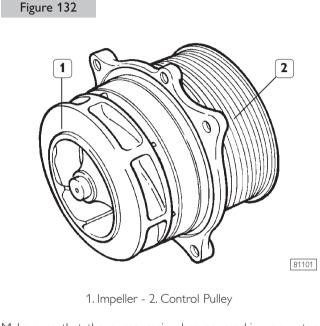
- Lubricate gasket with oil;
- □ Screw down the filters to bring the seals into contact with the supporting bases;
- □ Tighten the filter to a torque of 35 to 40 Nm.

COOLING SYSTEM COMPONENTS

Description and operation on Section 1.

Cooling by forced circulation obtained with centrifugal pump, driven by the drive shaft through a Poli-V belt. Liquid circulation is regulated by a thermostatic valve.

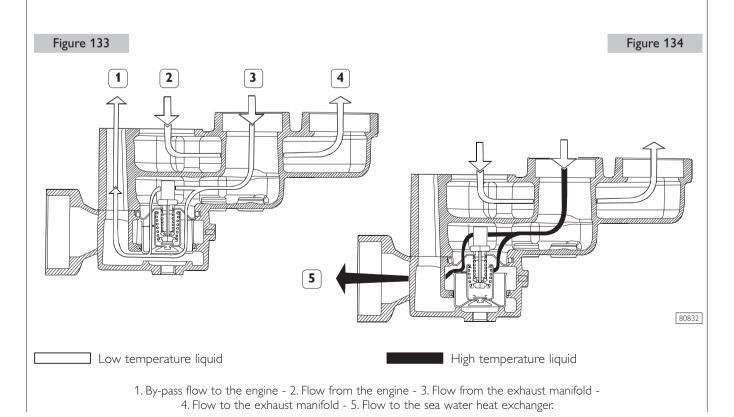
Water pump



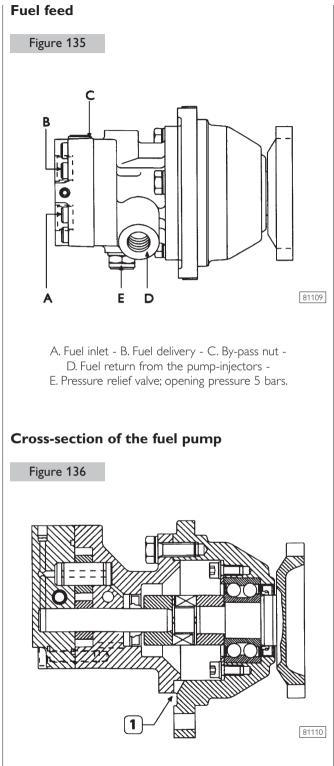
Make sure that the pump casing has no cracking or water leakage; otherwise, replace the entire pump.

Thermostatic valve

The valve is calibrated to start opening the channel to the sea water heat exchanger at a temperature of 68 ± 2 °C and to shut the channel to the coolant pump completely at the temperature of 78 ± 2 °C. Check the valve works properly; replace it if in doubt.

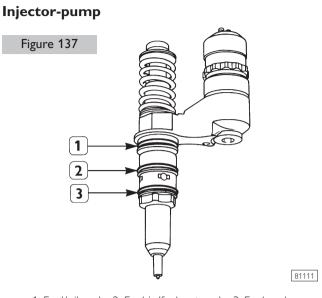


FUEL FEED COMPONENTS



1. Oil and fuel leakage indicator

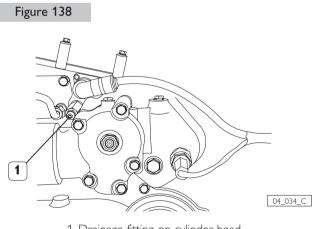
The seal rings are present on the fuel side and driving side. Any leakage will result in liquid spillage from the provided hole (1).



1. Fuel/oil seal - 2. Fuel in/fuel out seal - 3. Fuel seal.

CAUTION

The injectors require no calibration and because of the high level of precision of the components and the complexity of their assembly, none of their parts can be replaced. If replacement does become necessary, contact the IVECO MOTORS-FPT Technical Assistance Service to receive the appropriate operating instructions. Prescriptions for removal and re-assembly are provided in Section 6.

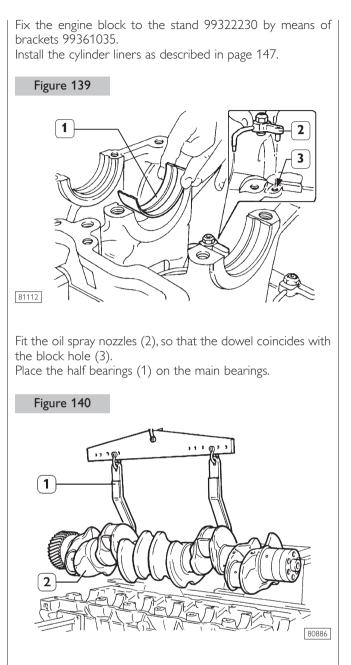


1. Drainage fitting on cylinder head

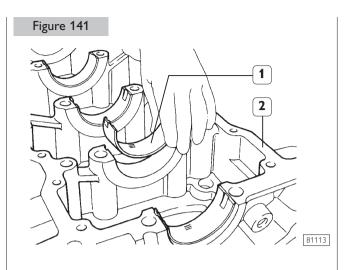
Before extracting the injector-pump, you must empty the fuel inflow and recirculation channels machined in the cylinder head, to prevent the liquid from dripping into the underlying combustion chamber machined in the piston crown. To do so, loosen the fuel inlet junction to the cylinder head and the drainage cap in the front part of the cylinder head (1). Avoid spilling fuel into the environment and contacts with the auxiliary organ belt.

For disassembly see Figures 21 to 24 of this Section. For assembly see Figures 170 to 175 of this Section.

ASSEMBLING THE ENGINE ON THE BENCH

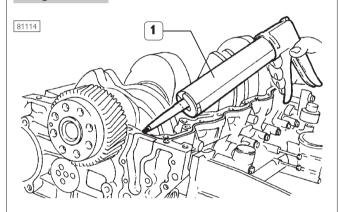


Lubricate the half bearings, then install the crankshaft (2) by means of hoist and hook 99360500 (1).

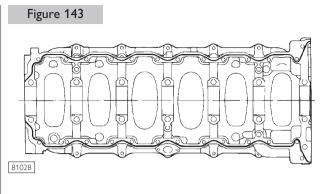


Place the half-bearings (1) on the main bearings in the underblock (2). Remove the underblock.

Figure 142



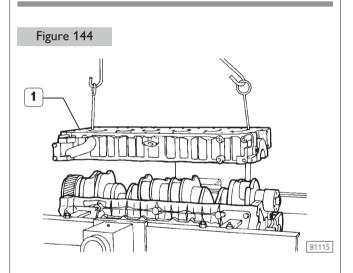
By means of suitable equipment (1), apply Loctite 5970 $\ensuremath{\mathsf{IVECO}}$ n. 2992644 sealant to the block, as shown in the figure.



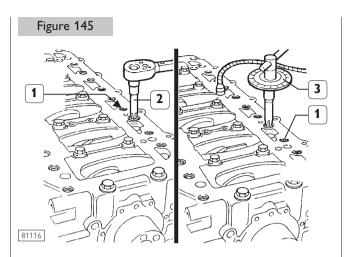
SEALANT APPLICATION DIAGRAM

CAUTION

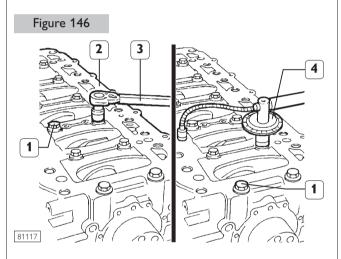
Fit the underblock within 10' since application of the sealant.



Fit the underblock by means of a suitable hoist and hooks (1).



Fit the underblock and, using a dynamometric wrench (2), close the splined outer (1) screws to 30 Nm torque, according to the diagram shown on next page.



Close the inner screws (1) to 120 Nm torque by means of a dynamometric wrench (3, Figure 146), then with two further angular phases $60^{\circ} +55^{\circ}$, using tool 99395216 (4). Tighten again the outer screws (1, Figure 145) with 60° angular closing, using tool 99395216 (3, Figure 145).

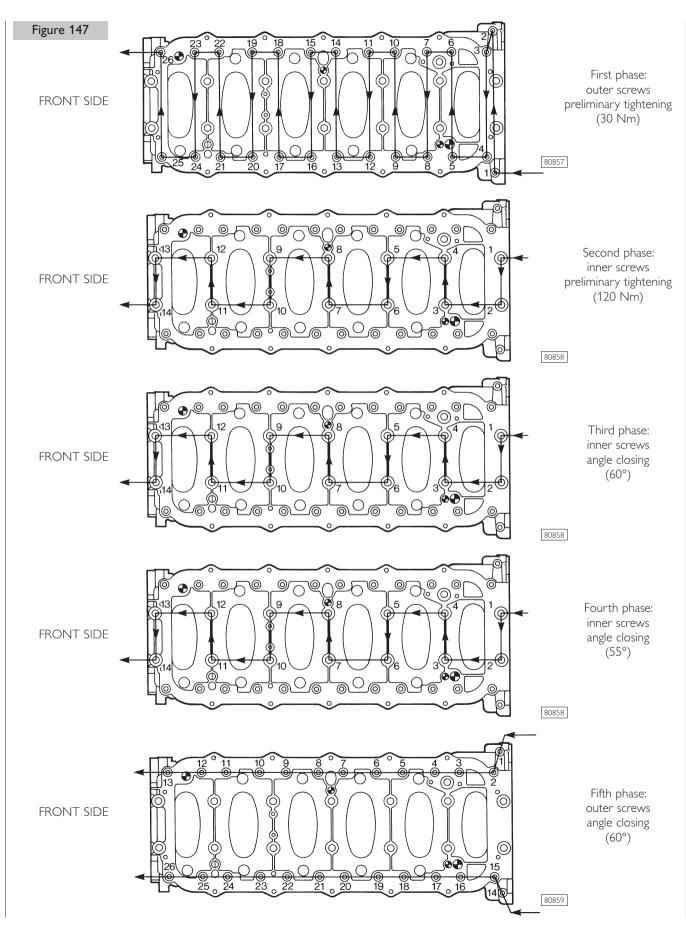
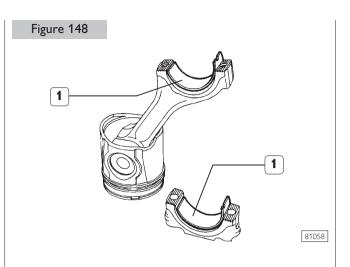
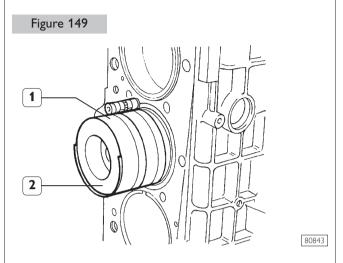


Diagram showing the underblock fixing screws tightening order



Rotate the cylinder assembly placing it vertically. Fit the half-bearings (1) on both the connecting rod and the cap. Fitting the connecting rod-piston assembly into the cylinder liners

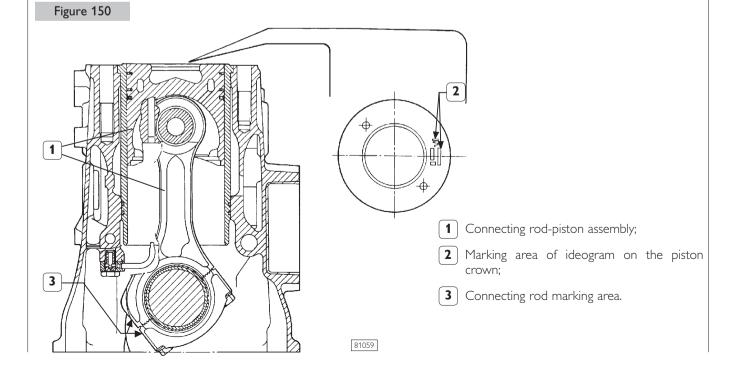


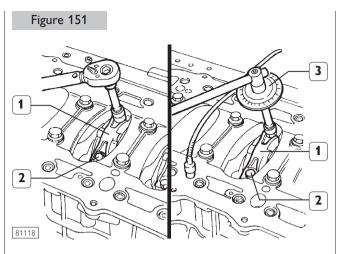
Fit the connecting rod-piston assemblies (2) into the piston liners, using the band 99360605 (1, Figure 149). Check the following:

- □ The openings of the split rings are offset by 120°;
- All pistons belong to the same class, A or B;
- □ Ideogram (2, Figure 150), stamped on the piston crown, is placed toward the engine flywheel, or the cavity located on the piston skirt corresponds to the position of the oil spray nozzles.

Piston protrusion check

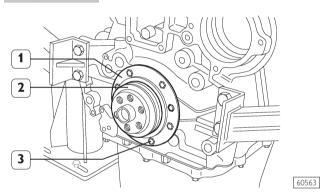
Once assembly is complete, check piston protrusion from cylinder barrels: it must be 0.12 to 0.42 mm.



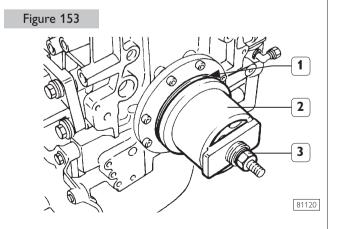


Connect the connecting rods to the relative journals, fit the connection rod caps (1) with half bearings; tighten the fixing screws (2) of the connecting rod caps to 60 Nm torque (6 Kgm). Using tool 99395216 (3), further tighten screws with 60° angle.

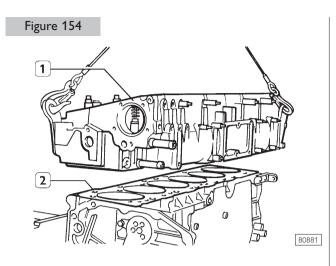
Figure 152



Using the centring ring 99396035 (2), check the exact position of the cover (1). If it is wrong, proceed accordingly and lock the screws (3).



Fit the sealing gasket (1), install the fitting tool 99346250 (2) and drive the sealing gasket (1) by screwing nut (3).



Make sure that pistons 1-6 are exactly at the TDC. Place the sealing gasket (2) on the block.

Fit the cylinder head (1) and tighten screws as shown in figs. 155, 156 and 157.

Figure 155

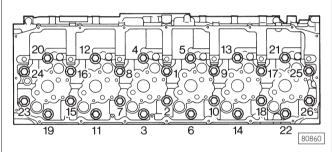
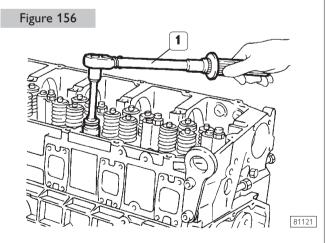


Diagram showing the cylinder head fixing screws tightening order.



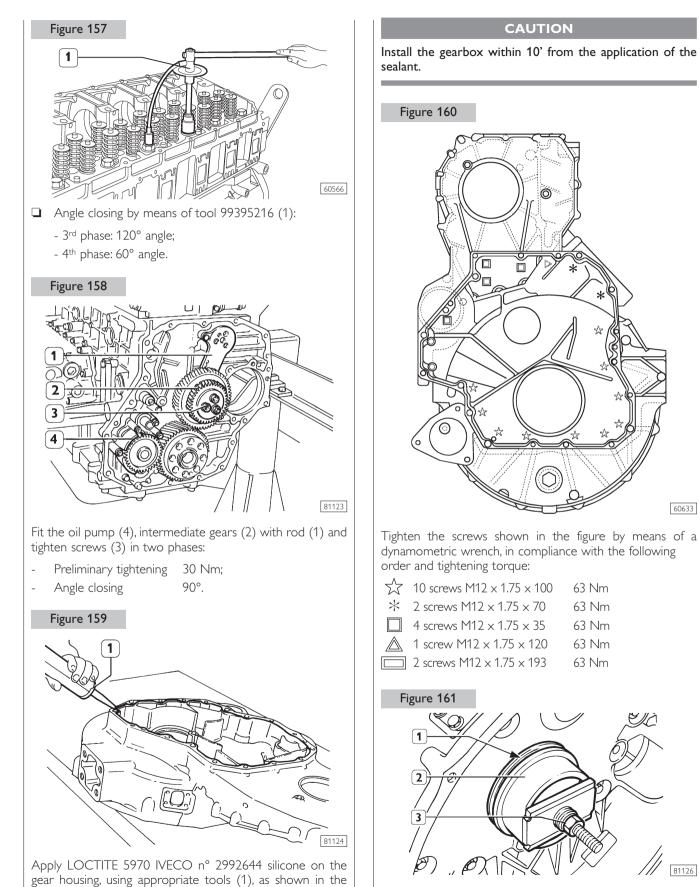
- Preliminary tightening by means of a dynamometric wrench (1):
 - 1st phase: 60 Nm (6 Kgm);
 - 2nd phase: 120 Nm (12 Kgm).

figure.

The sealer string (1) diameter is to be 1.3 to 2 mm.

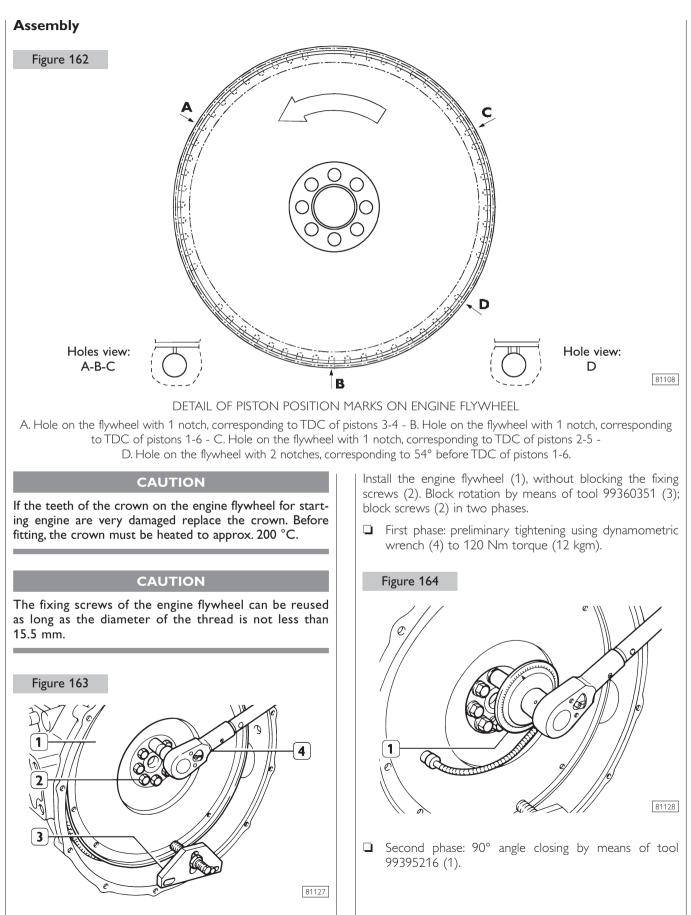
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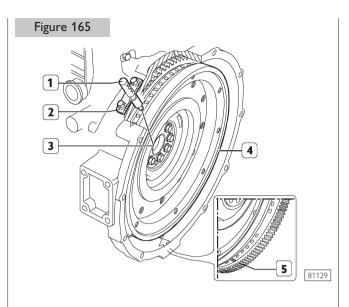


Fit the sealing gasket (1), install the fitting tool 99346251 (2) and drive the sealing gasket by screwing the nut (3).

ENGINE FLYWHEEL



FITTING CAMSHAFT



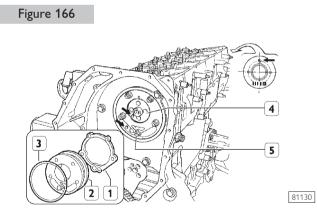
Position the crankshaft with the pistons 1 and 6 at the top dead centre (TDC).

This situation occurs when:

- The hole with reference mark (5) of the engine flywheel (4) can be seen through the inspection window;
- 2. The tool 99360612 (1), through the seat (2) of the engine speed sensor, enters the hole (3) in the engine flywheel (4).

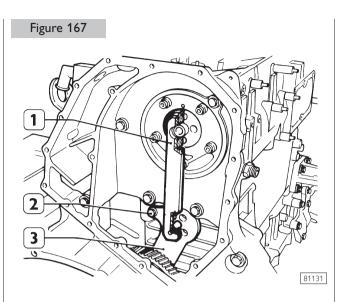
If this condition does not occur, turn the engine flywheel (4) appropriately.

Remove the tool 99360612 (1).



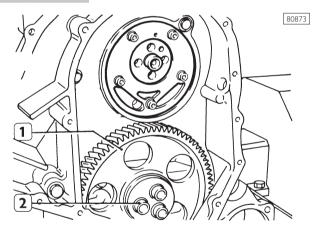
Fit the camshaft (4), positioning it observing the reference marks (\rightarrow) as shown in the figure.

Lubricate the seal (3) and fit it on the shoulder plate (2). Mount the shoulder plate (2) with the sheet metal gasket (1) and tighten the screws (5) to the required torque.

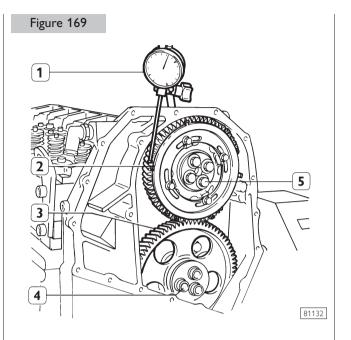


□ Apply gauge 99395219 (1), check and record the position of the rod (3) for the transmission gear; tighten the screw (2) to the prescribed torque.

Figure 168



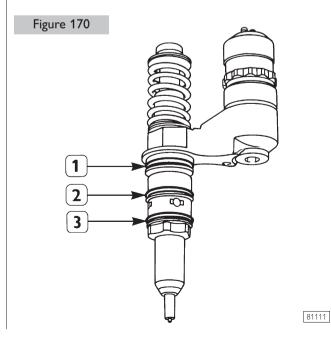
Remove the transmission gear (1) and tighten screws
 (2) by means of proper splined wrench.



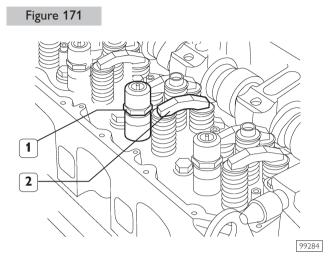
Fit back the gear (2), without fully tightening screws (5) on the camshaft and place it so that the 4 oval holes are centered with respect to the camshaft fixing holes. Using a magnetic gauge, make sure that the gear (2 and 3) clearance is 0.073 to 0.195 mm, otherwise adjust the clearance as follow:

- Untighten screws (4) fixing transmission gear (3);
- □ Untighten screw (2, figure 167) fixing the rod, move the rod (3, figure 167) to obtain the required clearance;
- □ Tighten the rod fixing screw (2, figure 167) as well as the screws (4, figure 169) fixing the gear to the prescribed torque.

EUI Assembly



Mount the seal rings (1) (2) (3) on the injectors. Grease the rings with Vaseline for easier correct positioning in their seats.

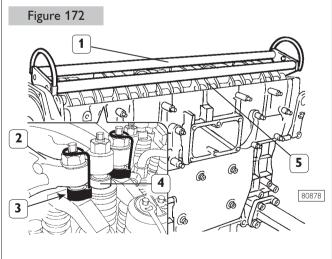


- Carefully position the injectors (1) into the seats and use a torque wrench to tighten the bracket screws at the torque of 26 Nm;
- □ Mount the braces (2) on the valve stems all oriented with the larger hole on the same side.

CAUTION

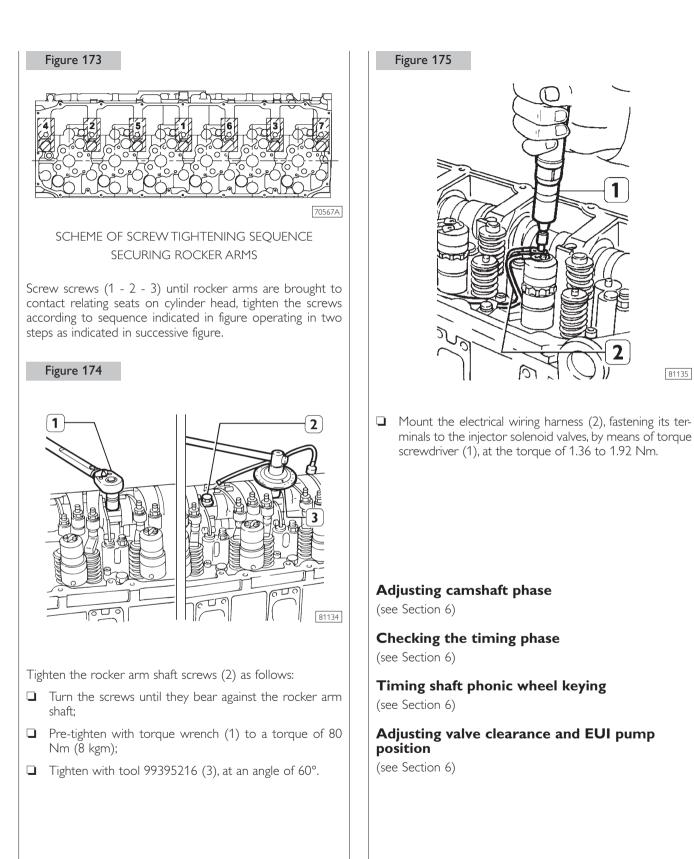
Before reassembling the rocker arm shaft assembly, ensure that all adjustment screws have been completely unscrewed.

Rocker arm shaft assembly

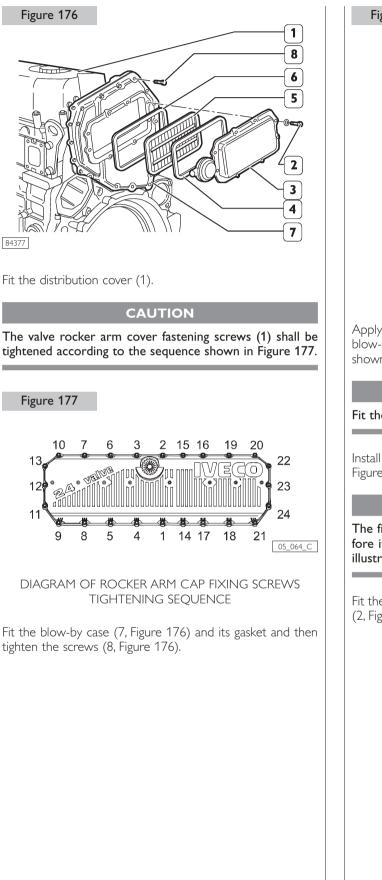


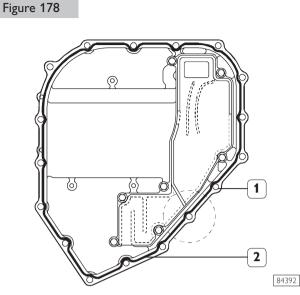
- □ Use the tool 99360144 (3) to fasten the blocks (4) to the rocker arms (2);
- Apply the tool 99360553 (1) to the rocker arm shaft (5) and mount the shaft on the cylinder head.

81135



ENGINE COMPLETION





Apply silicone Loctite 5970 IVECO No. 2992644 on the blow-by case and form a string (2) of \emptyset 1.3 to 2 mm, as shown in the figure.

CAUTION

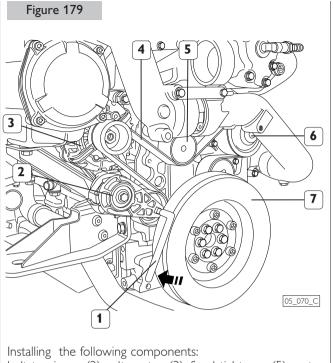
Fit the blow-by case (1) within 10' from sealer application.

Install the filter (5, Figure 176) and the gaskets (4 and 6, Figure 176).

CAUTION

The filter (5,Figure 176) operation is unidirectional, therefore it must be assembled with the two sight supports as illustrated in the figure.

Fit the cover (3, Figure 176) and tighten the fastening screws (2, Figure 176).



belt tensioner (2), alternator (3), fixed tightener (5), water pump (6), damping flywheel (7).

To install auxiliary organ drive belt (4), using the appropriate tool (1) loose the tensioner, as shown by arrow; insert the belt, verifying that it is correctly set onto the pulleys. Release the tensioner.

CAUTION

Automatic tensioners do not require further adjustments after the installation.

- □ Rotate the engine and install the oil rose pipe;
- Place the gasket on the oil sump, position the spacer and fit the sump to the engine block by tightening screws to the prescribed torque;
- Mount rockers lid tightening screws to the prescribed torque.

Remove the engine from the stand, fit the starter motor and the oil pressure adjuster valve (2, figure 10).

The operations described below can all be completed aboard the vessel.

If they take place at an overhaul center, secure the engine to an adequate support.

Install:

- $\hfill\square$ Sea water/engine coolant heat exchanger;
- □ Combustion air heat exchanger;
- Oil heat exchanger;
- Fuel pump;
- Fuel filter and piping;
- Intake manifold;
- Oil filter support and oil filters;
- Exhaust manifold;
- □ Turbocompressor and its oil and water piping;
- Oil level dipstick and oil vapor vent;
- □ Sensors, EDC unit and electrical connections.

Fill the engine with oil and coolant liquid quantity required.

SECTION 9

C13 ENS M33 ENGINE

	Page
SPECIFICATIONS	199
Dimensions	201
INJECTION SYSTEM - EDC	202
WIRE HARNESS	203
LOCATION OF ELECTRICAL COMPONENTS ON ENGINE	204
EDC SENSORS	205
Combustion air pressure/temperature sensor	205
Intake air sensor	205
Electrical equipment component code	206
Wiring diagram EDC connector A	208

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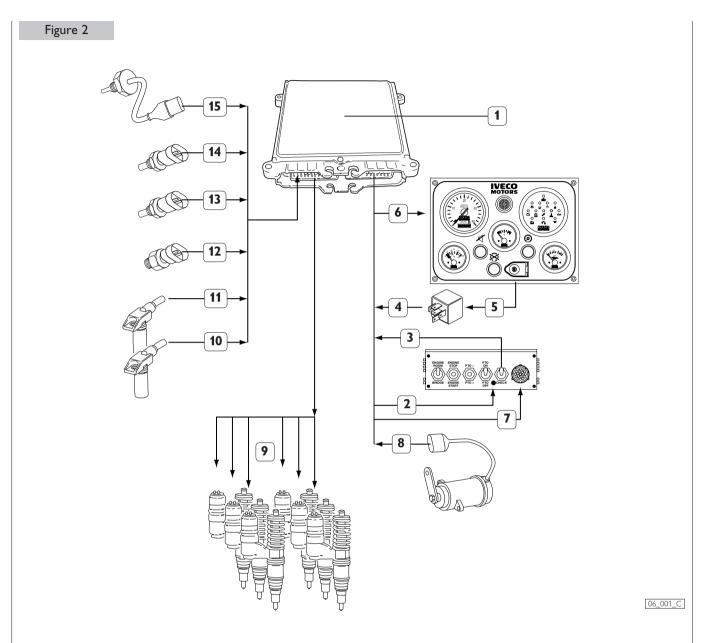
SPECIFICATIONS

Engine		C13 ENS M33
Cycle Charge Injection		4-Stroke Diesel Supercharged and intercooled Direct
Number of cylinders		6 in line
Bore	mm	135
Stroke	mm	150
Total displacement	cm ³	12880
Compression ratio		16.5 ± 0.8 to 1
Direction of rotation, flywheel side		counterclockwise
Minimum idling rpm	rpm	600 ± 25
Maximum engine rpm, no load	rpm	2170 ± 25
Allowed engine inclination angles		
Maximum longitudinal in continuous operation (static + dynamic)	degrees/360	+ 20°
Maximum transverse in continuous operation(static + dynamic)	degrees/360	± 22° 30'
Longitudinal for oil level check with standard dipstick	degrees/360	0 to +10°
Supercharge		
Turbocompressor with water-cooled body	HOLSET	HE 55IM-B
Pressure regulation		with waste-gate
Waste-gate maximum opening pressure	bar	2.1 ± 0.1
Lubrication		
Oil	type	SAE 15 W 40/E 3
Oil compliant with specifications		ACEA E3 / API CF4 / MIL L2104E/F
Total oil capacity on first filling	liters (kg)	42 (38)
Total oil capacity with sump at minimum level	liters (kg)	29 (26.3)
Total oil capacity with sump at top level	liters (kg)	36 (32.7)
Oil pressure, warm engine, minimum idling rpm	bar	≥ 1.5
Oil pressure, warm engine, maximum rpm	bar	≥ 5
Maximum allowed temperature	°C	105
Oil dipstick valid for static inclination	degrees/360	0 to +10°
Fuel supply		
Fuel oil compliant with standard		EN 590
Low pressure transfer pump		gear pump
Flow rate at maximum rpm	kg/h	88
Fuel return flow rate to tank	kg/h	≤ 12
Filtering: pre filter	μm	36.5
Filtering: filter	μm	5

Engine		C13 ENS M33
Injection system		
Туре		pump - injectors (EUI)
System		Bosch EDC MS 6.2
Maximum injection pressure	bar	1600
Low temperature starting		
Allowed, without external aids, down to	°C	-15
With electrical heating of intake air (optional), down to	°C	-25
With additional external heater, down to	°C	-30
Cooling		
Closed coolant loop with sea water heat exchanger		50% mixture of water/Paraflu II or equiv. Compliant with SAE J 1034 specification
Total coolant quantity	liters	45
Engine-only capacity	liters	19.5
Expansion tank		standard
Forced circulation		centrifugal pump
Flow rate at maximum rpm	l/h	32400
Temperature regulation Initial opening	°C	with thermostatic valve 68 ± 2
Sea water line	°C	78 ± 2 forced circulation
Sea water pump Max. pump capacity	l/h	centrifugal self-priming 1800
	1/11	1000
Exhaust gas expulsion		
Optional		stack
Optional		riser
Electrical system		
Nominal voltage	Vcc	24
Self-regulated alternator:		22
Voltage Maximum current intensity	Vcc A	29 90
Electrical starter motor:	/ \	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
Nominal voltage	\vee	24
Absorbed electrical power	W	5500
Recommended batteries capacity	Ah	≥ 180
Current discharge at - 18 °C (SAE J 537)	A	≥ 1200

Engine		C13 ENS M33	3
Drive train coupling			
Flywheel diameter	mm (inches)	355 (14)	
Flywheel case	type	SAE 1	
Weights			
Without liquids and without gearbox	kg	1320	
Dimensions Figure 1	Sizes in mm (inches)	92 (439,05)	1040 (40,94)

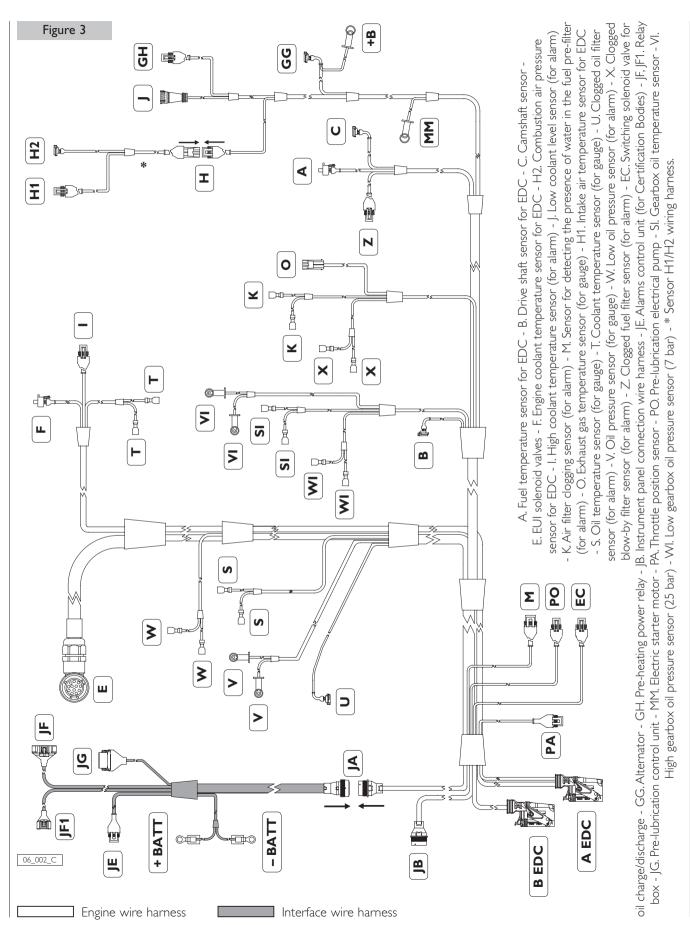
INJECTION SYSTEM - EDC (Electronic Diesel Control)



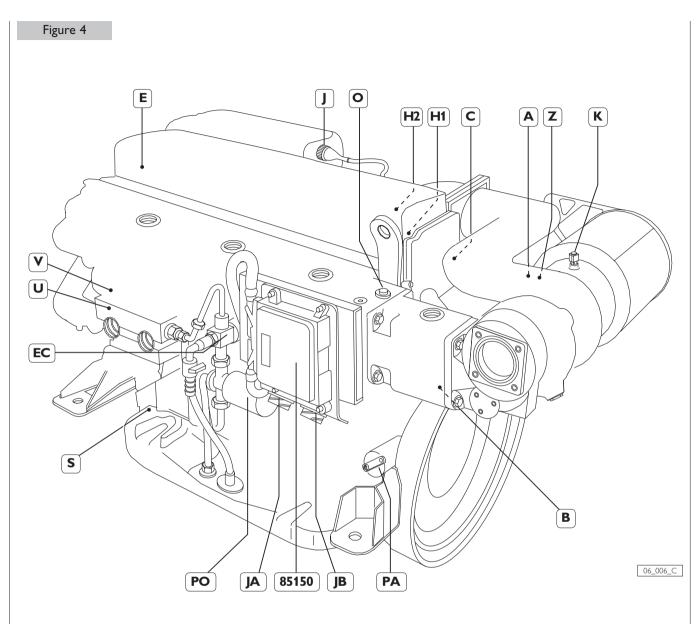
Central electronic unit ECU with atmospheric pressure sensor - 2. Fault indicator light - 3. Blink code request push-button Main relay - 5. Key control - 6. RPM Gauge - 7. Diagnostics connector - 8. Throttle position sensor - 9. Pumper injectors with electrical control, EUI - 10. Timing sensor - 11. Flywheel sensor - 12. Combustion air pressure sensor 13. Fuel temperature sensor - 14. Engine coolant temperature sensor - 15. Combustion air temperature sensor.

Due to the light supercharge pressure required, the C13 ENS M33 engine does not require the presence of the air/sea water heat exchanger. The electric system is common also to other engines of the same family, but the C78 ENS M20 engine is differentiated by the use of specific sensors for temperature and combusting air pressure. To connect these sensors to the engine wiring system it is necessary to use an extension cable connected to the H connector.

WIRE HARNESS

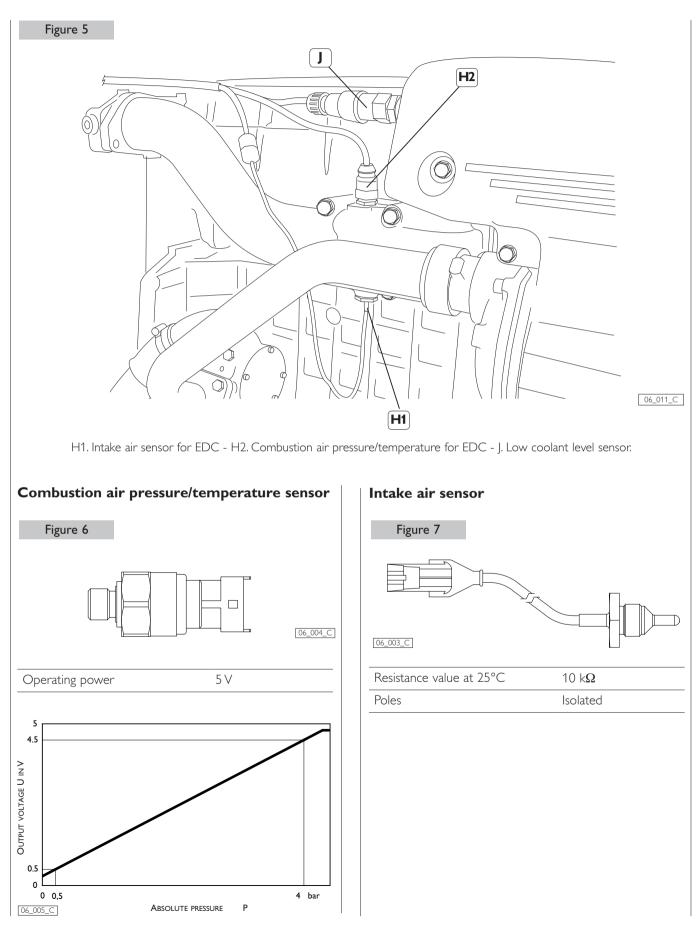


LOCATION OF ELECTRICAL COMPONENTS ON ENGINE



A. Fuel temperature sensor for EDC - B. Drive shaft sensor for EDC - C. Camshaft sensor - E. EUI solenoid valves - H2. Combustion air pressure sensor for EDC - J. Low coolant level sensor (for alarm) - K. Air filter clogging sensor (for alarm) - O. Exhaust gas temperature sensor (for gauge) - H1. Intake air temperature sensor for EDC - S. Oil temperature sensor (for gauge) - U. Clogged oil filter sensor (for alarm) - V. Oil pressure sensor (for gauge) - Z. Clogged fuel filter sensor (for alarm) - EC. Switching solenoid valve for oil charge/discharge - JA. Connection between engine wiring and interface wire harness - JB. Instrument panel connection wire harness - PA. Throttle position sensor - PO. Pre-lubrication electrical pump - 85150. EDC ECU.

EDC SENSORS



Electrical equipment component code

A	fuel temperature sensor for EDC
AC	battery
AQ	engine shut-off push-button on main panel
AS	engine shut-off push-button on secondary panel
В	drive shaft sensor for EDC
C CA	camshaft sensor
CA	key switch
CS	engine start push-button on secondary panel
DL1	EDC fault indicator and blink code LED (on relay box panel)
EC	switching solenoid valve for oil charge/discharge
F	engine coolant temperature sensor for EDC
GG	alternator
GH	power relay for starting aid
H2	combustion air pressure sensor for EDC
	high coolant temperature sensor (for alarm)
IN	injectors solenoid valve
J	low coolant level sensor (for alarm)
K	air filter clogging sensor (for alarm)
L	instrument panel light switch
Μ	sensor for detecting the presence of water in the fuel pre-filter (for alarm)
MC	CAN - BUS converter module for digital panel
MM	electric starter motor
MP	pre-lubrication and oil transfer module
MS	IVECO MOTORS-FPT indications and alarms module
0	exhaust gas temperature sensor (for gauge)
H1	intake air temperature sensor for EDC
P1	sound alarm inhibition push-button
PA	throttle position sensor
PE	emergency shut-down push-button (optional, installer's responsibility)
PH	grid heater
	pre-lubrication electrical pump

QP	main analog instrument panel
QS	secondary analog instrument panel
R1	3.3 k $\mathbf{\Omega}$ resistor to inhibit speed input
R2	DL1 resistor
R3	alternator pre-excitation resistor
S	oil temperature sensor (for gauge)
SA	buzzer
SI	gearbox oil temperature sensor
SW1	bridge or engine room engine control selector (on relay box panel)
SW2	start and stop push button (on relay box panel)
SW3	manual accelerator throttle control in engine room (on relay box panel)
SW4	PTO ON/PTO OFF selector (on relay box panel)
SW5	blink code emission request push-button (on relay box panel)
Т	coolant temperature sensor (for gauge)
U	Clogged oil filter sensor (for alarm)
V	oil pressure sensor (for gauge)
VI	high gearbox oil pressure sensor (25 bar)
W	low oil pressure sensor (for alarm)
WI	low gearbox oil pressure sensor (7 bar)
X	clogged blow-by filter sensor (for alarm)
Z	clogged fuel filter sensor (for alarm)
85150	ECU of the EDC system

(continues on next page)

9.207

Electrical equipment component code (cont.)

Connectors

A	35 pole EDC boat components
<u></u> В	35 pole EDC engine components
<u>Б</u> Е	
<u>–</u> Н	EUI injectors solenoid valve
	sensor H1/H2 wiring harness
J1	external diagnostic tool (on the relay box panel)
JA	connection between engine wiring and interface wire harness
JA on	SECONDARY DIGITAL INSTRUMENT PANEL set for connection to the main digital instrument panel
JB on e	ENGINE WIRE HARNESS set for connection to the main analog instrument panel or to the interface wire harness for converter module
JC ON	MAIN ANALOG INSTRUMENT PANEL set for connection to the engine wire harness
JD	IVECO MOTORS-FPT indications and alarms module
ID ON	INTERFACE WIRE HARNESS FOR CONVERTER MODULE
<u></u>	external throttle control
JE on M	external throttle control MAIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog
	external throttle control MAIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog instrument panel NTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the main digital instrument
	external throttle control MAIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog instrument panel NTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the main digital instrument panel MAIN DIGITAL INSTRUMENT PANEL set for connection to the secondary digital
	external throttle control MAIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog instrument panel NTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the main digital instrument panel MAIN DIGITAL INSTRUMENT PANEL set for connection to the secondary digital instrument panel MAIN INTERFACE WIRE HARNESS set for connection to the alarms control unit (fo
	external throttle control MAIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog instrument panel NTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the main digital instrument panel MAIN DIGITAL INSTRUMENT PANEL set for connection to the secondary digital instrument panel MAIN INTERFACE WIRE HARNESS set for connection to the alarms control unit (fo Certification Bodies) INTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the 2 nd main digital
	external throttle control MAIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog instrument panel NTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the main digital instrument panel MAIN DIGITAL INSTRUMENT PANEL set for connection to the secondary digital instrument panel MAIN INTERFACE WIRE HARNESS set for connection to the alarms control unit (fo Certification Bodies) INTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the 2 nd main digital instrument panel
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JE ON I JE ON I JE ON I JE ON I JE ON I JE1 ON JF JF JG	external throttle control MAIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog instrument panel NTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the main digital instrument panel MAIN DIGITAL INSTRUMENT PANEL set for connection to the secondary digital instrument panel MAIN INTERFACE WIRE HARNESS set for connection to the alarms control unit (fo Certification Bodies) INTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the 2 nd main digital instrument panel relay box relay box
JE ON I JE ON I JE ON I JE ON I JE ON I JE ON I JE ON I	external throttle control MAIN ANALOG INSTRUMENT PANEL set for connection to the secondary analog instrument panel NTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the main digital instrument panel MAIN DIGITAL INSTRUMENT PANEL set for connection to the secondary digital instrument panel MAIN INTERFACE WIRE HARNESS set for connection to the alarms control unit (fo Certification Bodies) INTERFACE WIRE HARNESS FOR CONVERTER MODULE set for connection to the 2 nd main digital instrument panel relay box pre-lubrication control unit SECONDARY ANALOG INSTRUMENT PANEL set for connection to the main analog

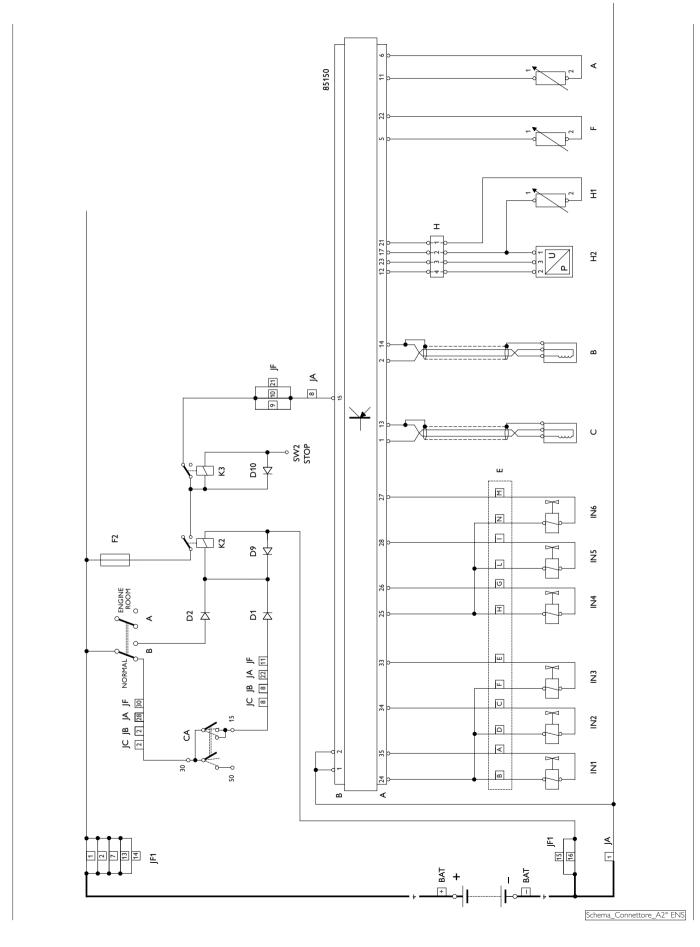
EDC	EDC malfunction
SAC	presence of water in fuel pre-filter
SATA	coolant high temperature
SBLA	low coolant level
SBPO	low oil pressure
SCP	pre-post heating
SIFA	clogged air filter
SIFB	clogged oil vapor filter
SIFC	clogged fuel filter
SIFO	clogged oil filter
SIM	expired programmed maintenance interval
SP	pre-lubrication
SS	alternator fault
SSV	overspeed engine
Gauges	
CG	revolution-counter
MI	gearbox oil pressure
MO	engine oil pressure
TA	engine temperature
TI	gearbox oil temperature
TS	exhaust gas temperature
V	voltmeter
Relays o	contained in the relay box
K1	EDC main (power supply
K2	key switch electric discharge
1/2	

K2	key switch electric discharge
K3	emergency engine shut-down provision
K4	enabling start engine from engine room
K5	power supply to terminal 50 of the electric starter motor
K6	cranking exclusion when engine is running

Fuses contained in the relay box

F1, F2 self restoring (not replaceables)

Wiring diagram EDC connector A



SECTION 10

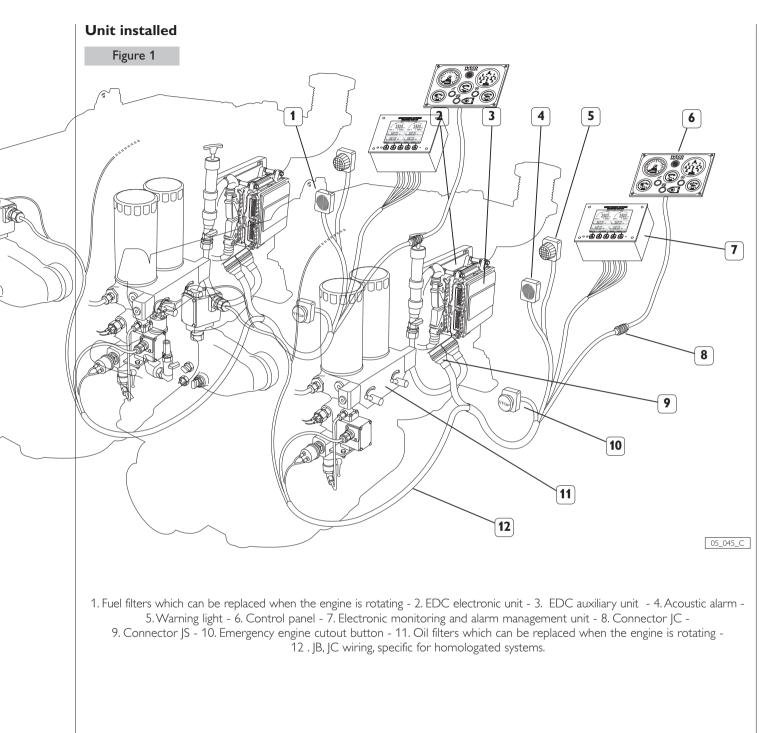
SAFETY SYSTEM FOR HOMOLOGATED INSTALLATIONS

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SAFETY SYSTEM FOR HOMOLOGATED INSTALLATIONS



The electric and electronic equipment of engines requiring a conformity declaration issued by the Certifying bodies comprises, in addition to that provided for the standard configuration, a series of components for the measurement, processing and recording of engine operating parameters. The aim of the system is to emit acoustic and optic alarms indicating that set limits have been exceeded. These limits will be programmed in accordance with different homologation requirements and may, when necessary, cut-out the engine in an emergency.

The system is made up of an electronic unit for the acquisition, display and recording of events occurring while the engine is running, using a series of sensors for this specific purpose; the alarm signals produced by the Unit will be emitted by acoustic and optic alarms installed by the Yard or by the Fitter. For boats equipped with only one engine, to offer a higher level of safety during navigation, it is necessary to install a second auxiliary EDC unit alongside the EDC engine controlling electronic unit to enable rapid replacement in the event of a failure. **Electronic monitoring unit**

Figure 2

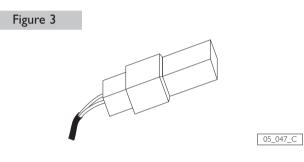
This unit monitors the operation of the specific safety system. With its computerised logic it acquires the electric signals issued by the sensors linked up to it, converting them into physical parameters of temperature, pressures and revs. This data is displayed on the liquid crystal display and processed according to the set parameters to draw attention to any approach towards the critical limits programmed and alarms should these limits be exceeded. Equipped with a built-in clock/calendar function, it is able to record and memorise the last 1000 alarms issued and the values of about 1000 samples of signals from sensors. It also issues electric signals to activate the acoustic and luminous alarm signals as requested by the homologation standards.

Sensors

Some sensors produce electric signals with a value proportionate to their physical entity

(temperature, pressure or rev. speed), allowing the electronic unit to monitor the engine operation to measure tendencies to approach the critical values; others indicate, with commutation by an electric switch, that a set pressure or temperature limit has been exceeded, generating an immediate "alarm" signal.

Given the high level of safety required, many of the monitoring system sensors are connected exclusively to this system; this means that the engine equipment comprises several components to measure the same physical entity but dedicated to different systems. In order to obtain an effective control of the integrity of the wiring, there are several resistors, connected in series with or parallel to the connection lines of the main sensors, which are used to recognise the conditions of cut-out or short-circuit of the connectors. After installation it is best to check that these components are correctly connected to the wiring (Figure 10).



- Line balancing element -

In observance of the provisions of the certifying bodies, the system equipment includes the presence of solutions which make it possible to check the efficiency of the monitoring functions and measure the relative parameters. By way of example, there is a valve which cuts off the oil in the connection of the "Low oil pressure" (WA) sensor, in order to test the efficiency of the related function and an unused extension cable (BA1 – BA1U).

Wiring

The presence of the Safety system in question in the electrics of the boat requires the use of specific

wiring unlike standard wiring.

The connection of the monitoring unit and the components connected to it are made on the JB-JC wiring used for the connection of the main control panel to the engine wiring. The electric connection of the system devices is made using connectors. Every multipolar connector is polarised to prevent inversion and is dedicated to a particular function.

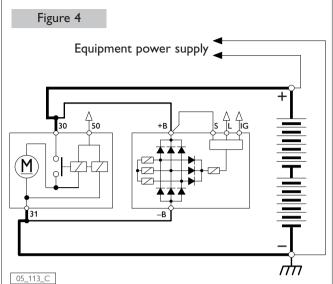
The electric diagrams, referred to the identification of the inputs/outputs of the connectors of the

monitoring unit may vary following the programming of particular features of the application.

CAUTION

To obtain the engine cut-out function by the JS monitoring unit it is necessary to unite the two JE connectors on the JB-JC wiring and the engine wiring.

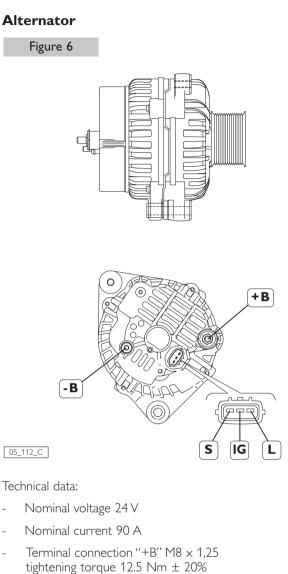
Insulated pole power network (optional)



The power network may be carried out in order to avoid using both the structure of engine and the structure of the hull (if this is metallic). For this purpose the electrical starting motor and the alternator required for this equipment are characterized by the presence of the terminals for electrical connections both with the positive and with the negative pole of the battery.

Electrical starting motor Figure 5 2 1 3 2 1 3 05_109_C _ 1. Excitation coil command (50) - 2. Positive power pole (+B) - 3. Negative supply pole (-BATT). Technical data: Nominal supply voltage 24 V _ _ Absorbed power 5 kW Terminal connection "50" M5 \times 0.8 _ tightening torque 2-2.5 Nm Terminal connection "+B" M10 x 1.5 _ tightening torque 14.7-17.7 Nm

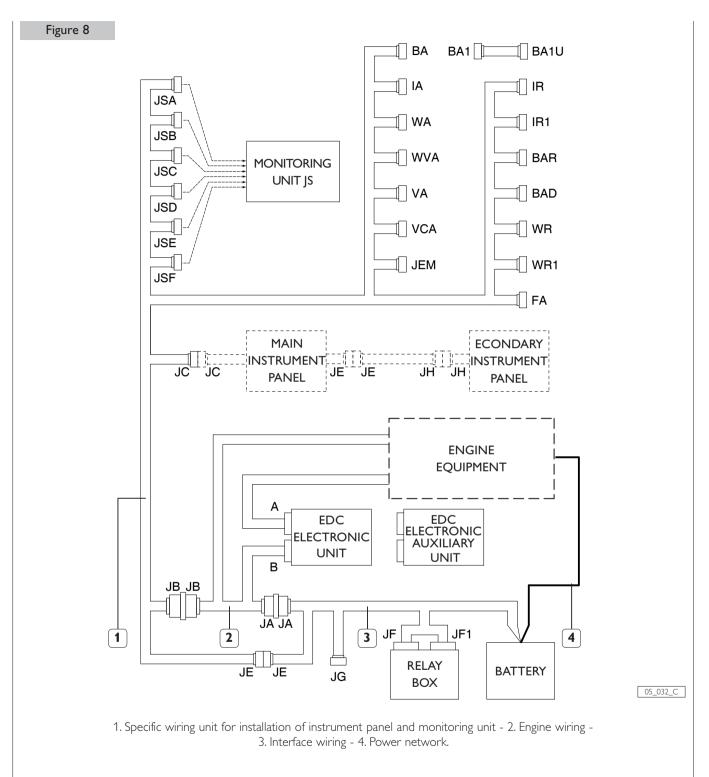
- Terminal connection "-BATT" M8 x 125 tightening torque 9.8-11.8 Nm



- Terminal connection ''–B'' M6 \times 1 tightening torque 6.0 Nm \pm 20%
- +B. (24 V) Power supply output terminal
- -B. (0 V) Power supply output terminal
- **S.** (Sense) Reference voltage of battery charge status (connected to +B terminal or to be connected to the positive pole of the battery in case of remote installation of the battery);
- IG. (Ignition) Regulator enabling signal (connected to voltage +, driven by key switch);
- L. (Lamp) Power supply voltage of recharge/alarm indicator light located on the panel.

Auxiliary EDC electronic unit This is fastened to the side of the unit in use to enable rapid replacement in the event of a failure. Should it be necessary to replace it, proceed as follows: □ stop the engine; u wait 10 seconds, then disconnect the terminal clamps from the battery; □ roceed as follows to extract and reinsert the connectors. Figure 7 R 80802A **REMOVING ECU CONNECTORS** 80802B INSERTING ECU CONNECTORS At the end of the operation: **u** reconnect the battery terminal clamps; □ start up the engine to run an efficiency test.

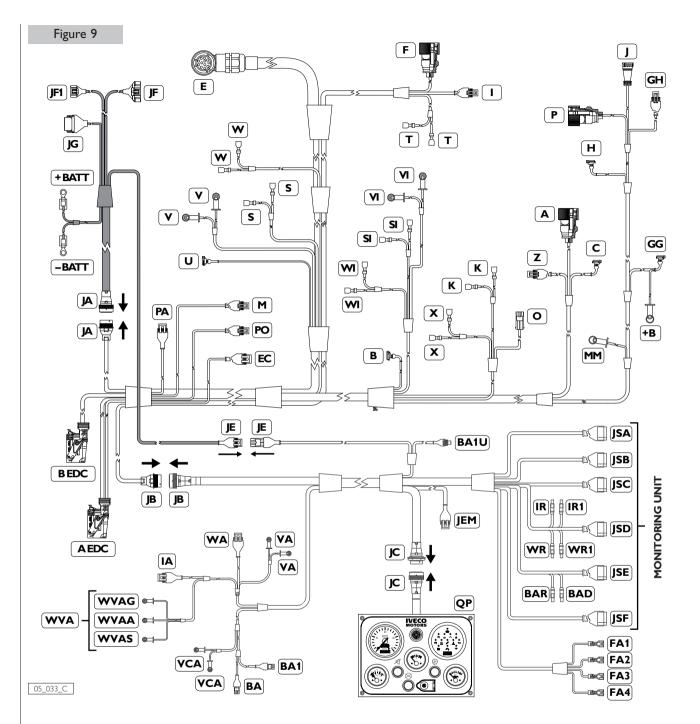
Synoptic



DESTINATION OF CONNECTORS OF THE SAFETY SYSTEM (excluding standard supply connectors)

BA. Drive shaft sensor - BAD. Diode for BA - BAR. Resistor for BA - BA1, BA1U. Connectors of the extension cable for engine rev. speed - FA. Acoustic and luminous alarms - IA. Coolant temperature sensor - IR. Parallel resistor for IA - IR1. Series resistor for IA - JE. Connector for cutting out agitated engine - JEM. Connector for cutout switches in the case of an emergency and motor cutout from the engine room - JS. Electronic monitoring unit - JSA, JSB, JSC, JSD, JSE, JSF. Connectors for monitoring unit - VA: Engine oil pressure sensor - VCA. Fuel pressure sensor - WA. Engine oil low pressure sensor - WR. Parallel resistor for WA - WR1. Series resistor for WA - WVA. Coolant pressure and low pressure sensor.

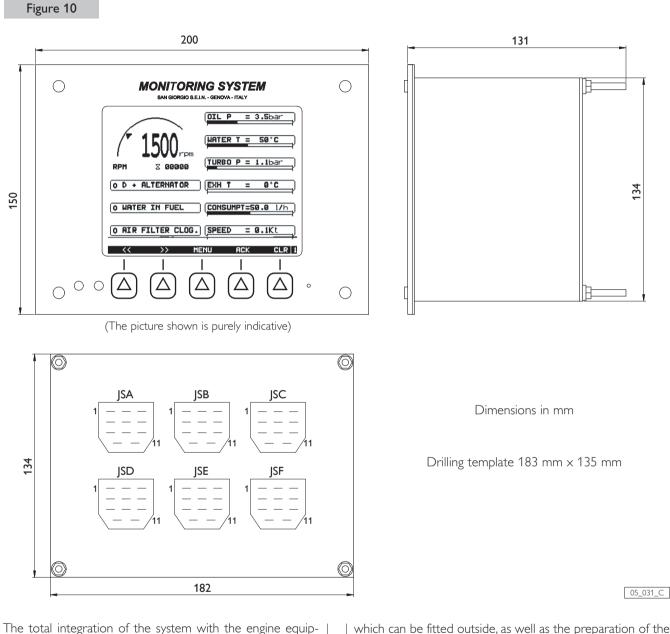
Wiring



DESTINATION OF CONNECTORS OF THE STANDARD ENGINE (excluding safety system connectors)

A. Fuel temperature sensor for EDC - B. Drive shaft sensor for EDC - C. Camshaft sensor - E. EUI solenoid valves F. Engine coolant temperature sensor for EDC - H. Combustion air pressure sensor for EDC - I. High coolant temperature J. Low coolant level sensor - K. Air filter clogging sensor - M. Sensor for detecting the presence of water in the fuel pre-filter O. Exhaust gas temperature sensor - P. Intake air temperature sensor for EDC - S. Oil temperature sensor - T. Coolant
temperature sensor - U. Clogged oil filter sensor - V. Oil pressure sensor - W. Low oil pressure sensor - X. Clogged blow-by
filter sensor - Z. Clogged fuel filter sensor - EC. Switching solenoid valve for oil charge/discharge - GG. Alternator GH. Pre-heating power relay - JA. Interface wiring - JB. Instrument panel connection wire harness - JE. Alarms control
unit (for Certification Bodies) - JF,JF1. Relay box - JG. Pre-lubrication control unit - MM. Electric starter motor - PA. Throttle
position sensor - PO. Pre-lubrication electrical pump - SI. Gear box oil temperature sensor - VI. High gear box oil pressure
sensor (25 bar) - WI. Low gear box oil pressure sensor (7 bar).

Monitoring unit



The total integration of the system with the engine equipment means that the installation procedures already listed for the standard version are joined by the placement of the electronic monitoring unit inside a console or dashboard, which can be fitted outside, as well as the preparation of the alarm management components pursuant to the homologation standard: acoustic and luminous signals, cut-out buttons.

GENERAL FEATURES AND REFERENCE STANDARDS

Power supply	12/24 V d.c.
Current absorption	500 mA (approx.)
Performances in compliance with *	R.I.N.A. "Regulation for automation systems" - Section E
Functional, climatic, vibration and EMC tests in accordance with *	IEC 945 "Maritime navigation and radio-communication equipment and system - General requirements - Methods of testing and required test results"
* The test reports are supplied by request	

Function of JS connection terminals

pin	JSA Thermocouples	JSB Supply	JSC CAN network
1	Exhaust fumes temperature	Supply 12/24 ∨ (+)	CAN (H)
2	-	Supply 12/24 V (+)	CAN (L)
3	-	Mass (-)	-
4	-	Mass (-)	-
5	Exhaust fumes temperature	-	GPS - NMEA 0183 ⁽²⁾ protocol
6	-	N.C. relay 1 - Acoustic signaling ⁽²⁾	Echo sounder - NMEA 0183 ⁽²⁾ protocol
7	-	Mass (-)	-
8	-	N.O. relay 1 - Acoustic signaling	-
9	-	N.C. relay 2 - light signal ⁽²⁾	GPS/Eco sounder ⁽²⁾ Mass (-)
10	-	Mass (-)	-
11	-	N.O. relay 2 - light signal	-

NOTE: one of the terminals of the following components is connected to the electric mass: VCA, WVA(G), VA, WA, BAD, IA, JE.

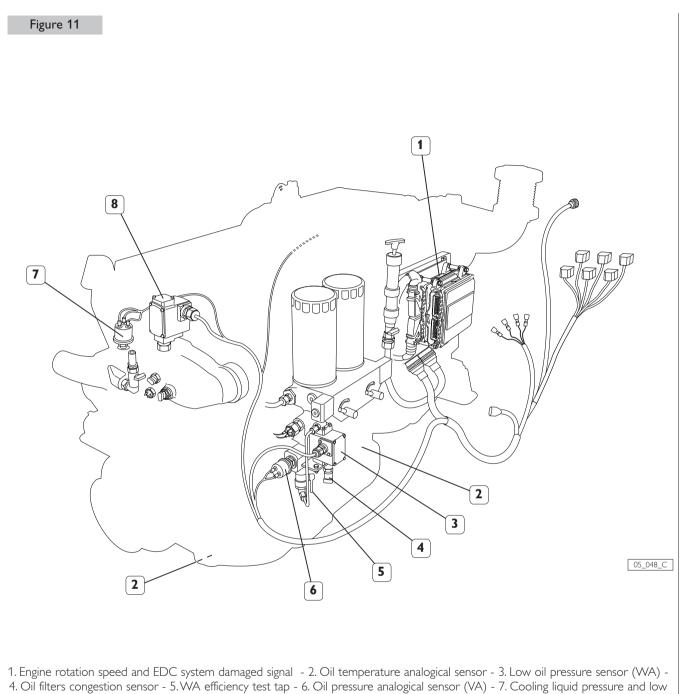
pin	JSD Sensors	JSE Signals	JSF Signals and alarms
1	Gear box oil pressure ⁽²⁾	Engine revs (EDC) ⁽¹⁾	N.C. Cut-out relay 3 ⁽²⁾
2	Coolant pressure (WVAS) ⁽¹⁾	Engine revs (BA) ⁽¹⁾	-
3	Engine oil pressure (VA) ⁽¹⁾	Low coolant level (J) ⁽¹⁾	12/24 V (+) common relay 3 stoppage
4	Sea water circuit pressure ⁽²⁾	Low gear box oil pressure ⁽²⁾	N.O. Cut-out relay 3 (JE) ⁽¹⁾
5	Engine oil temperature (S) ⁽¹⁾	Air filter blockage (K) ⁽¹⁾	Alternator recharge (L) ⁽¹⁾
6	Low engine oil pressure (WA) ⁽¹⁾	Low coolant pressure (WVAA) ⁽¹⁾	Pre-lubrication (opt.)
7	Water in the pre-filter (M) ⁽¹⁾	Fuel filter blockage (Z) ⁽¹⁾	Imp.Voltage signal 12/24 V (+)
8	Fuel pressure (VCA) ⁽¹⁾	Engine revs (BAR - BA) ⁽¹⁾	Engine stopping circuit damaged (JEM - JE) ⁽¹⁾
9	EDC (failure signal) ⁽¹⁾	-	-
10	High coolant temperature (IA) ⁽¹⁾	Oil filter blockage (U) ⁽¹⁾	-
11	Mass (-)	Engine cut-out (pin 4 JSF)	-

1) Code of the component or sensor to which the terminal is connected

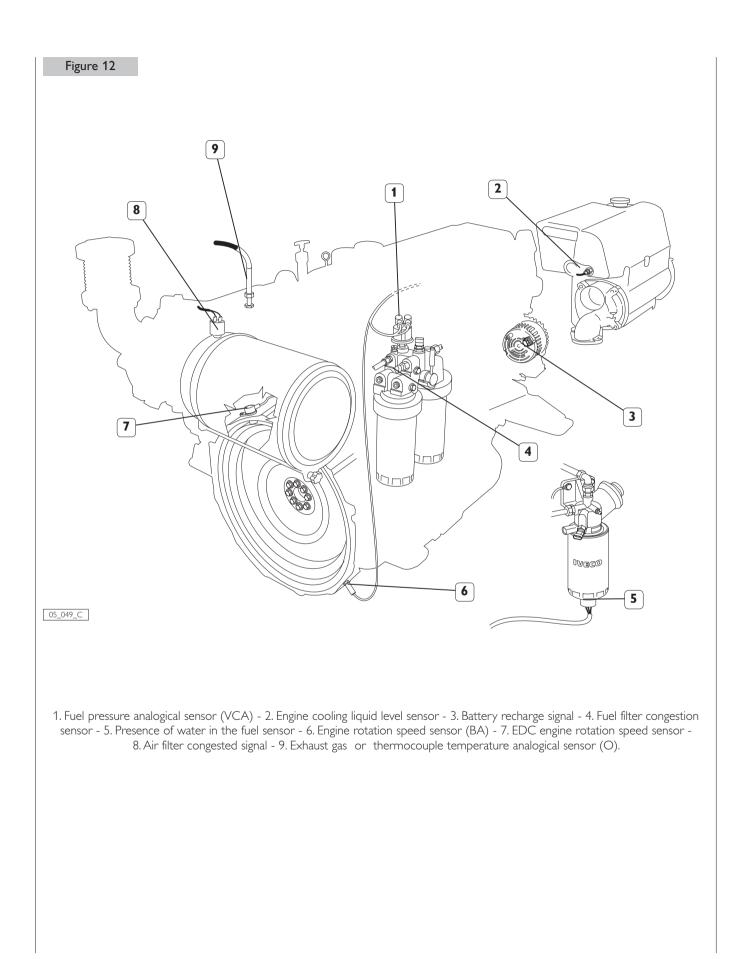
2) The terminal is prepared but not connected with the wiring.

CONNECTORS JS SEEN FROM WIRING SIDE

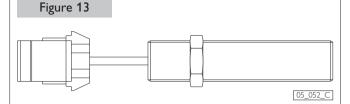
Position of the safety system sensors



pressure analogical sensor (WVA) - 8. Cooling liquid high temperature sensor (IA).



Drive shaft rev. speed sensor (BA)



This is of the inductive type and when the engine is running it produces a sinusoidal alternate signal the value of which increases in proportion to the engine rev. speed. The sensor BA enables the measurement of the engine rev- speed using the passage of the holes positioned in a radial arrangement on the outer circumference of the flywheel. The presence of the resistor BAR and the diode BAD can alter the value of the sensor resistance if measured on the JSE connector of the monitoring unit.

Resistance value at 20°C	$220 \pm 20 \ \Omega$
Poles	Isolated

Exhaust gas temperature sensor (O)



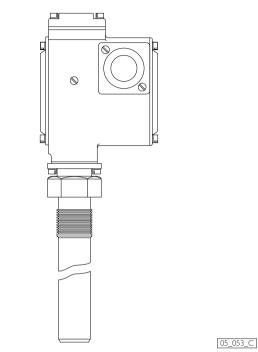


NiCr-Ni thermocouple sensor with insulated poles, providing the signal for the analog indication of exhaust gas temperature.

Temperature	Voltage
°C	mV
100	4,10
200	8,13
300	12,21
400	16,40
500	20,65
600	24,91
700	29,14
800	33,30
900	37,36

Coolant high temperature sensor (IA)

Figure 15



Thermometric switch which supplies the information for the engine high temperature alarm.

Operating power	from 6 V to 24V
Condition at ambient temperature	normally open
Commutation temperature:	°C
Poles	Isolated

Electric diagram:

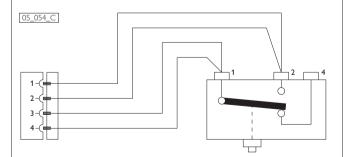


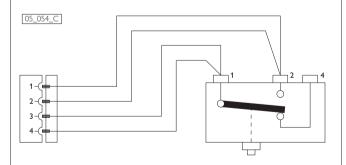
Figure 16

Engine oil low pressure sensor (WA)

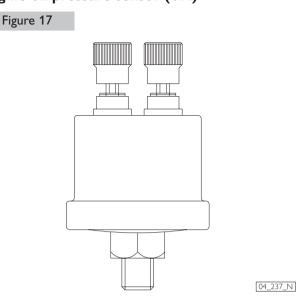
Switch activated by the fluid pressure, which supplies the information for the engine lubricant low pressure alarm.

Operating power	from 6V to 24V
Condition at ambient pressure	normally closed
Commutation pressure:	0,4/0,8/1,2 bar
Poles	Isolated

Electric diagram:



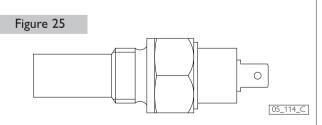
Engine oil pressure sensor (VA)



Component which supplies a rheostatic signal for the analogical indication of the fluid pressure.

Operating power	from 6 V to 24 V
Setting field from	0 bar to 10 bar
Resistance value at 0 bar	10 Ω +3/-5 Ω
Resistance value at 2 bar	52 ± 4 Ω
Resistance value at 4 bar	$88 \pm 4 \Omega$
Resistance value at 6 bar	124 ± 5 Ω
Maximum value of resistance	184 Ω
Operating temperature	from - 25°C to +100°C
Poles	Isolated

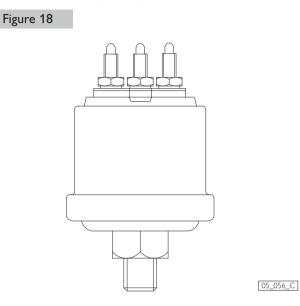
Coolant oil temperature sensor (S)



Resistor with negative temperature coefficient, providing the signal for analog temperature indication.

Operating voltage	6 V to 24 V
Calibration range	0°C to 120 °C
Resistance value at 90°C	51,2 ± 4,3 Ω
Poles	isolated

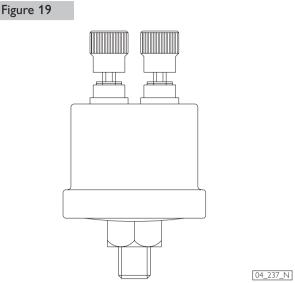
Refrigerating liquid pressure and low pressure sensor (WVA)



This integrates a component which supplies the rheostatic signal for the analogical indication of the pressure and a switch activated by the pressure which supplies the information for the engine coolant low pressure alarm.

Operating power	12/24 V
Rheostat	
Field of intervention	from 0 to 5 bar
Stamping of the terminals	M - G
Wiring terminals	WVAG - WVAS
Switch	
Condition at ambient pressure	normally open
Condition at ambient pressure	normally open
Closing pressure	≥ 0,25 bar
	, .

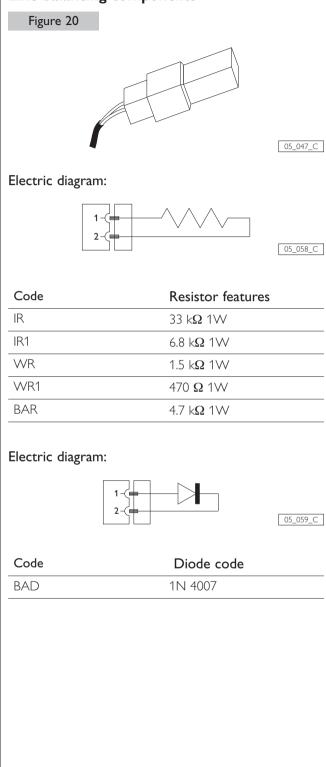
Fuel pressure sensor (VCA)

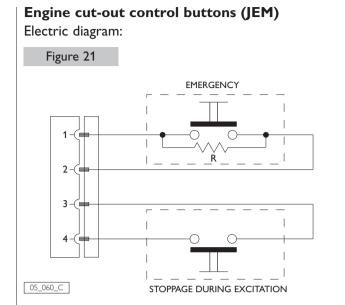


Component which supplies the rheostatic signal for the analogical indication of the fluid pressure.

Operating power	12/24 V
Field of intervention	from 0 bar to 10 bar
Poles	Isolated

Line balancing components





The balancing resistor R has a value of 10 k $\!\Omega.$

ELECTRICAL DIAGRAMS FROM THE SAFETY SYSTEM

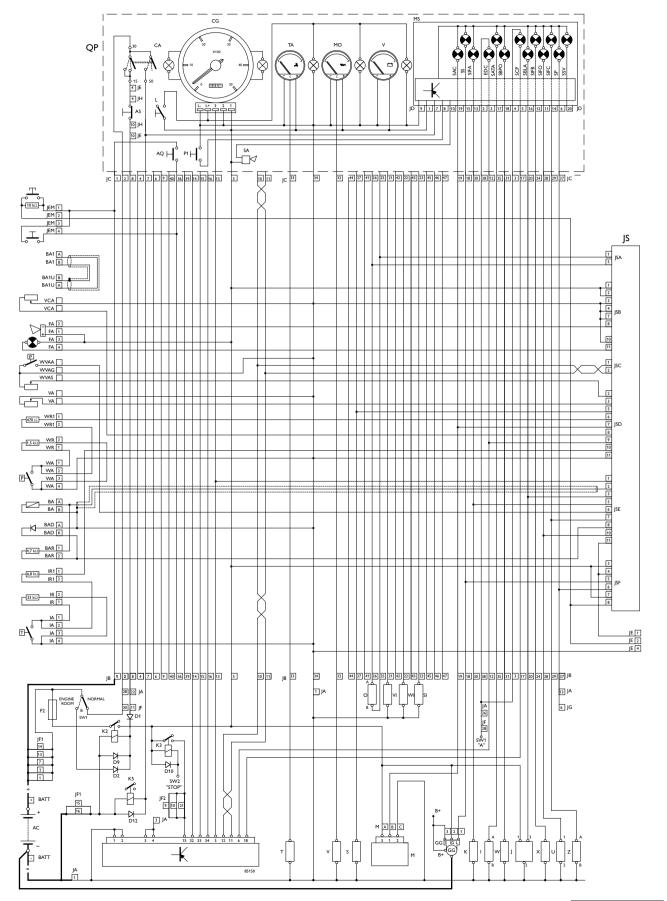
Ą	Fuel temperature sensor for EDC
3	Drive shaft sensor for EDC
2	Camshaft sensor
	EUI solenoid valves
:	Engine coolant temperature sensor for EDC
1	Combustion air pressure sensor for EDC
	High coolant temperature
	Low coolant level sensor
	Air filter clogging sensor
1	Sensor for detecting the presence of water in the fuel pre-filter
C	Exhaust gas temperature sensor
)	Intake air temperature sensor for EDC
	Oil temperature sensor
	Coolant temperature sensor
J	Clogged oil filter sensor
/	Oil pressure sensor
\sim	Low oil pressure sensor
<	Clogged blow-by filter sensor
7	Clogged fuel filter sensor
С	Switching solenoid valve for oil charge/discharge
GG	Alternator
GΗ	Pre-heating power relay
В	Instrument panel connection wire harness
Ξ	Alarms control unit (for Certification Bodies)
F, JF1	Relay box
G	Pre-lubrication control unit
ЧM	Electric starter motor
A	Throttle position sensor
0	Pre-lubrication electrical pump
	Gear box oil temperature sensor
′	High gear box oil pressure sensor (25 bar)
VI	Low gear box oil pressure sensor (7 bar)

Code of components of the safety system

BA Drive s	haft sensor
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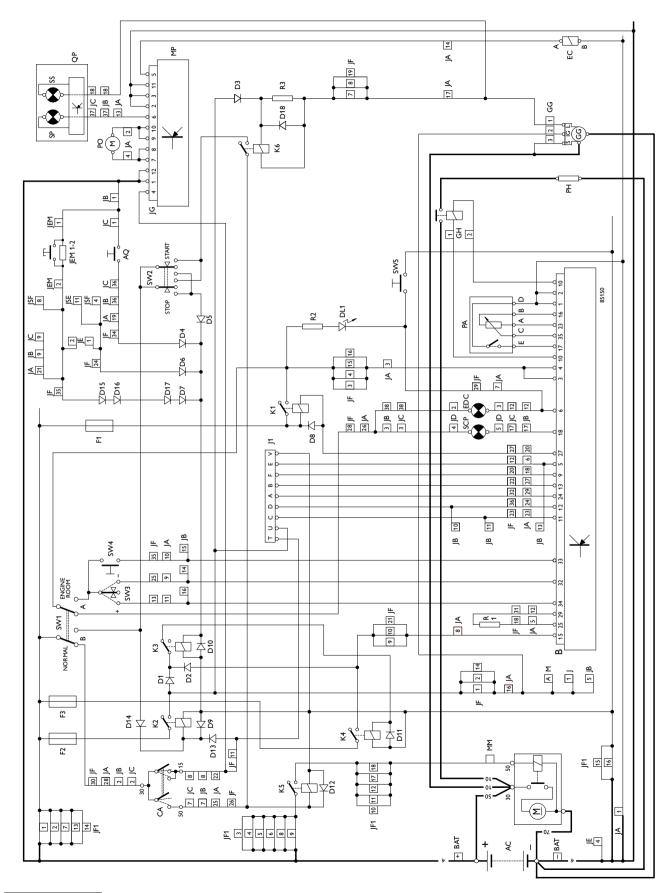
- BAD Diode for BA
- BAR Resistor for BA
- BA1, BA1U Connectors of the extension cable for engine rev. speed
- FA Acoustic and luminous alarms IA Coolant temperature sensor
- IR Parallel resistor for IA
- IR1 Series resistor for IA
- JE Connector for cutting out agitated engine JEM Connector for cutout switches in the case of an
- emergency and motor cutout from the engine room
- JS Electronic monitoring unit
- JSA, JSB, JSC, JSD, JSE, JSF Connectors for monitoring unit
- VA Engine oil pressure sensor
- VCA Fuel pressure sensor
- WA Engine oil low pressure sensor
- WR Parallel resistor for WA
- WR1 Series resistor for WA
- WVA Coolant pressure and low pressure sensor

Wiring unit JB - JC



C78 unità monitor omolog

EDC system – connector B



C78 Conn_B omolog

METHOD OF USE OF THE SAFETY SYSTEM INTERFACE

The following information relates to the method of use of the system in the configuration which is considered to be the IVECO MOTORS-FPT standard. Information concerning functions which require connection to external systems such as echo sounders and GPS, which are outside the safety system, are voluntarily explained briefly. The programming method which must be carried out by the Supplier or by the Assistance Service technician is not explained. For all the information which are not contained in this document, please refer to the manuals issued by the Supplier.

CAUTION

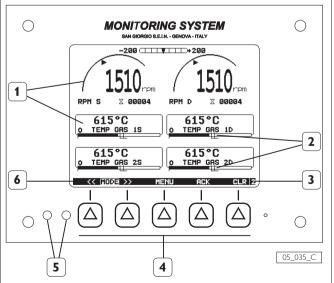
The system is supplied programmed to suit the homologation instructions arranged; every need linked to different programming of the operating characteristics will be met by the information presented by the Constructor with specific documentation. Please remember that the settings, allowed to adapt the system to different installations, will only be possible after the system password has been entered.

Monitoring

The monitoring interface enables a constant verification of the mechanic parameters required by the homologation norms so that it is possible to quickly identify the arousal of an anomalous condition. The information contained in the unit memory also enables the analysis of the events relating to the period preceding the survey. If there is an alarm status, an acoustic signal is emitted and the box containing the anomalous parameter data is visually highlighted through a flashing border.

The function of the keys changes depending on the different displays.

Figure 22



1. Analogue indicators in the form of bars or circles with reference to the parameter, value and unit of measurement -2. Recognition of the pre-set alarm limits - 3. Page number -4. Membrane keys - 5. luminous indicators - 6. Key functions.

Basic operations

Press the keys "<<" and ">>" to display the sequence of the pages containing the information relating to all the monitored parameters, including maintenance rates and optional information (see the relating figures).

The IVECO MOTORS-FPT standard configuration requires the detection of the following data:

- Pressure of engine cooling liquid (FRESHWATER PRESS)
- Low lever of engine cooling liquid (LOW WATER LEVEL)
- □ Low pressure of engine cooling liquid (FRESHWATER LOW P)
- Excessive temperature of engine cooling liquid (HIGH WATER TEMP)
- □ Pressure of engine lubricating oil (OIL PRESS)
- Absence of engine lubricating oil pressure (LOW OIL PRESS)
- □ Temperature of engine lubricating oil (OIL TEMP)
- □ Oil filter blocked (OIL FILTER CLOG)
- Deresence of water in fuel (WATER IN FUEL)
- □ Fuel pressure (FUEL PRESS)
- □ Fuel filter blocked (FUEL FILTER CLOG)
- □ Injection system failure (INJECT WARNING)
- □ The battery is not recharging (BATTERY WARNING)
- □ On going pre-lubrication (PRELUBRICATING)*
- D Power System Tension (VOLTMETER)
- □ Exhaust gas temperature (EX GAS TEMP)
- □ Engine rotation speed from EDC system (ENGINE E)
- □ Engine rotation speed from sensor (ENGINE S)
- Engine rotation speed sensor damaged (PICK-UP L FAULT)
- Engine stopping circuit damaged (MAN STOP L FAULT)
- Automatic engine stopping circuit damaged (AUTOSTOP L FAULT)
- □ Air filter blocked (AIR FILTER CLOG)
- Gear oil pressure (GEAR OIL PRESS)*
- Absence of pressure in the gear oil (LOW GEAR OIL P)*
- □ Sea water pressure (SEA WATER PRESS) *
- *) Information given only in the presence of the relating parts.

The setting of the alarm threshold must be carried out by the Technical Assistance Service personnel and requires the inputting of a password.

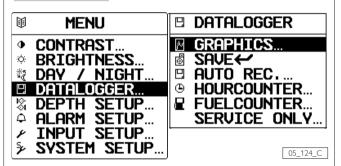
Video mode setting

The interface performances enable the modification of the brightness, the contrast and the image presentation mode, which is characterized by the inversion of the day/night.

- Press the "MENÚ" key to display the fast choice window.
- Press the keys "<<" and ">>" to highlight the display mode to be regulated: "BRIGHTNESS", "CONTRAST", DAY/NIGHT".
- \Box Press the "OK" key to confirm your choice.
- Modify the parameter setting using the "<<" and ">>" keys
- Press the "OK" key again to confirm.
- Press the "CLR" key to exit the "MENU".

Advanced operations

Figure 23



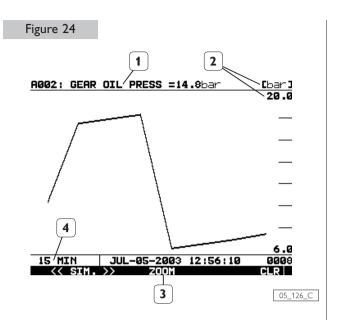
The values of the monitored parameters can be shown in different ways, including a diagram showing their evolution over a period of time.

To chose the display mode, do as follows:

- $\hfill\square$ Press the ''MENÚ'' key and display the fast choice window.
- □ Use the "<<" and ">>" keys to select the "DATALOG-GER" option inside the window.
- Press the "OK" key to confirm and display a second window containing the options which can be chosen.
- □ To select the required display mode use the "<<" and ">>" keys.
- Press "OK" to confirm.

Modalità di visualizzazione

- "GRAPHICS": this displays the evolution of the parameters value over time; the "ZOOM" key enables the modification of the time period shown on the display.
- □ Press the "<<" and ">>" keys to display the diagrams relating to the different parameters.
- $\hfill\square$ Press the "CLR" key to exit form this mode.



1. Parameter displayed - 2. Outside the stairs and measurement unit - 3. Period selection key (last 15 minutes, 1 hour, 6 hours, 24 hours) - 4. Displayed duration period.

- "SAVE": this enables the recording of the values of the parameters detected by the system in specific moments of the system working. Recording is carried out when the "OK" is pressed. The following pressures cause other data acquisitions. The recorded values can be shown in all the set modes.
- "AUTO REC.": this choice enables the modification of the data recording mode. It is not possible to carry out modifications.
- □ "HOURCOUNTER": this enables the management of the effective propeller/s movement hours; the data is displayed, as hours (ENGINE) or statistics (STATISTIC) only after inputting the correct password. This data can be used by the Assistance Centres Personnel to add just the programming of the maintenance intervals. From this mode it is possible to select the option "SERVICE RESET", which is explained in the paragraph: "Maintenance rates monitoring".
- General "FUELCOUNTER": (not programmed).
- "SERVICE ONLY": this is used only for the programming which must be carried out by the personnel of the Technical Assistance Service and requires the inputting of a password.

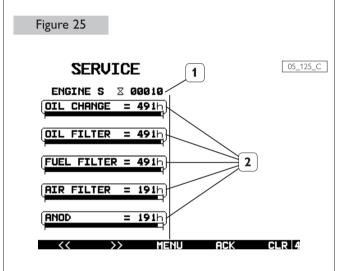
Maintenance rates monitoring

This unit is programmed to enable the monitoring of the hours during which the engine works before set maintenance interventions. Only the Technical Assistance Service Personnel can modify the data relating to the hours of the different intervals.

The unit hour counter decreases the data according to the effective working hours and, until negative values are reached, it enables the identification of interventions considerably before the need.

After each maintenance intervention, it is the boat user, or the personnel in charge, that must reset the display of initial data used for the counting.

The list of the number of working hours of the engine/s allowed before maintenance interventions can be displayed using the basic operations described in the sequence of pages which can be opened using the "<<" and ">>" keys.



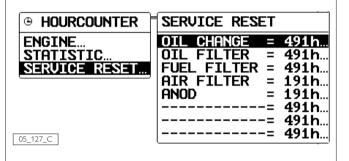
1. Engine working hours indicator - 2. Indicator of the remaining hours before intervention is required.

Maintenance intervals resetting

If one of the listed maintenance interventions has been carried out, to reset the counting data referring to the number of hours after which interventions is required again, do as follows:

- Press the "MENU" key to display the fast choice windows.
- □ Use the "<<" and ">>" keys to select the "DATALOG-GER" option inside the window.
- □ Press the "OK" key to confirm and display a second window containing the choice options.
- Select the "HOURCOUNTER" mode by pressing the "<<" and ">> keys.
- \Box Press the "OK" key to confirm.

Figure 26

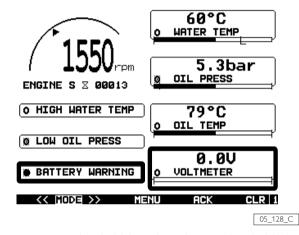


- □ Use the "<<" and ">>" keys to select the option "SERV-ICE RESET", inside the new window.
- Press the "OK" key to confirm and display the programmed interventions list together with the number of working hours still allowed before the next intervention is required or, if there is a minus sign (-) the hours of delay from the intervention request.
- □ Use the "<<" and ">>" keys to highlight the option relating to the intervention which has been finished
- Press the "OK" key twice consecutively to confirm.
- Verify that the number of hours shown as a maximum period is displayed. If this is not the case, repeat the last operations of the procedure.

Alarms management

The electronic system carries out in a sequence the verification of all the parameters which must be checked, irrespective of the page shown on the display. Two lower and two higher thresholds are set for each parameter, which respectively refers to the pre-alarm and to the alarm and which sometimes coincide. The programmed thresholds are shown on the bar analogical indicator which relates to the parameter (see the figure). Only the Technical Assistance Service personnel can modify these settings.





If a parameter value is higher than the set threshold, the acoustic signal is activated and the box representing the indicator is highlighted through a dark flashing border (clear border in the "NIGHT" mode)

Press the "CLR" key to stop the acoustic signal and the border flashing. The border is still displayed. The alarm condition is visually shown until the normal status is reset and the "ACK" key is pressed.

CAUTION

When an alarm signaling occurs, in order to verify that a damage really exists, it might be useful to press the "ACK" key. If the limit has only temporarily been passed, the alarm signaling stops immediately. If the alarm continues it is necessary to carry out the diagnosis of the cause. Once the cause is definitively removed, in order to reset the normal display status, press the "ACK" key.

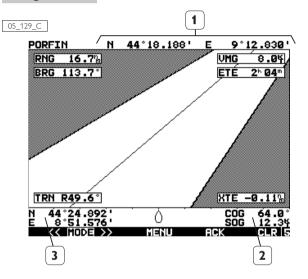
Navigation monitoring

If the interface has been connected with a GPS or self-piloting system (refer to the "JS connectors terminal working" section) which is able to supply navigation data according to the NMEA 0183 protocol, a pointing diagram useful to navigate will be shown among the monitoring pages.

Abbreviations list:

- RNG Distance from the next waypoint
- BRG Direction of the next waypoint
- VMG Real speed at waypoint
- ETE Expected arrival time
- TRN Course direction for waypoint
- XTE Off course mistake

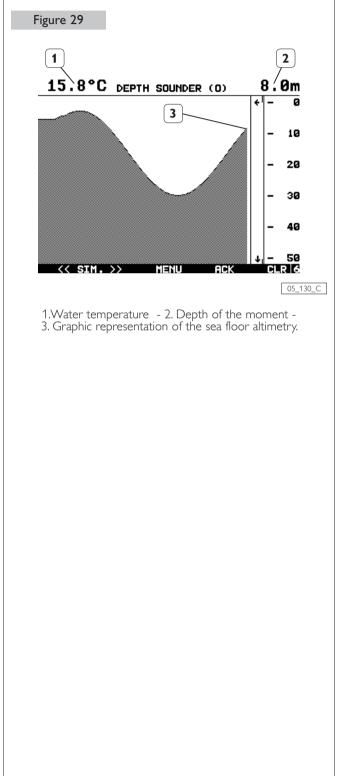




1. Destination (Waypoint) - 2. Course and speed -3. Position of the moment.

Depth monitoring (Echo sounder)

If the interface has been connected with an echo sounder (refer to the "JS connectors terminal working" section) which is able to supply water depth data according to the NMEA 0183 protocol, a diagram showing the depth evolution and the relating numeric value, including possible temperature, will be shown among the monitoring pages.



Safety behaviour

In order to guarantee the integrity of the engine and avoid major risks for the crew, The Monitoring Electronic Unit is programmed to cause the automatic stopping of the engine (this operation is carried out through the relay 3 and after connecting the JE connectors).

The following conditions are at the base of the engine automatic stopping:

- Lubrication low oil pressure (LOW OIL PRESS, WA sensor)
- Cooling high water temperature (HIGH WATER TEMP, IA sensor)
- Engine excessive rotation speed (ENGINE S, BA sensor).

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SECTION 11

SAFETY REGULATIONS

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Accident prevention	237
During maintenance	237
Respecting the Environment	238

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Standard safety regulations

Pay particular attention to some precautions that must be followed by all means in any working place and whose non-observance will make any other measures useless or not sufficient to ensure safety to the personnel in charge of maintenance.

- Be informed and also inform personnel of the laws in force regulating safety, by making informative documentation available for consultation;
- □ Keep working areas as clean as possible, and ensure adequate ventilation;
- Ensure that working areas are provided with emergency kits. These must be clearly visible and always fitted with adequate sanitary equipment;
- Provide for adequate fire extinguishing means, properly indicated and always easy to reach. Their efficiency must be checked on a regular basis and the personnel must be trained on intervention methods and priorities;
- Provide specific exit points to evacuate the areas in case of emergency, giving adequate indications of emergency escape paths;
- Smoking in working areas subject to fire danger must be strictly prohibited;
- Provide warnings by means of adequate boards signaling danger, prohibitions, and indications to ensure easy understanding of the instructions even in case of emergency.

Accident prevention

- When working close to engines and equipment in motion, do not wear unsuitable clothes, with loose ends, nor jewels such as rings and chains;
- □ Wear safety gloves and goggles when performing the following operations:
 - Filling inhibitors or antifreeze;
 - Topping or replacing lubrication oil;
 - Using compressed air or liquids under pressure (pressure allowed: \leq 2 bar).
- □ Wear a safety helmet when working close to hanging loads or equipment operating at head height level;
- Always wear safety shoes and clothes that adhere to the body, better if provided with elastics at the ends;
- Use protection cream for your hands;
- □ Change wet clothes as soon as possible;
- □ In presence of current tension exceeding 48-60 V verify the efficiency of earth and mass electrical connections. Ensure that hands and feet are dry and carry out working operations using isolating foot-boards. Do not carry out working operations you are not trained for;
- Do not smoke nor have exposed flames close to batteries and flammable material;

- Put rags smeared with oil, diesel fuel, or solvents in fireproof containers;
- Do not carry out any intervention you have not been given all necessary instructions for;
- Do not use any tool or equipment for any operation different from the ones they have been designed and provided for. Serious injury may occur;
- □ In case of test or calibration operations requiring the engine to be in operation, ensure that the area is sufficiently ventilated or use specific aspirators to eliminate exhaust gas. Danger: poisoning and death.

During maintenance

- Never open the filler cap of the cooling circuit when the engine is hot. Operating pressure would provoke hot liquid to pour out with serious danger and risk of scalding. Wait until the temperature decreases below 50 °C;
- Never top up an overheated engine with cooler and use only appropriate liquids;
- Always operate with the engine turned off: in case particular circumstances require maintenance intervention on the running engine, be aware of all risks involved in such operation;
- □ Be equipped with adequate and safe containers for draining engine liquids and exhaust oil;
- □ Keep the engine clean from oil, diesel fuel, and/or chemical solvents stains;
- □ The use of solvents or detergents during maintenance may generate toxic vapors. Always keep working areas ventilated. Whenever necessary wear a safety mask;
- Do not leave rags impregnated with flammable substances close to the engine;
- Upon engine start after maintenance, undertake proper preventive action to stop air suction in case of overspeed;
- Do not use fast screwdriver tools;
- □ Never disconnect batteries when the engine is running;
- Disconnect batteries before any intervention on the electrical system;
- Disconnect batteries from the system to charge them with the battery charger;
- □ After every intervention, verify that the battery clips' polarity is correct and that the clips are tight and safe from accidental short circuit and oxidation;
- Do not disconnect or connect electrical connections while the power is connected.

- Before proceeding with pipeline disassembly (pneumatic, hydraulic, fuel pipes) check for liquid or air under pressure. Take all necessary precautions by bleeding and draining residual pressure or closing separation valves. Always wear adequate safety masks or goggles. Nonobservance of these instructions may cause serious injuries and poisoning;
- Avoid incorrect or over-torque tightening. Danger: incorrect tightening may seriously damage the engine's components, affecting its lifetime;
- Avoid priming from fuel tanks made of copper alloys and/or with ducts without filters;
- Do not modify cable wires: their length must not be changed;
- Do not connect any other equipment to the engine's electrical equipment unless specifically approved by IVECO MOTORS-FPT;
- Do not modify the fuel or hydraulic systems without having received specific approval from IVECO MOTORS-FPT. Any unauthorized modifications will compromise the warranty assistance and furthermore may affect the correct operation and lifetime of the engine.

For engines equipped with an electronic control unit:

- Do not carry out any electric arc welding without having removed the electronic control unit first;
- Remove the electronic control unit in case of any interventions requiring heating over 80 °C;
- Do not paint the components and the electronic connections;
- Do not vary or alter any data filed in the electronic control unit. Any manipulation or alteration of electronic components will fully compromise the engine's warranty of assistance and furthermore may affect the correct operation and lifetime of the engine.

Respecting the Environment

- Respecting the Environment is of primary importance: all necessary precautions to ensure the personnel's safety and health must be adopted;
- Be informed and also inform the personnel of laws in force regulating use and exhaust of liquids and engine exhaust oil. Provide for adequate noticeboards and organize specific training courses to ensure that personnel is fully aware of such legal obligations and of basic preventive safety measures;
- □ Collect exhaust oils in adequate containers with air-tight sealing ensuring that storage is made in specific, properly identified, areas that are ventilated, away from heat sources, and not exposed to fire danger;
- □ Handle batteries with care, storing them in a ventilated environment and in anti-acid containers. Warning: battery exhalations represent a serious danger of intoxication and environment contamination.





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